# **YASKAWA**

# Machine Controller and AC Servo Drive Solutions Catalog



# **YASKAWA**

# Ever Forward, Ever Better 100 Years Together with Our Customers

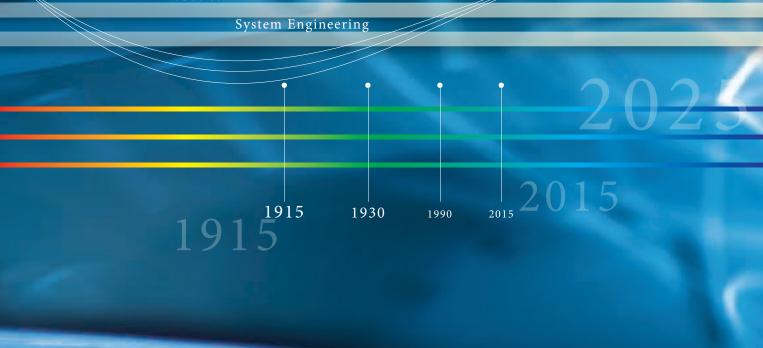
Since its founding in 1915 as a manufacturer for motors, Yaskawa Electric has capitalized on its motor drive technology to provide continuing support for the key industries of the times, first for factory automation, and today, for mechatronics and robotics.

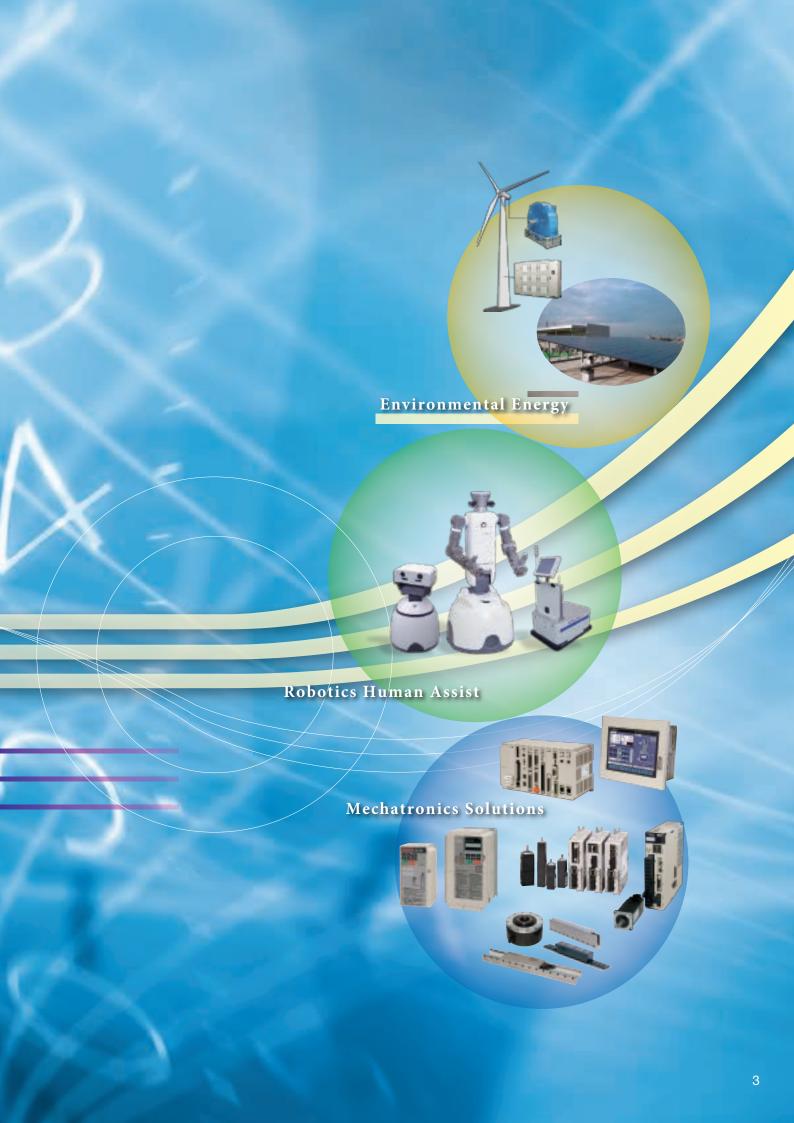
Today, Yaskawa is striving to make effective use of its technologies developed in the motion control, robotics, and system engineering sectors, and is also taking on the challenges of achieving the highly efficient utilization of natural energy and the creation of a society in which people and robots exist side-by-side.

Throughout our extensive 100-year history, we have consistently sought to develop the world's leading technologies and applications that would best delight and be most useful to our customers. Yaskawa will continue to treasure the results, technologies, and reputation we have achieved thus far, and look ahead to create "e-motional solutions" for emerging global challenges.

Motion Control

Robotics

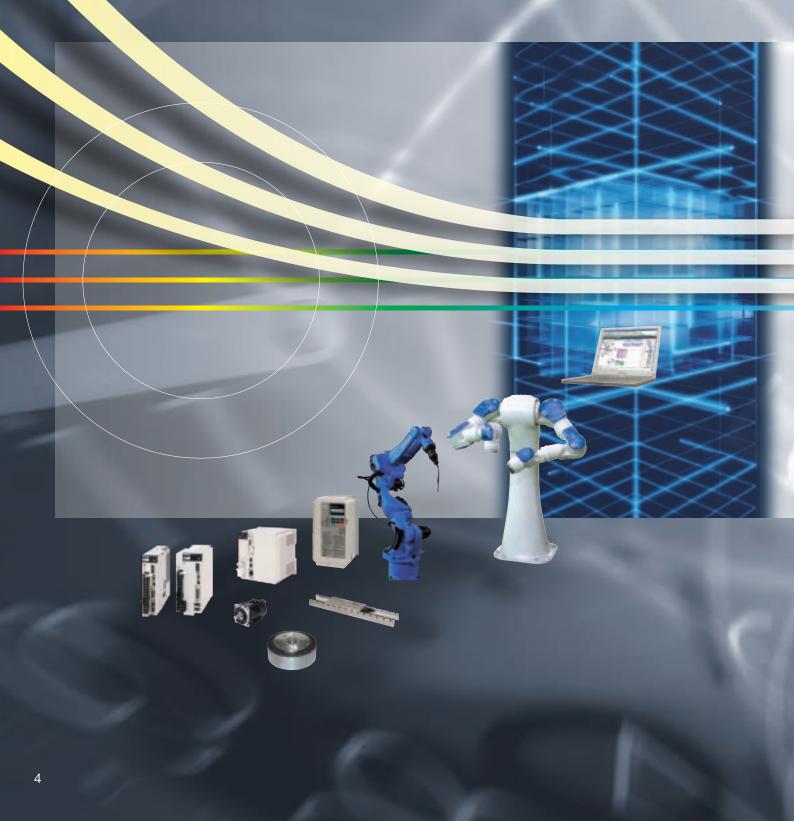


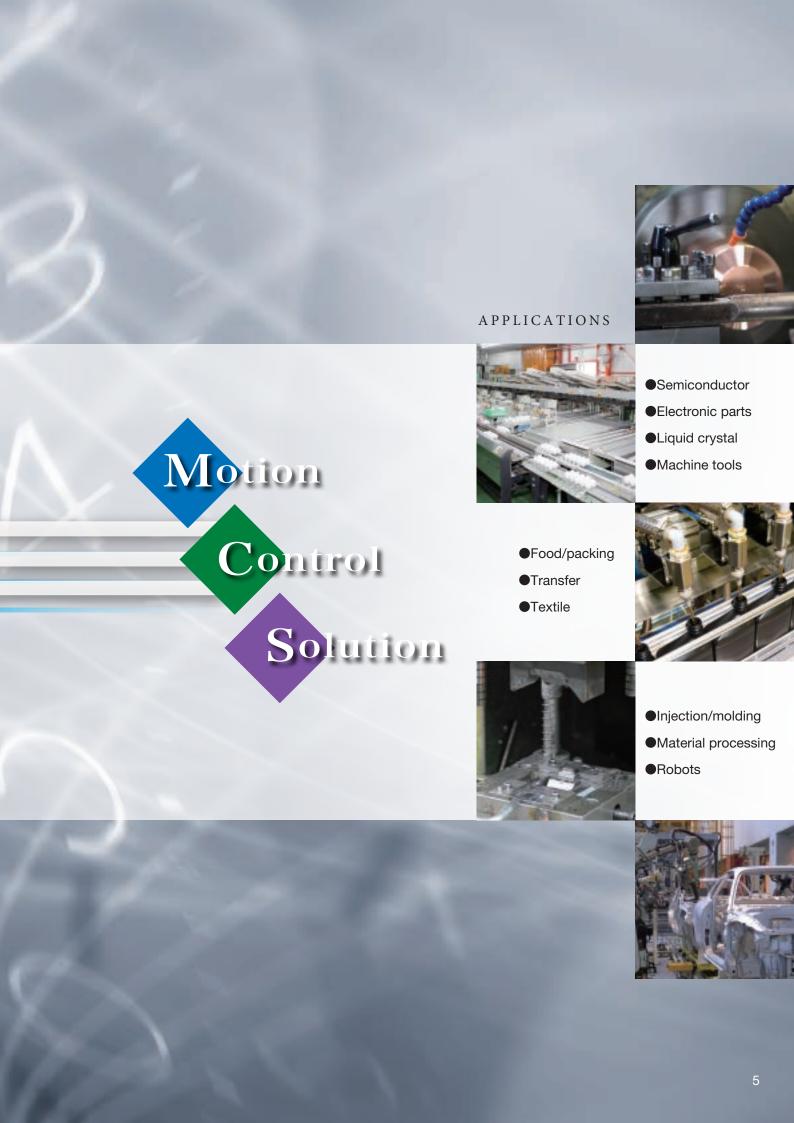


# *i* - Mechatronics Changing Motion, Changing the World

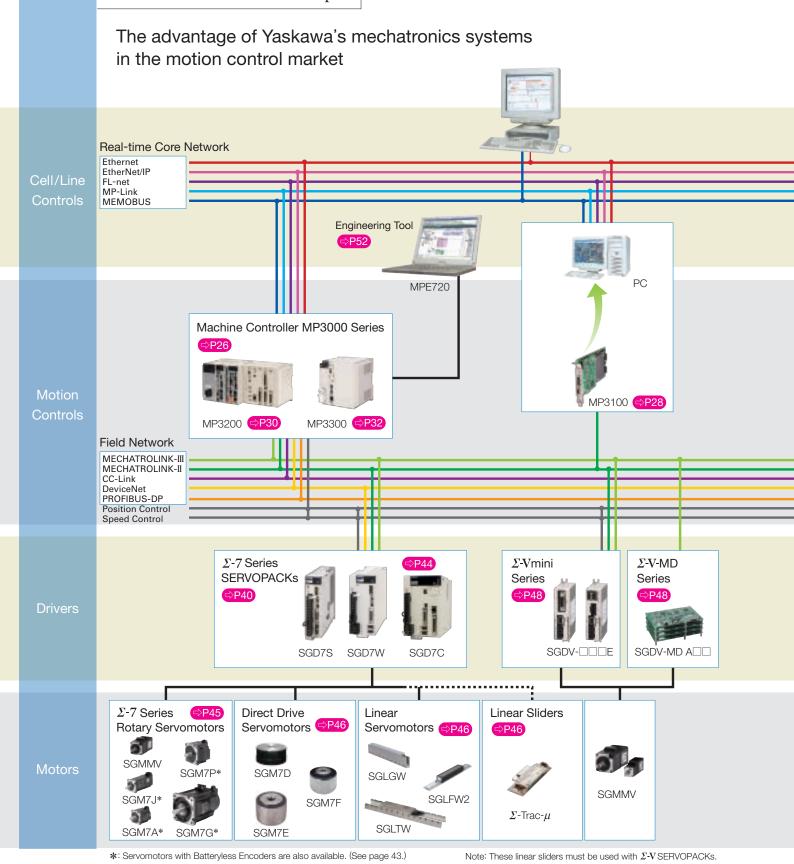
offering new solutions to the world.

Yaskawa's technology and mechatronics products are used in a wide-variety of industrial sectors, systems, and machinery, and enable ultra-high-speed and ultra-precision control. In addition to industrial sectors, our motion technology has a nearly limitless range of applications, including familiar sectors such as lifestyles, medicine, and welfare. Changing the motions performed by motors creates new concepts and products that can change the world.





#### Product Lineup



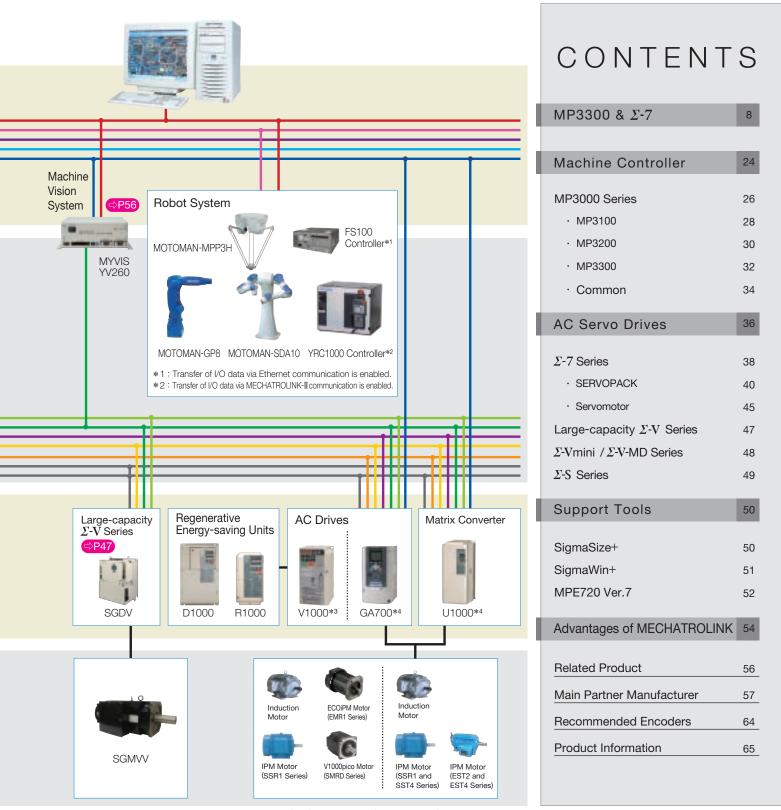
## Support for industrial standard networks for open system architecture

We provide components compatible with the industrial standards required for mechanical system configurations including real-time core networks to connect controllers and field networks to connect equipment.

- Support for systems around the world through compliance with international standards. (Consult with Yaskawa for information on support for standard networks.)
- Supports multi-vendor system configurations.

Real-time core networks : Ethernet, MODBUS ( MEMOBUS ), FL-net, EtherNet / IP

Field networks : MECHATROLINK-III, MECHATROLINK-II (Consult with Yaskawa for information on support for other networks.)



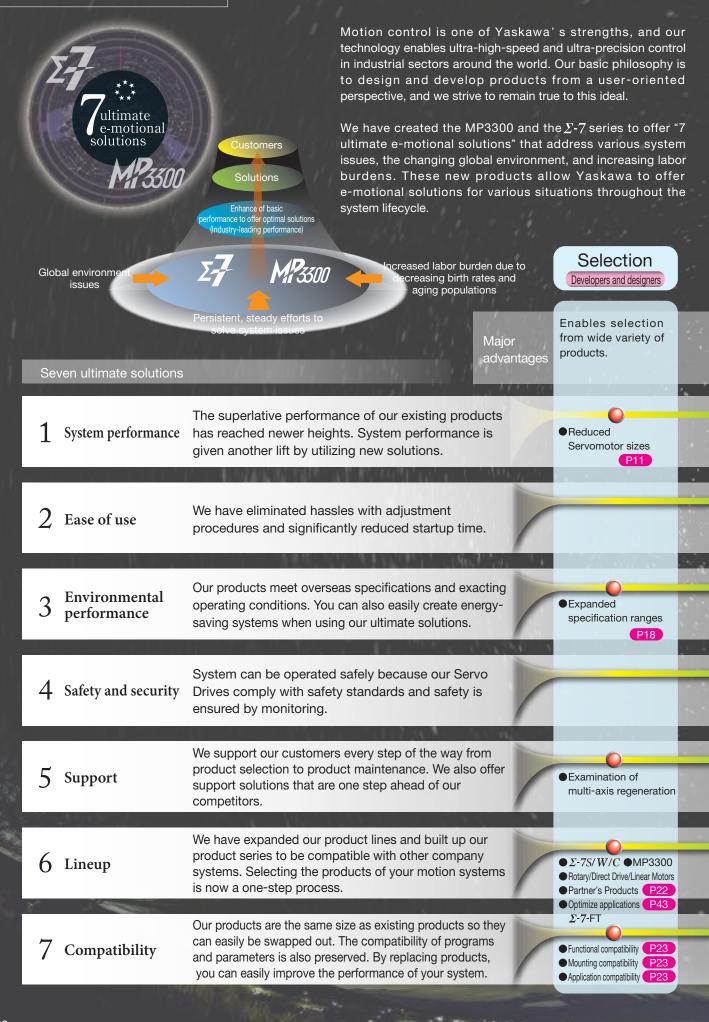
- \*3: Compatible with CompoNet and CANopen\*4: Compatible with CANopen and LONWORKS

#### MECHATROLINK, the motion network from our motion control expertise

High-performance mechanical systems can be constructed, in combination with our mechatronics components.

- Servo systems and input/output equipment necessary for configuring mechanical systems can be easily connected, providing high-speed response.
- 1: n synchronous communication for high-precision motion control.
- Certification under the SEMI E54.19 standard has been acquired. (This standard covers the sensor and actuator networks of semiconductor production systems.)
- Communication specifications MECHATROLINK-II: Transmission speed: 10 Mbps; communication cycle: 250 μs and higher; transmission distance: 50 m max.

 $MECHATROLINK-III: Transmission\ speed: 100\ Mbps, Communication\ cycle: 125 \mu s\ and\ higher;\ transmission\ distance: 75\ m\ between\ stations$ Note: The communication specifications of MECHATROLINK differ depending on the specifications of the Machine Controllers, SERVOPACKs, and AC Drives used. For further details, check the communication specifications of each equipment.





	Design Developers and designers	Trial production  Developers and designers	Production Manufacturers	Operation Operators	Maintenance Maintenance staff
	Enhance performance and preventive safety measures to increase safety and security.	Avoid wasted time with stable and vibration-free operation without tuning.	Ship products with specified parameters to facilitate assembly.	Monitor temperatures directly using built-in temperature sensors to increase safety and security.	Easily collect and manage product data to enhance service.
	● Industry-leading performance P10 to P11 ● Optimal functions for each application P11	• Vibration suppression P11			
	●Self-configuration P15	Multi-axis tuning P15 Tuning-less P15 Integrated tracing			●Traceability P19
•					_
-	●List of specifications			●Energy-saving functions	
	List of specifications			●2-axis SERVOPACKs	
		Sec. 1		P18	_
	<ul><li>Safety functions P19</li><li>Supports SIL3 specification requirements</li><li>P19</li></ul>			Momentary power interruptions     Temperature protection     P19	
	Downloading of CAD data     Self-configuration     P15		●Build-To-Order P20 service	Visual identification of operating statuses P18     (Monitoring by controller)	● Traceability P21  ● Data logging  ● Lifespan diagnostics P21
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The superlative performance of our existing products has reached newer heights. System performance is given another lift by utilizing new solutions.

Fastest in the

 $\Sigma$ -7: Features of  $\Sigma$ -7: Features of MP3300

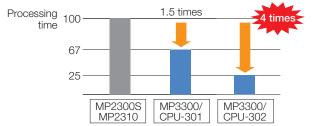
# MP3300 Machine Controller



- ★ Operates 1.5 times faster
- ★ 64-bit data types (double-precision real numbers, quadruple-length integers) supported
- ★ MECHATROLINK-III provided as a standard feature

#### Improved CPU performance\*

Helps increase equipment speed and shorten takt times.



\*: Ladder operation speed where the scan time of the MP2300S/MP2310=100

#### High-precision control

• 125  $\mu$ s communications cycle is supported.

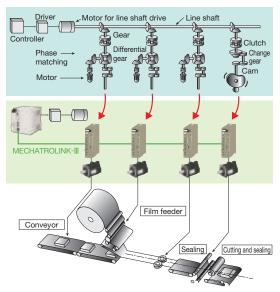


Double-precision real-number, 64-bit integer data are supported.
 Rounding errors during arithmetic calculations are reduced, and control at higher levels of precision can be achieved.

#### Applicable for electronic cam control

Using electronic cams that can compensate for mechanical error not only makes it easier to design the cams, but it also lets you create high-performance equipment with less error.

Equipment performance is improved Machines are easier to design

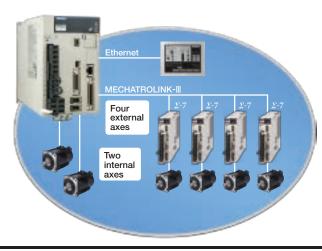


# $\Sigma$ -7C Two-axis SERVOPACKs with Built-in Controllers



- ★ Internal axes can be synchronized with external axes.
- ★ High-speed I/O used for the Controller Function Module.
- ★ 3.1 kHz response frequency
- ★ Improved vibration suppression

Fastest in the world



Build small-scale equipment system without PLC using one SERVOPACK.

# Controller and Servo Functionality All-in-One!

- The command/response delay is minimized with the two internal axes.
- · Compact with Built-In Controller
- No Battery Required
- 16 digital inputs (DI), 16 digital outputs (DO), and a pulse input (PI) on one channel as Standard I/O



#### $\Sigma$ -7 SERVOPACKs



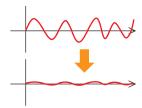
(Single-axis)



 $\Sigma$ -7W(Two-axis)

- ★ 3.1 kHz response frequency
- ★ Improved vibration suppression
- Fastest in
- ★ FT specifications to optimize applications

#### Ripple compensation



 $\Sigma$ -7 SERVOPACKs can reduce speed ripples caused by motor cogging, even for machines for which speed loop gains cannot be set high. This ensures smooth operation.

#### Enhanced vibration suppression function

· Notch filter

Suppresses high-frequency vibrations of 500 Hz or higher.

- ⇒ Number of filters increased from 2 to 5.
- Anti-resonance control

Suppresses vibrations at frequencies ranging from several hundred Hz to 1 kHz.

⇒ Vibrations can now be suppressed at multiple frequencies in comparison with one frequency in earlier models.

#### Vibration suppression

- Suppresses vibrations at low frequencies (30 Hz and lower).
- ⇒ Vibrations can now be suppressed at two different frequencies in comparison with one frequency in earlier models.

These functions can be adjusted automatically using the autotuning function.



★ Compact dimensions (approx. 80% smaller than our earlier models)

Smallest in the industry

- ★ High-resolution 24-bit encoder incorporated (16,777,216 pulses/rev)
- ★ Maximum torque: 350% (small capacity)

Highest in the industry

#### Compact dimensions

Models: SGM7J, SGM7A □40 mm (50/100/150 W)



Approx. 80% smaller than earlier models.

#### High-resolution, 24-bit encoder

Encoder resolution comparison



 $\Sigma$ -7series 24 bits = 16 million pulses/rev (approx.)



Solution for 50-W or greater models

#### Servomotors with Batteryless Absolute Encoders are also available. (Except SGMMV model)

 Retains current position without a battery When the motor turns, power is generated by the magnet and coil to store the data in non-volatile memory.



Batteryless encoders remove worries about the battery running out and losing rotational data.

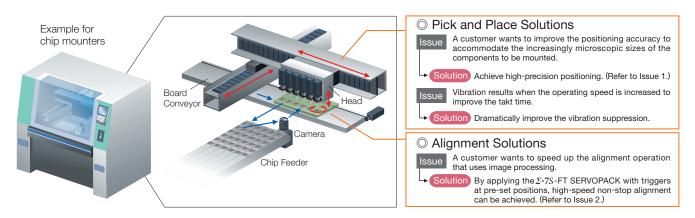
Solves issues related to batteries



Easily replace Servomotors

See page 23.

# **Examples of Solutions**



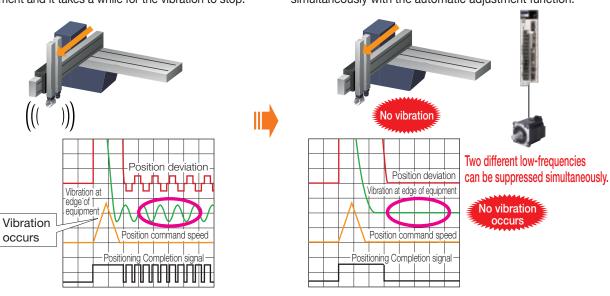
#### We want to increase productivity by suppressing vibration of equipment.



Vibration occurs at two different frequencies at the edges of equipment and it takes a while for the vibration to stop.

#### Solution

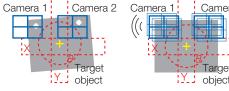
Vibration at two different low-frequencies is suppressed simultaneously with the automatic adjustment function.



#### Issue 2 We want to improve positioning accuracy to handle increasingly smaller workpieces.

#### Problem

Positioning accuracy needs to be improved because parts that are handled are becoming increasingly smaller.

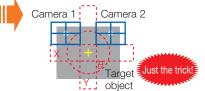


Before positioning correction

object

After positioning correction

High-precision positioning becomes possible for precision workpieces by replacing the existing drive with the  $\Sigma$ -7 Servo Drive.



Vibration when stopped. ± 10nm level also possible. Note: This will depend on the installation conditions.



- · 3.1 kHz response frequency
- · Improved vibration suppression

 $\odot$   $\Sigma$ -7 Servomotors (High-resolution encoders)

24 bits = 16,777,216 pulses/rev. For 20 mm lead ball screws 1.2 nm resolution



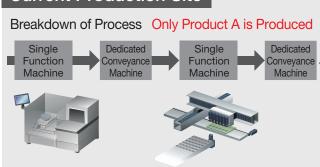
## Issue 3 We want to handle variable product and lot size production.







# Current Production Site



# Changing Environment around Manufacturing

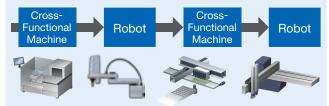
#### Variable Product and Lot Size Production

Demands for productivity improvements and for flexible production lines that can handle variable product and lot size production have been increasing at production sites in recent years. Therefore, achieving cross-functionality in equipment itself is becoming increasingly necessary.

#### **Next-Generation Production Site**

Breakdown of Process

Products A, B, and C Can All Be Produced



A production line that saves labor and improves productivity through cross-functional machines and robots for conveyance between processes.

Yaskawa can contribute to building your future production site with a rich set of components that will meet your new needs and our record of delivering those components.

#### Yaskawa's Rich Set of Components

Yaskawa offers a full lineup of components including motion control products (Machine Controllers, AC Servo Drives, Inverters, and other products) and robots. We can propose solutions that contribute to automating and creating cross-functionality in your equipment and conveyance machines between processes.









In particular, the  $\Sigma$ -7C facilitates the creation of modular equipment in both the software and hardware facets of equipment.

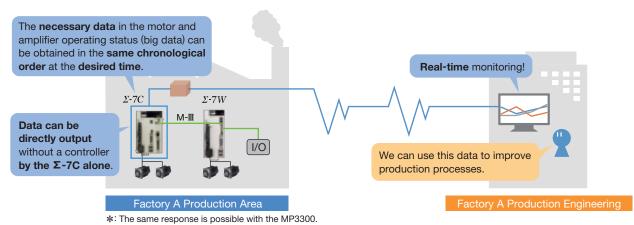
Refer to Issue 7 of the Examples of Solutions on page 17.

# We want to respond to requests from users to visualize the operating status of equipment.





You can respond to requests from users to visualize the operating status of equipment.



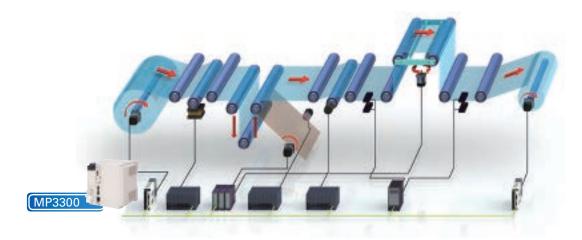
# **Examples of Solutions**



Ussue 5 We want to achieve high-precision roll-to-roll control without extra effort in hardware or software.



This application example for a winder achieves high-precision winding, feeding, dancer control, and tension control. Control is achieved with standard Servo Drives and Inverters. Special tension controllers are not required. User functions are prepared in advance to simplify programming.

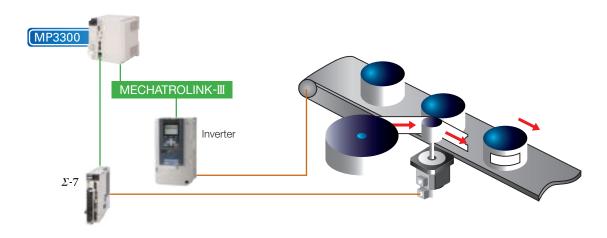


Usue 6 We want to follow a high-speed driven mechanism with another mechanism at high speed and precision.





This application example for a labeling machine applies labels to workpieces that are conveyed from an upstream process on a high-speed belt conveyor. A high-speed, high-precision system can be easily built by connecting Inverters and Servo Drives to a network and having the slave axes (Servo Drives) follow the control of the master axis (an Inverter).







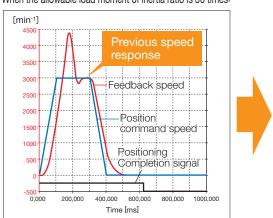


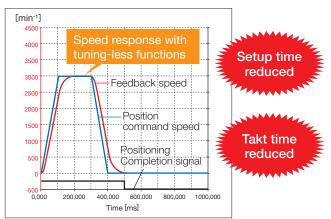
# No need to adjust servo gains $\Sigma$ -7

With Yaskawa's original tuning-less function, systems can run without vibration for a load with 30 times (max.) of the load moment of inertia. Systems remain stable even with load changes during operation.

	$\Sigma$ - $ m V$ Series	$\Sigma$ - $7$ Series
Allowable load moment of inertia ratio	30 times (max.)	30 times (max.)
Max. control gain	Speed loop gain 40 Hz (approx.)	Speed loop gain 70 Hz (approx.)

When the allowable load moment of inertia ratio is 30 times:





#### Automatic setup using the self-configuration function



The self-configuration function automatically recognizes the configuration of all the MP3300 optional units and modules, as well as all slave devices (servo units and I/O devices) connected to the MECHATROLINK motion network. This function eliminates the need for definition input work, and delivers vastly shortened startup times. The self-configuration function generates the definition files listed below.

- · Module configuration definition
- · I/O register assignments
- · Communication parameters for Communication Module
- · Servo Drives connected to MECHATROLINK (servo parameters and user definitions)
- · I/O devices connected to MECHATROLINK (number of input and output points)

#### Using the DIP Switch



Using the MPE720 support tool



## Online editing enables programming without stopping the machine MP



Efficient debugging operations while using online editing ensure you finish trial operation faster. A register map will show you the current application status of registers in the program at a glance so that you can easily search for unused registers that are required to add to or change programs.

Editing without Stopping the Controller While online, you can change the program in the Controller and on the PC at the same time.



#### Register Status Displayed in Colors

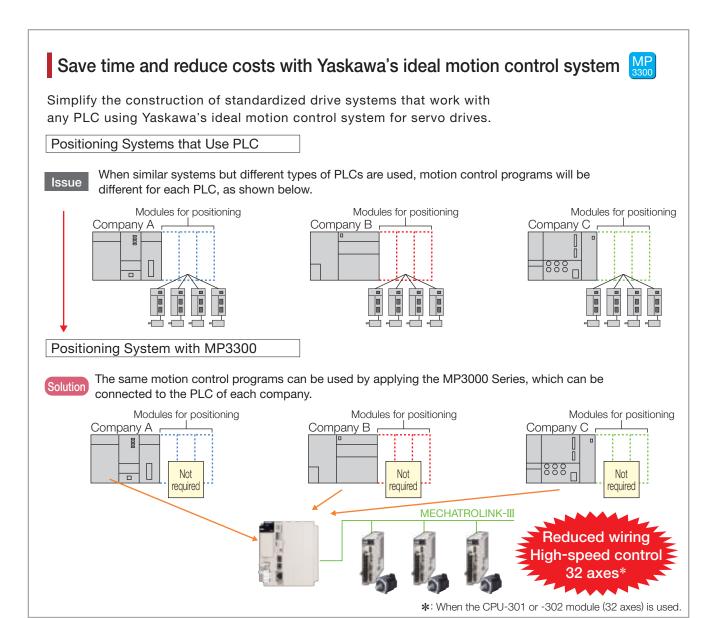
White: Unused registers

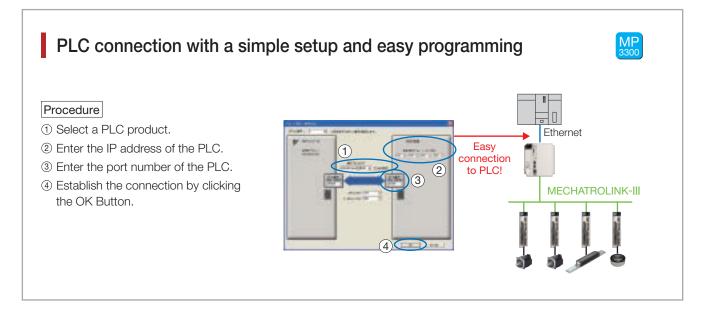
Green: Registers used with the same data type Red: Registers used with different data types



When the program is not working correctly, you can check red registers. If you need to use new registers, just look for white ones.

Information on used registers is displayed in balloons for mouse rollovers.



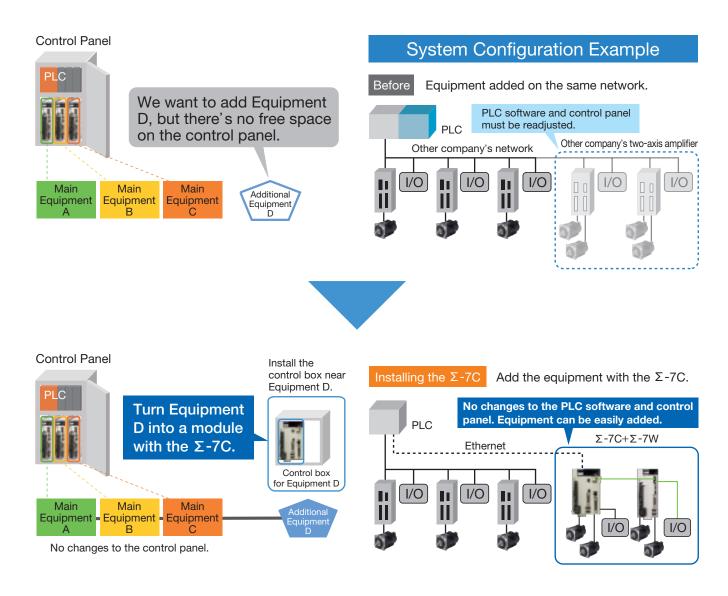




# **Examples of Solutions**

#### We want to easily add new units to existing equipment. Σ-70 Issue 7

This solution is a specific example for improving the flexibility of upstream and downstream conveyance processes for equipment and the equipment itself. Options can be easily added by creating modular equipment.



# Satisfies specifications for use overseas and in harsh operating conditions



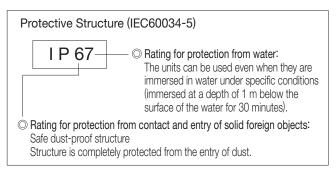
- · 240 VAC supply voltage also supported
- · High-altitude use increased to 2,000 meters above sea level\*



# Waterproof protective structure Σ-7 upgrade to IP67 rating



[SGM7J, SGM7A (IP22 for 7.0 kW) and SGM7G models]



# Saves energy with effective use of regenerative energy $\Sigma$ -7

Regenerative energy can be effectively used between two axes when using a 2-axis integrated SERVOPACK or single-axis SERVOPACKs with a DC bus connection. This saves energy in equipment where regenerative energy was previously consumed by regenerative resistors.

#### Features

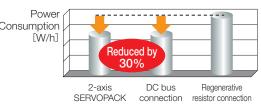
#### Energy savings for all equipment

- · Supplies regenerative energy that was discarded as heat to other axes.
- · Reduces the amount of electrical power consumed.

#### Eliminates the need for regenerative resistors\*

- · Uses regenerative energy and eliminates the need for regenerative resistors.
- · Lowers the cost of systems and saves space.
- · Reduces temperature increases commonly caused by the use of regenerative resistors.
- \* : Regenerative resistors may be required, depending on machine configurations.

# $\Sigma$ -7Wmodel $\Sigma$ -7S model $\Sigma$ -7Smodel 2-axis SERVOPACK DC bus connection Regenerative resistor Power Consumption [W/h]

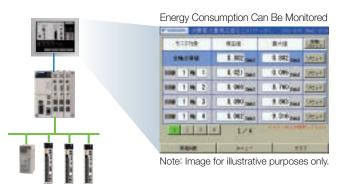


# Visualization of Energy Consumption

The power in the motion system can be monitored through the MP3300.







## No Battery Disposal Required





#### Servomotors with Batteryless **Absolute Encoders**

Batteries that were required for each axis of a Servomotor with Encoder are no longer necessary.



#### Two-axis SERVOPACKs with Built-in Controllers $\Sigma$ -7C

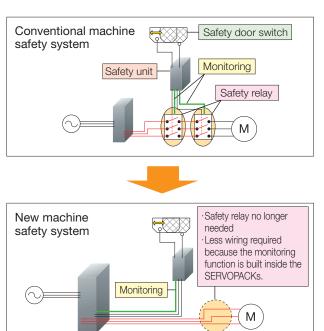
A battery in the controller section is no longer required due to the use of non-volatile memory.





# Satisfies requirements of the SIL 3 of the IEC 61508 functional safety standards (first in Japan)

Certification under this standard will improve the safety of our customers' systems and reduce the costs associated with additional safety certification. It will also be easier to implement compliant safety systems for press machines and other systems on the market in Europe and other regions. This certification will also reduce the man-hours required for wiring connections and the number of peripheral devices.



Features

Stop Category 0 (Safe Torque Off) incorporated

- Meets safety standards for SIL 3 of the IEC 61508 Yaskawa will become the first company in Japan to acquire SIL3 certification for its servo drives. This indicates a significant improvement in safety compared to the  $\Sigma$ -V series.
- Improved functions with safety option module The safety option module (SGDV-OSA01A) for the  $\Sigma$ -V series can also be used with the  $\Sigma$ -7 series. The following functions meet the requirements stipulated under IEC 61800-5-2:\*
  - STO: Safe Torque Off (immediate removal of power to motor)
  - SS1: Safe Stop 1 (removal of power after motor has decelerated and stopped)
  - SS2: Safe Stop 2 (maintenance of power after motor has decelerated and stopped)
  - SLS: Safely-Limited Speed (limit placed on motor speed)

The responsiveness of these safety functions is significantly enhanced without going through a host system.

\* : SIL2 applies when a system is used with the safety option.

# Protect systems from high temperatures



MP3300,  $\Sigma$ -7SERVOPACKs, and servomotors are equipped with temperature sensors that can directly monitor temperatures of machines and detect abnormalities to prevent failures.

Real-time temperatures can be viewed on a display by using MP3300.



## Several kinds of powerful functions to prevent unauthorized access



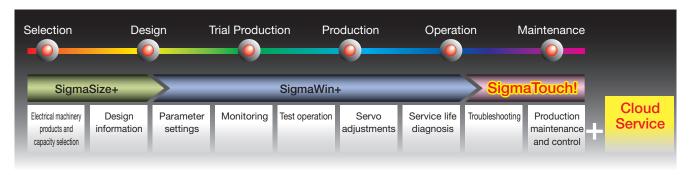
Security functions stand guard to block off multiple possible entry points including programs, projects, controllers, and users.



Yaskawa supports our customers in all their decisions, from product selection to production maintenance, and offers solutions that are always one step ahead of our competitors.

Yaskawa's MechatroCloud offers Build To Order (BTO) services. The SigmaTouch! smartphone application can be used to enhance product lifecycle management and maintenance service.









#### MechatroCloud is a new cloud service provided by the Yaskawa Electric.

MechatroCloud is available in Japan only. Refer to Cloud Services on the e-Mechatronics website for more information about MechatroCloud.



#### Details of service

Build To Order service

Customers can place orders after specifying the parameters they want when their SERVOPACKs are shipped from the factory.

Product management and maintenance service The product manufacturing information used specifically by each customer can easily be saved and displayed at any time.

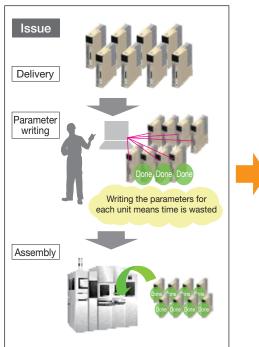
#### How to use the service

Register as a corporate member of our customer Web services. You can use MechatroCloud after you have registered.

# Single or multiple orders possible after specifying parameters (BTO) 2-7



Customers can now place single or multiple orders for SERVOPACKs in the  $\Sigma$ -7 series after specifying parameters at the factory shipment stage. It is no longer necessary to write the parameters at the system assembly site, which means that production lead times can be reduced.



#### Solution

The  $\Sigma$ -7 SERVOPACKs are delivered with the customer-specified parameters already written prior to shipment.

This reduces the man-hours involved in system assembly work.

The names of the axes are printed on the boxes in which the products are delivered. This ensures that these are no mistakes made when installing the axes.





# Product management and maintenance service MP

- · Manufacturing information for each product can be easily viewed by using SigmaTouch!, Yaskawa's smartphone application. To view, simply hold your smartphone over the QR code of the product.
- · MechatroCloud can also be used with SigmaWin+.



MechatroCloud service. · You can view the product manufacturing information and the troubleshooting information stored in the MechatroCloud.

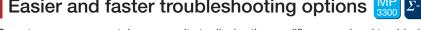
· You can view manuals for servomotors, servo drives, and machine controllers.



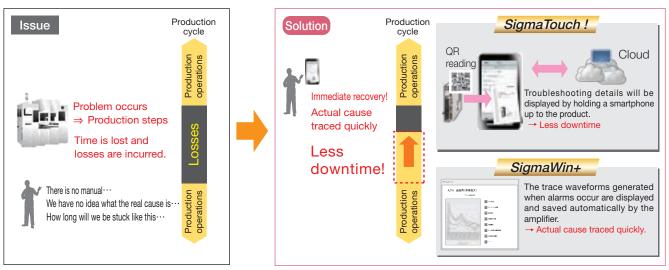


Note: QR code is a registered trademark of Denso Wave Incorporated.

# Easier and faster troubleshooting options

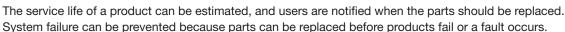


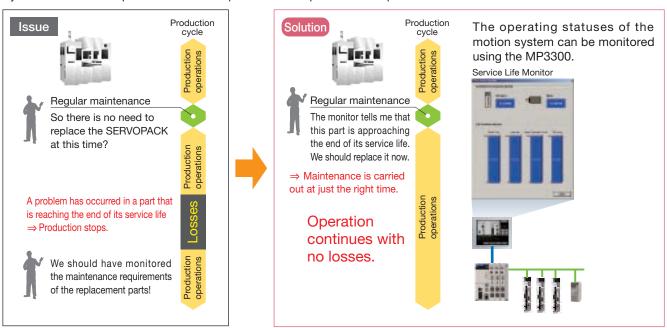
Operators can use smartphones on-site to display the amplifier manual and troubleshooting details. The trace waveforms generated when alarms occur can be saved automatically, and the real causes of problems can be tracked faster, which reduces downtime.



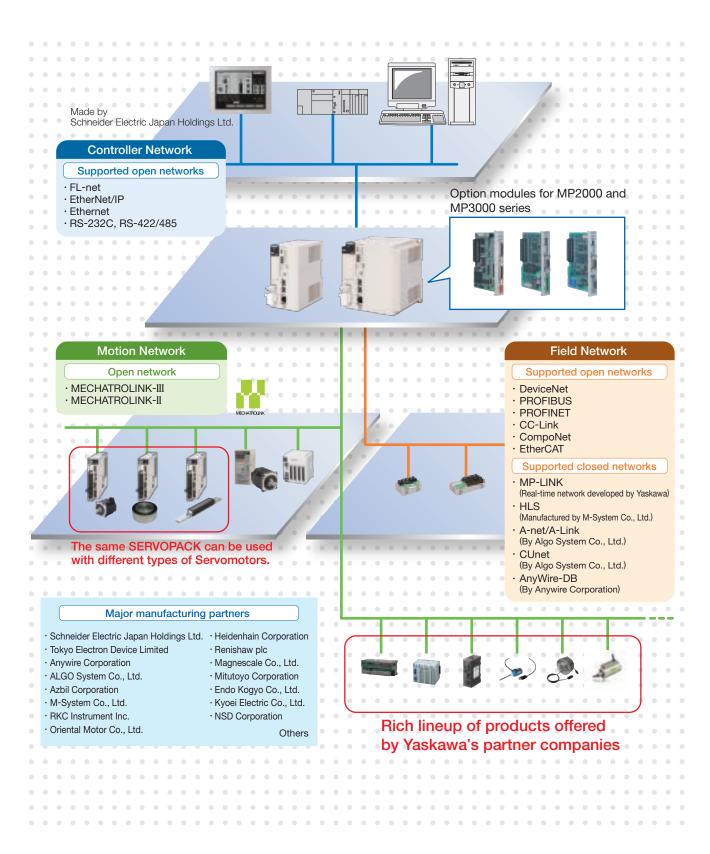
# Achieve planned maintenance by monitoring the remaining service life MP







We have expanded our product lines and built up our product series to be compatible with other company systems. Selecting the products of your motion systems is now a one-step process.

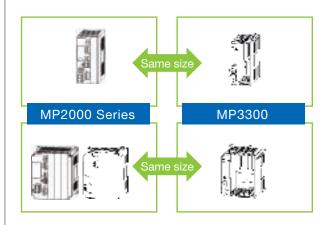


Our products are the same size as existing products so they can easily be swapped out. The compatibility of programs and parameters is also preserved. By replacing products, you can easily improve the performance of your system.





Compatible with MP2000 series



#### Applications

Program applications for the MP2000 series can be converted and used with the MP3300.



SERVOPACK

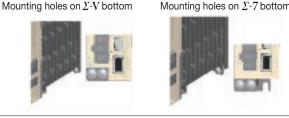
• Installation compatibility with the models in the  $\Sigma$ -V SERVOPOACK having the same capacity is featured for the SERVOPACKs.

The  $\Sigma$ -7 SERVOPACKs have improved shapes for mounting holes. With this new shape, it is much easier to insert a screwdriver.

Mounting holes on  $\Sigma ext{-}\mathrm{V}$  top



Mounting holes on  $\Sigma$ -7 bottom



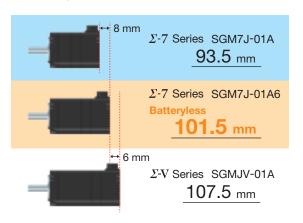
#### Parameters

A parameter conversion mode is provided. The parameters of the  $\Sigma$ -V SERVOPACKs can be used with the  $\Sigma$ -7 SERVOPACKs, when using the SigmaWin+ parameter converter.

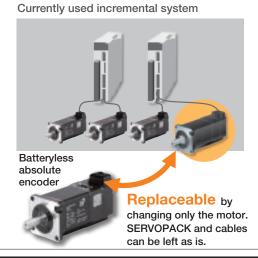




 Installation compatibility with the models in the  $\Sigma\text{-V}$  SERVOPOACK having the same capacity is featured for the SERVOPACKs.



• Easily-replaceable system configuration



# Machine Controller

The MP Machine Controller series anticipates the needs of increasingly complex and advanced systems to offer customers the most optimal solutions.

In the 1990s, Yaskawa introduced Machine Controllers to the motion control market that was dominated at the time by programmable controllers. Since then, Yaskawa has evolved as a top manufacturer of Machine Controllers and is turning customer problems into opportunities.

These efforts have included improvements in the high-speed performance of machines and systems, enhancement of productivity by reducing takt times, and monitoring the operation status.











MP3000 Series

# AP3000

Modular Type

**Machine Controller** 

MP3100

A controller capable of high-speed, high-capacity data processing in systems that use computers.





**Unit Connection Type** 



Machine Controller

MP3200

Motion, vision, and robotics systems deliver the highest possible machine performance.

Board Type



MP3300

The base unit, CPU modules and optional modules can be freely combined to create a Machine Controller best suited to the user's control scale and control panel size.

#### Machine Controller

# MP3000 Series

The MP3000 series includes an extensive lineup of Machine Controllers and develop the most ideal system scale and meet motion requirements. In addition, diversified functions, performances, and services are available to support customer needs throughout the entire machine lifecycle.





Features

#### Ultimate system performance

Equipped with the fastest CPU, the MP3300 Machine Controller makes it simple to construct a high-speed, high-accuracy, and multi-axis system by connecting units that support MECHATROLINK-III.

#### Ultimate environmental performance

The power consumption of the motion system can be monitored, which helps to conserve energy.

#### Ultimate support

The support available from Yaskawa now makes it easier to handle large-volume data, such as system operation statuses. This improves traceability at the production site. New support services such as Yaskawa's MechatroCloud service make it even more convenient for users to store and manage product information.

#### Ultimate ease of use

Misnon

The adjustments to a multi-axis system can be completed in a short time using the MPE720 Ver. 7 engineering tool. It is also easy to add a motion system to an existing sequence system.

#### Ultimate safety and security

Security measures have been enhanced to prevent the outflow of know-how. In addition, temperature sensors installed in the MP3300 enable early identification of abnormal temperatures in the system.

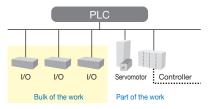
#### Ultimate lineup

In addition to the  $\Sigma$ -7 series of AC Servo Drives, a strong lineup of products is also available from Yaskawa's partners.

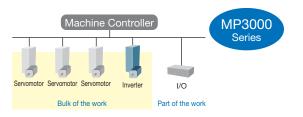
#### Ultimate compatibility

Program applications for the MP2000 series can be converted and used with the MP3000 series.

#### Machine Controller and PLC (Programmable Logic Controller): How do They Differ?



- © Excellent at controlling I/O.
- Focuses more on connectability to various
   I/O devices than axes synchronization.
- Most are modules.



- Ideal for controlling machines and devices.
- © Focuses on precise synchronous and high-speed control on multiple motors.
- The optimal controller models can be selected based on the device requirements.

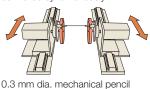


#### Four all-in-one control modes

Every aspect of control from simple to complex operations can be achieved using one CPU without adding optional modules for each kind of control.

#### Synchronous Phase Control

Speed control with position compensation (electronic shaft) or position control with 100% speed feed forward (electronic cam). Multi-axis servomotors can be controlled synchronously.



#### Torque Control

regardless of speed.

Torque When T1=T2

T1

Load Torque
T2

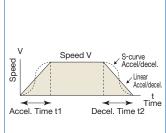
Motor Time

Generates a constant torque,

#### **Position Control**

lead does not break.

Advances to the target position, and stops or holds.



#### **Speed Control**

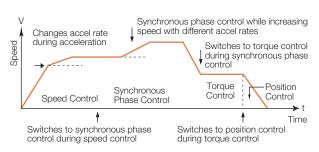
Speed

Turns the motor at the specified speed, with user-defined acceleration/deceleration slopes.

Decel. Time t2

#### Switch between any of the modes while online

The MP3000 series can switch between these four modes while online.



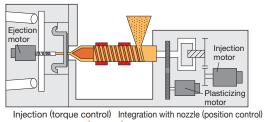
#### Packaging machines

Synchronized phase control enables cutting, sealing and other kinds of processing that are synchronized with the movement of the workpiece.



#### Injection molding machines

Switching from position control to torque control can be executed without deceleration.



Return operation (positioning)

#### The MP3000 Series Brings a Cornucopia of Solutions

#### Gantry Mechanism and Alignment Stage Mechanism

Accel, Time t1

These mechanisms comprise the basic system used in devices for the manufacturing and the inspection of semi-conductor chips, LCDs, and other components. High precision as well as high acceleration and deceleration are required for these processes. Two axes must be synchronized to control and operate the gantry mechanism.

Advantage Achieves complete synchronous multi-axis control and online adjustment.

#### Solution for Conveyance

Provides a solution for the control mechanism that allows workpieces to be processed in accordance with the speed of the production line.

Advantage Allows the slave axes to follow master axis operation when the inverter is used as the master axis and both the inverter and servo drives are connected through a network.

#### Solution for Winder

Provides a solution for the control mechanism where a winder winds and a feeder unwinds.

Advantage Achieves high-precision winding, feeding, dancer control, and tension control with standard servo drives and inverters. Line control can be constructed easily with user functions set in advance.



# Machine Controller MP3000 Series

# MP3100

A controller capable of high-speed, high-capacity data processing in systems that use computers.

A rich set of motion APIs have been prepared so that motion control can be freely executed using PC applications such as VC++, C#, and VB.NET.



# The general-purpose, high-function MP3100

The MP3100 Machine Controllers enable data access and motion control from a PC with an abundant API. Compatibility with the MP2100 Series is maintained while functionality and ease of application are improved. In addition to high-speed, high-precision motion control, linking with a PC through a motion API has been strengthened.

#### Super-high-speed application processing

#### ■ Greater CPU Performance

The processing speed is four times faster than the MP2100. The high-speed scan time can be set to as low as 125  $\mu$ s.

#### ■ MECHATROLINK-III

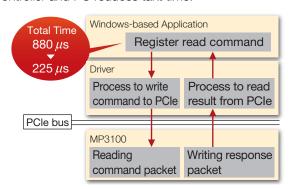
A 125- $\mu$ s communications cycle enables detailed commands to be sent at high speeds and improves processing precision and tracking accuracy.

#### ■ High-speed I/O (5 inputs and 4 outputs)

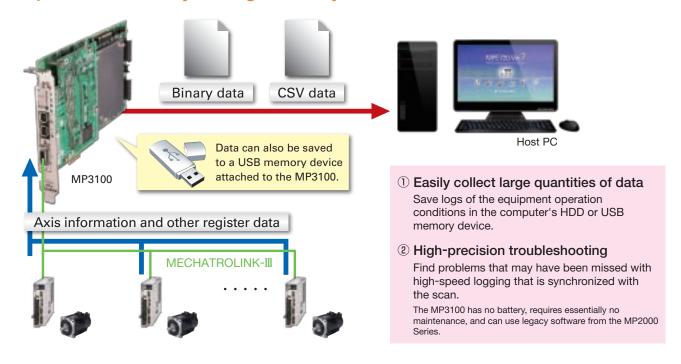
A High-speed I/O Module is built in to provide I/O service with a high-speed scan of  $125 \,\mu s$ .

#### PCI Express

Faster data communications between the Machine Controller and PC reduces takt time.



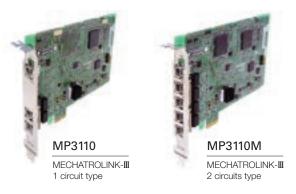
#### Improved traceability for large-scale systems





#### The MP3110 with high-speed SoftMotion

The MP3110 and MP3110M achieve motion functionality on a PC. A high-speed architecture called SoftMotion is used to increase motion control speed by using the processing speed of the PC. The high-speed PCI Express bus is also supported for even greater speed. User applications written in C language call Motion API functions to operate MECHATROLINK-III-compatible devices, such as Servo Drives and Distributed I/O Devices, that are connected to the MP3110 or MP3110M PC Board-type Machine Controller.



#### SoftMotion

The architecture that drives the motion functions on the PC is called SoftMotion. The MP3110 and MP3110M use SoftMotion. The motion performance of the MP3110 and MP3110M depends on the processing speed of the PC. If your equipment requires high performance, use a high-performance PC. If you want to balance cost with performance, use a less-expensive PC. It's all up to you.

#### • Control cycle of 125 μs

The use of SoftMotion and the PCI Express bus enables controlling MECHATROLINK- $\mathbf{III}$ -compatible devices with the fastest control cycle on the planet: 125  $\mu$ s.

\*: The Motion API is a software interface that controls the MP3110 or MP3110M from an application on a PC. It allows you to easily perform motion control from a PC.

#### • Realtime OS support

The Motion API\* runs on a realtime OS. By using a realtime OS, you can achieve motion control that synchronizes I/O boards, video boards, and other devices with the MP3110 or MP3110M. If you use a realtime OS that runs together with Windows (i.e., a hybrid OS), you can achieve HMI control and motion control on one PLC to reduce equipment costs.

#### Motion network

A MECHATROLINK-III communications interface is provided, one channel for the MP3110 and two channels for the M3110M. Normally the number of PCI Express slots on a PC is restricted, so Yaskawa provides a lineup that lets you maximize limited resources.

#### Comparison

Items		MP3100		MP3110		
Abbreviations		MP3100 (16 axes)	MP3100 (32 axes)	MP3110	MP3110M	
Mode	el	JAPMC-MC3100-1-E	JAPMC-MC3100-2-E	JAPMC-MC3110-E	JAPMC-MC3130-E	
	PCI Express standards	PCI Express 1.1 (Gen1)		PCI Express 1.1 (Gen1)		
ပ္သ	MECHATROLINK-III	1 circuit w	ith 2 ports	1 circuit with 2 ports	2 circuits with 4 ports	
Hardware specifications	USB	USB 2.0, Type A host, 1 port Compatible devices: USB storage		_		
Hai	Input and output signals	Inputs: DI × 5 inputs Outputs: DO × 4 outputs		_		
	Outer dimensions	PCI Express half size		PCI Express half size		
	Motion control	SVC/SVR	SVC32/SVR32	SoftMotion		
tions	Number of controlled axes	16 axes	32 axes	32 axes 64 axes		
Integrated functions	Program memory capacity	15 MB	31 MB	-	_	
Irate	Ladder program	Applicable		-		
) teg	Motion program	Applicable		-		
	Data tracing	Applicable		_		
	Data logging Applicable		-	_		

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# Machine Controller MP3000 Series

# MP3200

The MP3200 is the flagship model of the MP3000 series that integrates motion, vision, and robotics systems to provide the most optimal machine performance. Adjustments, design, and maintenance can be also centrally controlled using the MPE720 Ver. 7 system integrated engineering tool.



[Catalog No. KAEPC88072502]

# A Complete lineup

With the MP3200, you can select the Power Supply Units, CPU Units, and Base Units according to the control scale of your equipment. You can easily handle a multi-axis system by adding Rack Expansion Interface Units and Modules.

Power su	ipply unit
PSA-12	PSD-12
Input voltage: 85 VAC to 276 VAC	Input voltage: 24 VDC
, r.	S)

CPU	unit	
CPU-201	CPU-202	
Communication cycle: 250 $\mu$ s		

Base unit				
MBU-B08	MBU-B05	MBU-B03		
8 slots	5 slots	3 slots		
WIIIHII				

#### · Option

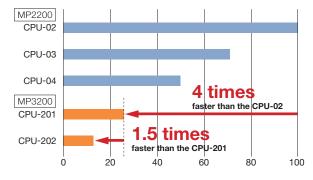
Rack Expansio	n Interface Unit
EXU-001	EXU-002
For main rack	For expansion rack

## Ultra-high-speed CPU

# Fastest application processing in the industry: 4-axis, $125 \mu s$

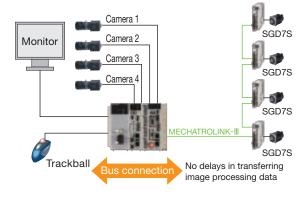
Arithmetic processing must be performed at higher speeds for systems to work faster. The MP3200 features the CPU-202, an ultra-high-speed CPU that runs 1.5 times faster than the CPU-201, to improve takt times.

#### When the scan time of the CPU-02=100



## Integration of motion and vision system

The CPU Unit and Vision Unit are connected using a high-speed bus which enables motion processing and vision processing to be executed with absolutely no communication delays. Four digital interface cameras, each with a different format, can be connected.



Note: Estimates are required before ordering the Vision Unit. Contact your Yaskawa representative for more information.

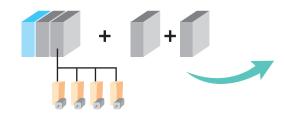


# Ideal for high-level automation

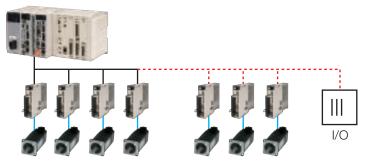
#### Control of 32 axes; systems expansion at no additional module

You can connect up to 42 stations (with up to 32 Servo Drives) to one MECHATROLINK-III channel, which provides leeway even for a large-scale system.

Previously, modules had to be added when a system was expanded.



With the MP3200, axes can be added with no additional modules (internal SVC.)



42 stations max. (Number of servo axes are 32 axes max.)

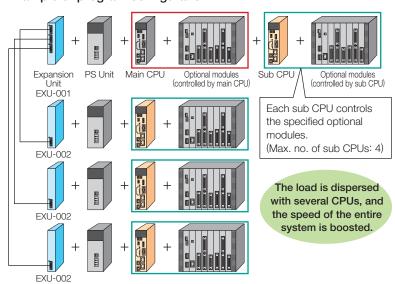
#### ■ Sub CPU Units to distribute the load and achieve a high-speed, high-precision system

A maximum 4 sub CPUs can be arranged by using Rack Expansion Interface Unit. Because both the main CPU and sub CPUs control optional modules, high-speed processing can be achieved even with large programs.

#### Sub CPU functions

Item	Sub CPU function
Connection method	MP3000 bus connection
Max. number of CPUs	5 CPUs (1 main CPU + 4 sub CPUs)
Data update cycle between CPUs	125 $\mu$ s, 250 $\mu$ s,32 ms
Max. CPU interface register size	Input: 2048 W Output: 2048 W
Servo connection for sub CPUs	For the servo connections on the sub-CPU side, 32 axes can be connected with the built-in SVC.

#### Example of program configuration



# Machine Controller MP3000 Series

# MP3300

The MP3300 Machine Controller makes it possible to freely combine the Base Unit and CPU modules to match the customer's control scale and control panel size. Combination with the  $\Sigma$ -7 series of AC Servo Drives realizes e-motional motion control in the customer's system.



[Catalog No. KAEPC88072503]

# A complete lineup

With the MP3300, you can select the CPU Unit type and MBU type according to the control scale of your equipment. There are a total of 16 possible combinations with 4 types of CPU Units and 4 types of MBUs.

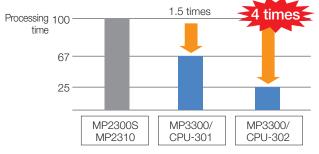
Mount Base Unit				
MBU-301	MBU-301 MBU-302		MBU-304	
85 VAC to 276 VAC		24 VDC 3 slots	24 VDC 1 slot	

CPU Module		
CPU-30	01/-302	
16 axes control User memory 15 MB	32 axes control User memory 31 MB	

# Enhanced control performance

The MP3300 delivers high-speed and high-level performances, and expands program capacity. The MP3300 is also capable of high-speed, synchronized communication with MECHATROLINK-III compatible Servo Drives and AC Drives.

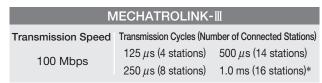
#### ■ Improved CPU performance\*



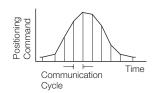
\*: Ladder operation speed where the scan time of the MP2300S/MP2310=100

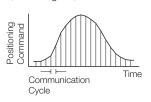
#### Fastest transmission cycle: 125 $\mu$ s (4 stations)

The MECHATROLINK-III motion network, which is among the fastest in the industry, is provided with the main unit CPU of the MP3300 as a standard option. The smoother motion control results in higher levels of precision.



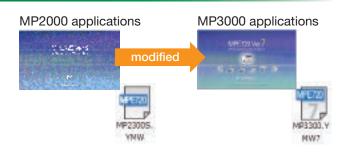
\*: The maximum number of stations, including I/O, is 21.





# Complete upper compatibility with the MP2000 series

The full lineup of optional modules and application programs for the MP2000 series can be used with the MP3300. This enables a completely hassle-free upgrade from the MP2000 series to the MP3300, which easily enhances system performance and functions.

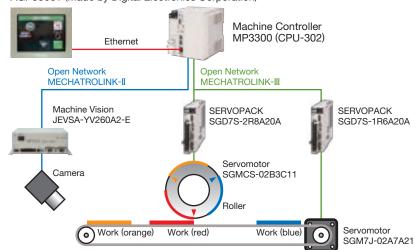


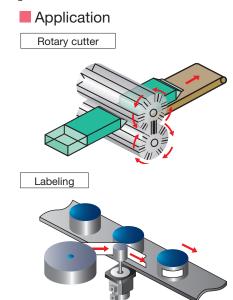


# High-precision, intermittent synchronization solutions

Intermittent synchronization of the rollers is performed between the lengths of workpieces on the belt. The MP3300 performs synchronized control only during the required sections of the linear operation of the belt and rotary operation of the rollers. This can be applied to many packaging machines, including rotary cutters and labeling machines.

# Operation panel AGP3300T (Made by Digital Electronics Corporation)



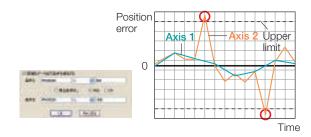


# **Enhanced maintainability**

A storage USB port is provided on the CPU Unit as a standard option, which makes it easy to update the version of the equipment, back up data, and import and export large-volume data. A data logging function also allows the system's operation statuses to be saved in the internal RAM or on a USB memory device. The logging data can be easily accessed from remote host systems. This makes it possible to acquire large volumes of data such as the system's operation statuses, and vastly improves traceability on the production site.

#### Data logging function

Settings can be selected for the conditions under which the logs are output. The logging data is saved only if the values of the specified registers fail to meet the output conditions. This enables a rapid response when trouble occurs.



#### Loading/saving function of program and data

Operations can be performed using the DIP switches on the CPU Unit body. Even in places where a PC cannot

be brought in, you can update the versions of the equipment and back up the data on-site with ease.



#### File transfer function

By transferring the system's operation data (logging data and register data) at the specified synchronization, large volumes of operation data can be acquired with no fear that the data may be unexpectedly damaged. As a result, the traceability at the production site is vastly improved.



# ∥ Common ∥

# Specification Comparison of MP3000 Series

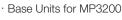
● : Applicable × : Not applicable

						• : Applicable	e × : Not applicable
		MP3100		MP3200		MP3300	
Items							
CPU		MP3100 (16 axes)	MP3100 (32 axes)	CPU-201	CPU-202	CPU-301 (16 axes) CPU-302 (16 axes)	CPU-301 (32 axes) CPU-302 (32 axes)
	e comparison of (when compared CPU-02)	6.0	6.0	4.0	6.0	CPU-301: 1.5 CPU-302: 4.0	CPU-301: 1.5 CPU-302: 4.0
Number of so		-	-	3/5	5/8	1/:	3/8
Rack expans	sion						
Multi-CPU c	configuration		•	● (Up to 5 modu main CPU		;	<
Communica	ition I/F	Ethernet × 1 p	ort: 100 Mbps	Ethernet × 2 por function):		Ethernet × 1 p	ort: 100 Mbps
USB I/F				Provided (for s	torage device)		
MECHATRO	DLINK I/F	Minimum comm	MECHATROLINK-III Provided Minimum communication cycle: 125 μs  MECHATROLINK-III Provided Provided Minimum cycle: 250 μs Minimum cycle: 125 μs		MECHATROLINK-III Provided Minimum communication cycle: CPU-301: 250 μs, CPU-302: 125 μs		
	SVC	16 axes	32 axes	32 a	ixes	16 axes	32 axes
Number of controlled	SVR	16 axes	32 axes	32 axes		16 axes	32 axes
axes	Maximum number of controlled axes	256 axes (when ontional modules are used or when rack			ks are expanded)		
,	Data tracing	256 K words	1 M words	1 M words		256 K words	1 M words
Program memory	Table data	1 M bytes	3 M bytes	3 M t	•	1 M bytes	3 M bytes
capacity	M registers			1 M v		I	
0 11 1	User memory	15 M bytes	31 M bytes	31 M		15 M bytes	31 M bytes
Optional mo MotomanSv		Ethornot/MD2000		MP2000 series opti			connection
MotomanSy	Number of	Ethernet/MP3000 bus connection Ethernet/MP3000 bus connection					
	ladder programs	High-speed scan DWGs: max. 1000, Low-speed scan DWGs: max. 2000, User function DWGs: max. 2000, Motion programs: max. 512  S/M/G/I/O/C/D/#					
Basic functions	Register types						
TUTICUOTIS	Data types Index registers	B/W/L/Q/F/D/A					
	Register capacity	Subscripts I /J, and array registers  M registers: 1 M words, G registers: 2 M words					
Motion	Slave functions	INITEGISLETS: 1 IVI WOTAS, G TEGISLETS: 2 IVI WOTAS					
control	Slave CPU synchronization				•		
Communication	Automatic reception		● (Maximu	m number of autom	atic reception conn	ections: 10)	
functions	File transfer reception	● (FTP server/client)					
	Number of groups			1, 2, 4 (se	electable)		
Data tracing	Trace memory	256 K words/ 4 groups	1 M words/ 4 groups		s/4 groups	256 K words/ 4 groups	1 M words/ 4 groups
functions	Traceable data points	16 points/group					
Data logging functions		Number of groups: 4 Number of log files: Built-in RAM disk (max. 8 MB), or USB memory device (4 GB*) Data logging points: 64 points					
USB memory functions				ect files, data loggir	ng, import/export of	f register data	
Linkage functions for Servo tracing			•	and reggii	)ps. 4 oxport of	129.515. 3414	•



# All MP2000 optional modules supported

Approximately 30 types of MP2000 optional modules can be connected for a high degree of expandability.











#### ■ Option Modules for MP3000 and MP2000 series

#### Motion Modules



Connects to the SERVOPACK for motion control. Various MECHATROLINK slaves can be connected to the SVC-01 or SVB-01 module.

Name	Model	Description
SVC- 01	JAPMC -MC2320-E	MECHATROLINK- <b>Ⅲ</b> × 1
SVB- 01	JAPMC -MC2310-E	MECHATROLINK-II×1
SVA- 01	JAPMC -MC2300	Analog-output 2-axis servo control
PO-01	JAPMC -PL2310-E	Pulse-output 4-axis servo control

Note: One CPU can control up to 16 modules.

#### **Expansion Interface Module**

Used to connect the Expansion Rack (MP2200 Base Units MBU-01/-02/-03) to add the option modules.

Name	Model	Description
EXIOIF	JAPMC- FX2200-F	Expansion Interface

Note: Use the EXU-001 and -002 units when using Rack Expansions with sub-CPU for MP3200.

#### I/O Modules



Provides digital or analog I/O interface.

Name	Model	Description
LIO-01	JAPMC -IO2300-E	Digital input: 16 points (sink output mode) Digital output: 16 points (sink output mode) Pulse input: 1 point
LIO-02	JAPMC -IO2301-E	Digital input: 16 points (source output mode) Digital output: 16 points (source output mode) Pulse input: 1 point
LIO-04	JAPMC -IO2303-E	Digital input: 32 points Digital output: 32 points (sink output mode)
LIO-05	JAPMC -IO2304-E	Digital input: 32 points Digital output: 32 points (source output mode)
LIO-06	JAPMC -IO2305-E	Digital input: 8 points Digital output: 8 points (sink output mode) Analog input: 1 channel Analog output: 1 channel Pulse counter: 1 channel
DO-01	JAPMC -DO2300-E	Digital output: 64 points (sink output mode)
AI-01	JAPMC -AN2300-E	Analog input: 8 channels
AO-01	JAPMC -AN2310-E	Analog output: 4 channels
CNTR-01	JAPMC -PL2300-E	Pulse-input counter

Note: One CPU can control unlimited number of modules.

#### Communication Modules



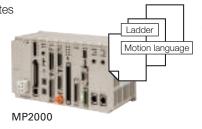
Used to construct an open network. Modules with various types of interfaces are available.

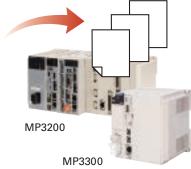
Name	Model	Description
218IF-01	JAPMC -CM2300-E	Ethernet (10BASE-T) port × 1 RS-232C port×1
218IF-02	JAPMC -CM2302-E	Ethernet (100BASE-TX) port $\times$ 1 RS-232C port $\times$ 1
217IF-01	JAPMC -CM2310-E	RS-232C port × 1 RS-422/485 port × 1
260IF-01	JAPMC -CM2320-E	DeviceNet port × 1 RS-232C port × 1
261IF-01	JAPMC -CM2330-E	PROFIBUS port × 1 RS-232C port × 1
262IF-01	JAPMC -CM2303-E	FL-net (100BASE-TX) port × 1 (10BASE-TX) port × 1
263IF-01 EtherNet/IP	JAPMC -CM2304-E	EtherNet/IP (Scanner and adapter) port × 1
264IF-01 EtherCAT	JAPMC -CM2305-E	Port for EtherCAT slave × 2 (1 circuit)
265IF-01 CompoNet	JAPMC -CM2390-E	CompoNet port × 1
215AIF-01 MPLINK	JAPMC -CM2360-E	MPLINK communication/ RS-232C
215AIF-01 CP-215	JAPMC -CM2361	CP-215 communication/ RS-232C
266IF-01 PROFINET	JAPMC -CM2306-E	PROFINET master*
266IF-02 PROFINET	JAPMC -CM2307-E	PROFINET slave
269IF-01 CC-Link	JAPMC -CM2308-E	CC-Link IE Field Slave

\*: Estimates are required before ordering this product.
Contact your Yaskawa representative for more information.
Note: One CPU can control up to 8 modules.
For RS-232C communications, 16 ports can be used.

# MP2000 application programs usable without modifications

Compatibility with the MP2000 applications eliminates the need for re-design and paves the way to the effective use of software resources.





# AC Servo Drives

The AC Servo Drives  $\Sigma$  series guarantees maximum performance as the core components of systems.

Yaskawa introduced its AC Servo Drives to the market in 1983, and further marketed the  $\Sigma$  series in 1992. Since then, Yaskawa has continued to develop the  $\Sigma$  series, focusing on making these products compact, and enhancing performance and ease of use. As a result of these efforts, the total shipments of AC servomotors reached 10 million units in March 2012.

Yaskawa will continue to develop world-class AC Servo Drives to provide even greater satisfaction to its customers.



The  $\Sigma$ -7 series delivers a leading performance based on the concept of "7 ultimate e-motional solutions." These Servo Drives also support a variety of new needs, such as further enhancing safety and incorporating environmentally friendly designs.







\*: Applied upon order



NEW CONCEPT Z-S Series

Easy, compact, and low price! The  $\Sigma$ -S series is recommended for applications that do not conventionally use Servo Drives, and enables servo control of pneumatic and other equipment.



Lineup Page 39

## **SERVOPACK**







 $\Sigma$ -7W



 $\Sigma$ -7C

Single-phase, 100 VAC

50 W to 400 W

Three-phase, 200 VAC 50 W to 15 kW

200 W to 1.0 kW 200 W to 1.0 kW

# Servomotor



Rotary Servomotors

10 W to 15 kW



Direct Drive Servomotors



### 3.3 W to 30 W

# $\Sigma$ -Vmini/ $\Sigma$ -V-MD

The powerful  $\Sigma$ -Vmini Servo Drives retain all the leading performance, functionality and ease of use of the  $\Sigma$ -V series in a palm-size package.

These board-type SERVOPACKs enable multi-axis control.



 $\Sigma$ -Vmini



### 22 kW to 55 kW

## Large-capacity $\sum$ - $\bigvee$

Large-capacity  $\Sigma$ -V Servo Drives feature superlative performance, simple startup, and outstanding expand ability. These drives also help achieve considerable energy savings.





# $\Sigma$ -7 Series

The  $\Sigma$ -7 series delivers a world-leading performance based on the concept of "7 ultimate e-motional solutions." These Servo Drives also support a variety of new needs, such as further enhancing safety and incorporating environmentally friendly designs. This makes it possible to offer solutions that can satisfy a wide range of conditions throughout the system lifecycle.

[Catalog No. KAEPS80000123]



### **Features**

### Ultimate system performance

 $\Sigma$ -7 series SERVOPACKs can achieve a high-speed response frequency of 3.1 kHz. Vibration suppression functions have also been enhanced. The motors incorporate 24-bit, high-resolution encoders that further increase system takt times and achieve a high throughput.

### Ultimate environmental performance

Specifications have been improved to allow installation in a wider range of environments. These new safe and secure designs enable use even in harsh environments where previously prohibited, such as altitudes of 2,000 m or ambient temperatures of  $60^{\circ}\text{C*}^{1}$ . Regenerative servo energy inside the system can also be effectively used with 2-axis integrated SERVOPACKs or by connecting multiple axes with a DC bus connection.

### Ultimate support

- Build-To-Order service (BTO)
   Products can be shipped from the factory with the specified parameters, which helps to reduce system production lead times
- Product control and maintenance support
   Product QR codes can be read using Yaskawa's SigmaTouch! smartphone application. This allows users to view manuals and troubleshooting information.

### Ultimate compatibility

Mounting compatibility with the  $\Sigma$ -V series is ensured, and  $\Sigma$ -V parameters can be converted simultaneously to  $\Sigma$ -7 parameters using the SigmaWin+ parameter converter.

### Ultimate ease of use

Tuning-less function stability has been increased to approximately twice that of the  $\Sigma$ -V series. This enables swift movement with no vibration or gain adjustment.

### Ultimate safety and security

Σ-V Servo Drives satisfy of SIL3 the functional safety standard IEC61508 (first certification in Japan\*<sup>2</sup>). Temperature sensors are incorporated as a standard feature, and signs of abnormalities can be caught at an early stage by monitoring the temperature from a host controller.

### Ultimate lineup

In addition to Yaskawa's products, our partner companies in the MECHATROLINK Members Association (MMA) offer an extensive lineup of I/O devices and sensors, and provide all the components needed to construct equipment motion systems.

- \*1 : Derating required.
- \*2 : As investigated by Yaskawa.





∑-7S
Single-axis SERVOPACK
100 VAC/200 VAC
50 W to 15 kW

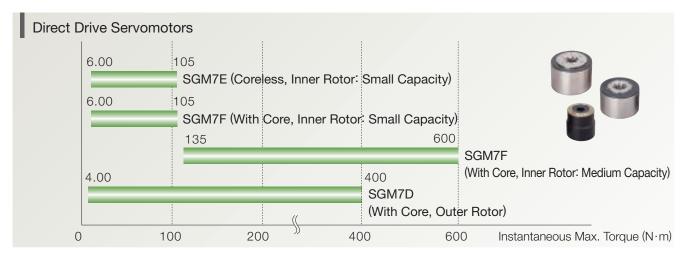


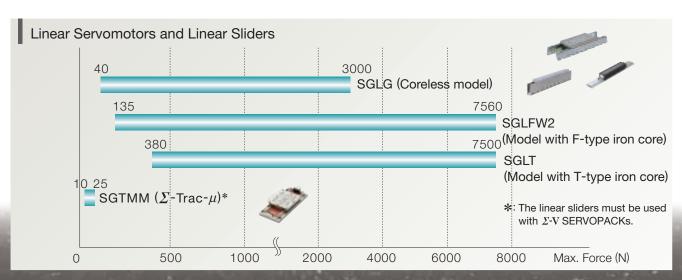
∑-7W
Two-axis SERVOPACK
200 VAC
200 W to 1.0 kW



∑-7C
Two-axis SERVOPACK
with built-in Controller
200 VAC
200 W to 1.0 kW







### SERVOPACK

### **SERVOPACKs**



Single-axis MECHATROLINK-III communications reference  $\Sigma$ -7S



Two-axis MECHATROLINK-III communications reference  $\Sigma$ -7W



Single-axis MECHATROLINK-II communications reference  $\Sigma$ -7S



Analog voltage/ pulse train reference

### MECHATROLINK-III/-II Communications Reference

### ©Real-time communication

A high transmission speed allows real-time transmission of various data required for control.

### Cost savings

Multiple stations can be connected to a single MECHATROLINK transmission line, so wiring costs and time are greatly reduced. Also, only one signal connector is required on the host controller. The all-digital network eliminates the need for a converter to change speed/torque references from digital to analog and for a pulse generator to create position references.

### ©High-precision motion control

The SERVOPACK when connected to the host controller in the MECHATROLINK-III/-II network provides not only torque, position, and speed control, but also synchronized phase control that requires advanced control technology. The control mode can be changed online so that the machine can move smoothly in complex motions with great efficiency.

Communications protocol	MECHATROLINK-III	MECHATROLINK-II
Physical layer	Ethernet	Same as RS-485
Baud rate	100 Mbps	10 Mbps
Transmission cycle	$\Sigma$ -7 $S$ : 125 $\mu$ s to 4 ms, $\Sigma$ -7 $W$ : 250 $\mu$ s to 4 ms	125 $\mu$ s to 4 ms
Number of transmission bytes	32 or 48 bytes/station	17 or 32 bytes/station
Number of slaves	62 max.	30 max.
Maximum transmission distance	75 m between stations	50 m total (100 m with Repeater)
Minimum distance between stations	20 cm	50 cm

### Analog Voltage/Pulse Train Reference

	Chand	Reference	Max. input	±12 V (forward s	peed reference with positive reference)											
/oltage e	Speed	voltage	Factory	6 VDC at rated s	peed (Input gain setting can be changed.)											
Analog voltage reference	Torque	Reference	Max. input voltage	±12 V (forward to	±12 V (forward torque reference with positive reference)											
control voltage		Factory setting	3 VDC at rated torque (Input gain setting can be changed.)													
φ			Туре	Select one: Sign + pulse train, CW + CCW pulse train, or two-phase pulse train with 90° phase differential												
enc			Form	For line driver, or	pen collector											
rain refer	Docition 1	Position p	Reference pulse										n pulse	Max. input	Line driver	Sign + pulse train, CW + CCW pulse train: 4 Mpps Two-phase pulse train with 90° phase differential: 1 Mpps
Pulse t			frequency*	Open Collector	Sign + pulse train, CW + CCW pulse train: 200 kpps Two-phase pulse train with 90° phase differential: 200 kpps											
		Clear signal (Position erro	or clear)	For line driver, or	pen collector											

<sup>\*:</sup> If the maximum reference frequency exceeds 1 Mpps, use a shielded cable for I/O signals and ground both ends of the shield. Connect the shield at the SERVOPACK to the connector shell.

### Command Option Attachable Type

- $\bigcirc$ Compatible with all features of the new  $\Sigma$ -V Series
- SERVOPACKs can interface with various communication formats by using attachable optional modules for commands.

Note: Be sure to use INDEXER or DeviceNet optional modules for the command option attachable type SERVOPACKs. They will not work without these modules.





Command Option Attachable Type

### SERVOPACK With Optional Module



Optimal expandability can be achieved by attaching an optional module to the SERVOPACK.

Combination of SERVOPACKs and Option Modules

√: Possible X: Not Possible

			Option Module		
	SERVOPACK (Model Number)		Fully-Closed Module (SGDV-OFA01A)	Safety Module (SGDV-OSA01A)	
Analog Voltage and Pulse Train	✓ *1	✓ *1			
MECHATROLINK-II Communica	ations Reference (Single Axis: SG	GD7S-□□□□10A)	✓ *1	✓ *1	
MECHATROLINK-III Communica	✓ *1	✓ *1			
MECHATROLINK-III Communica	×	×			
SERVOPACK with Option Module (Set Model Number)	SERVOPACK (Model Number)				
INDEXER Module-Mounted Type (SGD7S - E0A - 10 - 10 - 1)	Command Option	INDEXER (SGDV-OCA03A)	<b>~</b>	×	
DeviceNet Module-Mounted Type	Attachable Type (Single Axis: SGD7S-□□□□E0A)	DeviceNet*2 (SGDV-OCA04A)	✓	×	
(SGD7SE0A50)*2 (SGD7SE0A60)*3		DeviceNet*3 (SGDV-OCA05A)	✓	×	

**INDEXER Module** 

### Simple

- Interactive methods for everything from adjustment to programming are available with the setup support tool SigmaWin+ for Windows (Ver.5.72 or later).
- O Simple connection to the host controller can be established with the I/O module.

### Smart

O Special languages are not required, because required operation patterns are easily made by simply setting the data for position and speed in program tables. Optimum operation method supports your application. For positioning, up to 256 steps can be programmed.

(Operation) Program tables,

Position and speed tables (station positioning), Registration (positioning by external signals), Serial communication

O Various functions, including external positioning, JOG table operation, homing, and programmable signal outputs are provided.

### Speedy

- © Reliable high-speed, high-precision positioning when combined with high-performance  $\Sigma$ -7S SERVOPACKs.
- Motion control is accomplished without using motion controllers.

Note: The INDEXER module can be used in combination with the Fully-Closed Module.



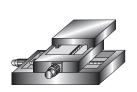


Program Table Editing Window

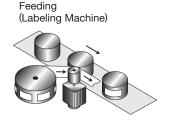
### Specifications

Function	Specifications
Stations for Program	256
Table Operation	230
JOG Speed Setting	16
ZONE Signal Output	32
Serial Communication	HR: ASCII; max. axes: 16 MEMOBUS: Binary
Homing Methods	3
Equally-dividing and Indexing Positioning (Station Positioning Command)	Rotary machine and tool setting

### Application Examples Point-to-point positioning (X-Y Table)







<sup>\*1:</sup> You cannot use a Fully-Closed Module and a Safety Module together.
\*2: Driven by SERVOPACK control power supply.
\*3: Driven by external power supply.

### SERVOPACK

With Optional Module

### **Using Commands**

DeviceNet Module

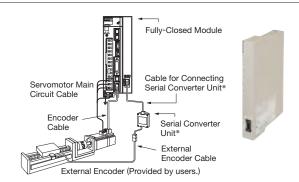
- © Compliant with the communication specifications of the DeviceNet open field network.
- Maintainability improved by the host controller using DeviceNet to monitor the operating conditions of servo drives, alarm status, and other information.
- © Full range of positioning functions featured including simple positioning, homing, continuous speed operation, positioning after continuous speed operation, and programmed operation.
- © Round micro-connectors used for the connectors.
- Modules can be driven by two different power-supply methods: servo control power or external power.

Note: The DeviceNet module can be used in combination with the Fully-Closed Module.



### Fully-Closed Module

- O High-precision and high-response positioning by using feedback from detector (such as an external encoder) installed on the machine.
- O High resolution with external encoders (linear) scales).
- \*: Not required depending on the type of the external encoder. Note: The Fully-Closed Module can be used in combination with the INDEXER module or DeviceNet module.



Safety Module

The Safety Module complies with EN ISO13849-1 (the standards harmonized with EU Machinery Directive 2006/42/EC) and has safety functions equivalent to those stipulated in IEC61800-5-2. By using  $\Sigma$ -7S SERVOPACKs with the safety module, optimum safety designs can be created for mechanical systems to better meet the needs of the industry.

- © The first product for AC servo drives in Japan that has safety functions equivalent to the following ones stipulated in the international standard IEC Safe Torque Off (STO), Safe Stop 1 (SS1), Safe Stop 2 (SS2), Safely-Limited Speed (SLS)
- © Two safety functions (A and B) are provided and stopping functions can be allocated individually to these safety functions.
- © With the attachable Safety Modules for SERVOPACKs, system configurations are simplified and compact.



### ■With Functions Defined by IEC61800-5-2

By using the Hard Wire Base Block function (HWBB) of SERVOPACKs, the following four safety functions can be achieved.

0-4-4	A li a a la la	Products			
Safety Standards	Applicable Standards	SERVO PACK	SERVOPACK + Safety Module		
Safety of Machinery	EN ISO13849-1: 2015 IEC 60204-1	0	0		
Functional Safety	IEC 61508 Series IEC 62061 IEC 61800-5-2	0	0		
EMC	IEC 61326-3-1	0	0		

■Compliance with Safety Standards

0.51		I	Products
Safety Function	Description	SERVO PACK	SERVOPACK + Safety Module
Safe Base Block Function (SBB function)	This safety function is equivalent to the STO function. It shuts OFF the power supply to the motor.	0	0
Safe Base Block with Delay Function (SBB-D function)	This safety function is equivalent to the SS1 function. It shuts OFF the power supply to the motor after monitoring the deceleration of the motor for the specified length of time.	_	0
Safe Position Monitor with Delay Function (SPM-D function)	This safety function is equivalent to the SS2 function. It monitors the deceleration of the motor for the specified length of time and the position after the motor has stopped.	_	0
Safely Limit Speed with Delay Function (SLS-D function)	This safety function is equivalent to the SLS function. It monitors the deceleration of the motor for the specified length of time and the motor speed to make sure it is within the allowable range.	_	0





### **Choose the Best SERVOPACK for the Application**

The know-how we have acquired in every market has resulted in the creation of a lineup of SERVOPACKs with FT specifications that have added functions to optimally suit a variety of applications.

√ : Possible 
− : Not Possible

FT	Applications	Additional Functions	Features		Interface		
Specifications	Applications	Additional Functions		A/P	M-II	M-III	
FT19	Tracking	Built-in Less Deviation Control	Little delay in motor operations for position references as a result of built-in less deviation control. Ideal for applications that require reference tracking performance (high position accuracy) during movement.	V	-	V	
FT21	Machining and Cutting	Feed Shaft Supporting	Improved tracking ability and high-accuracy machining operations with the use of clearance (constant distance) control, predictive control, and quadrant projection compensation functions.	_	-	V	
FT40	Press and Injection Molding	Pressure Feedback	Highly accurate pressure control with input of pressure sensor signals directly to the SERVOPACK.	-	-	V	
FT41	Press and Injection Molding	Pressure Feedback	Highly accurate pressure control by feeding back the signals of the pressure sensors directly to the SERVOPACK through the MECHATROLINK-I/O system.	-	-	V	
FT60	Conveyance Three-Point Latching		The host controller can detect the orientation of the workpiece or offsets in multiple workpieces based on the information on the three positions input to the SERVOPACK.		-	V	
FT62	Conveyance and Alignment	Triggers at Pre-set Positions and Rotational Coordinate System	points to enable coordinated operations with the use of trigger signals. Turntables can be easily		-	V	
FT63	Conveyance	Built-in Semi- Closed/Fully-Closed Loop Control Online Switching Function	Allows loop control to be switched between semi- closed/fully-closed while online.	V	-	V	
FT70	Gantry	Built-in Optimal Gantry Control	Three built-in functions (Position correction table, Synchronized stopping during alarms, and the Position deviation between axes overflow detection) effective for driving gantries		-	V	
FT77	Conveyance	Built-in Torque/ Force Assistance	Multiple SERVOPACKs can be used for applications that require more than one axis to easily build a system will increase the torque or force up to five times.		_	V	
FT79	FT79 Indexing Built-in INDEXER		Convenient positioning functions (ZONE signal outputs, job speed table, homing, other) added for high-precision and high-speed positioning without a motion controller.	V	_	-	
FT82	For Special Motors	SGM7D Motor Drive	SERVOPACKs with high torque, high precision, and a user-friendly design for SGM7D motors.	V	V	V	
FT83	For Special Motors	SGM7D Motor Drive	SERVOPACKs with built-in INDEXER for SGM7D motors.	V	-	-	

### SERVOPACK

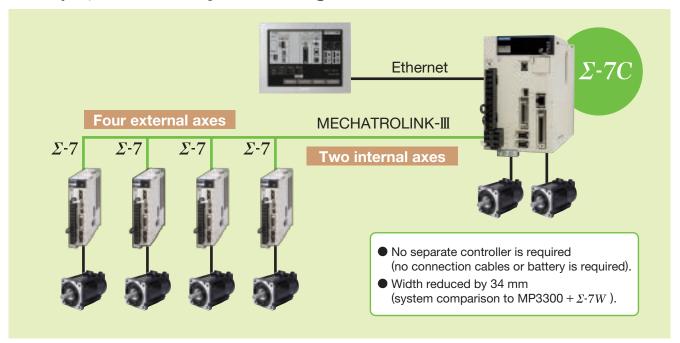




# New Two-Axis SERVOPACKs with Built-in Controllers!

Yaskawa's newest two-axis SERVOPACKs with built-in controllers offer the ideal configuration to control small-scale equipment and mechanisms to meet the increasing needs of component downsizing, equipment modularization, and system distribution.

### Simple, All-in-One System Configuration



### Features

### Less system space required

- Configure up to six axes.
- Build small-scale equipment system without PLC using one SERVOPACK.
- Expand functionality by mounting an Option Base Unit.

### Equipment modularization and distributed control system

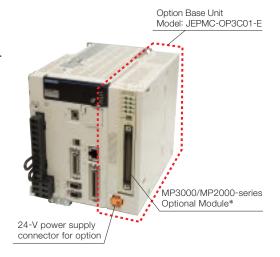
O Reduce burden of designing software when part of the equipment changes.

### **High-Speed Response**

- O High-speed response frequency of 3.1 kHz has been achieved.
- O High-speed I/O used for the Controller Function Module.
- The command/response delay is minimized with the two internal axes.
  These axes can be synchronized with the external axes.

### **Easier Maintenance**

- No battery is required for the Controller Function Module, which reduces the time and cost of periodic replacement.
- Protective functions have been improved for outputs to the Controller Function Module.



\*: Excluding the following Optional Modules: SVA-01, SVB-01, SVC-01, PO-01, MPU-01, 215AIF-01, and EXIOIF.



### **Rotary Servomotors**

Rated output	Rated speed/ Max. speed (min <sup>-1</sup> )
l	



### SGMMV model (Low inertia, ultra-small capacity)

- O Contributes to machine downsizing (flange size: 25 mm × 25 mm).
- O Mounted high-resolution serial encoder: 17 bits



### SGM7J model (Medium inertia, high speed) 50 W to 750 W 3000/6000

- O Protective structure: IP67
- O Mounted high-resolution serial encoder: 24 bits
- O Cable installation direction is possible both of the toward load, and away from load.



### SGM7A model (Low inertia, high speed)

50 W to 7 kW

3000/6000

- □ Instantaneous peak torque: 350% of rated torque (For motors of less than 1 kW)
- O Protective structure: IP67 (IP22 for 7.0 kW motor)
- O Mounted high-resolution serial encoder: 24 bits
- Ocable installation direction is possible both toward load and away from load. (For motors of less than 1 kW)



### SGM7P model (Medium inertia, flat type)

100 W to 1.5 kW

3000/6000

- O Mounted high-resolution serial encoder: 24 bits



### SGM7G model (Medium inertia, large torque)

300 W to 15 kW

1500/3000

- O Protective structure: IP67
- O Mounted high-resolution serial encoder: 24 bits



### **Servomotors with Batteryless Absolute Encoders** (Except SGMMV model)

You can eliminate Batteries and Battery Cases used for individual Servo Drives or on the host controller to simplify wiring in the control panel.

# Maintenance-free

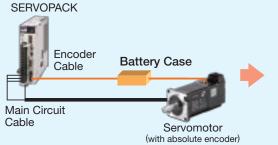
No time or effort for replacement

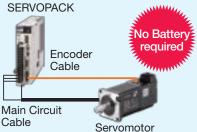


### **Easier Wiring**

 $\Sigma$ -7-Series Applicable models

- · SGM7J
- · SGM7A
- · SGM7P
- · SGM7G





(with Batteryless Absolute Encoder)

45

# AC Servo Drives 2-7 Series

### Servomotor

### **Direct Drive Servomotors**



### Coreless, Inner Rotor (SGM7E)

Outer Diameter Rated Torque Max. Torque (mm) (N·m) (N·m)

135 to 290 2 to 35 6 to 105

Ideal for applications that require smooth movement without speed fluctuations.

- O Built-in 24-bit encoder.
- O Low cogging with a core-less system provides smooth operation free from speed variations.



### With Core, Inner Rotor (SGM7F)

100 to 360 2 to 200 6 to 600



Ideal for applications that require downsizing and a shorter takt time.

- □ Built-in 24-bit encoder. □ Compact design with small rotor diameter.
- High-speed, high-frequency positioning. Low inertia. Low heat generation.



### With Core, Outer Rotor (SGM7D)

1.3 to 240 4 to 400

Ideal for applications that require high torque, high precision, and high rigidity.

Compatible with former Yokogawa Electric DYNASERV Motors.

- Built-in 24-bit encoder. 
   Application to large loads possible with a high allowable load moment of inertia ratio.
- © Large center aperture design provides more space available for wiring connections. © High rigidity.

### **Linear Servomotors**



### SGLG (Coreless model)

, ,	(m/s)	(IV)	(IV)
Standard	4 to 5	12.5 to 750	40 to 3000
High force	4.2	57 to 255	230 to 1080

Max. speed | Rated force |

Peak force

- O Direct-feed mechanism for high-speed and high-precision positioning
- Lack of magnetic attraction force helps extend the life of linear motion guides and minimizes noise.
- Zero cogging for minimal force ripple



### SGLFW2 (Model with F-type iron core) | Standard 2.5 to 5

- O Direct-feed mechanism for high-speed and high-precision positioning
- The large magnetic attraction force between the moving and stationary members can be used to effectively increase the rigidity by preloading the linear guide.
- The magnetic preloading on linear guide can help increase the system's frequency response, improving its damping and settling performances.



- **SGLTW** (Model with T-type iron core) 130 to 2000 380 to 7500 Standard 2.5 to 5 High force 3.1 to 4.8 300 to 900 | 600 to 1800 O Direct-feed mechanism for high-speed
- and high-precision positioning
- Yaskawa's unique construction principles of the SGLTW linear motors negate the effects of the magnetic attraction force between the relative motor members.
- Lack of magnetic attraction force helps extend the life of linear motion guides and minimizes noise.
- Very little cogging

### Linear Sliders

### **SGTMM**( $\Sigma$ -Trac- $\mu$ )

Standard 1	1.0 to 1.5	3.5 to 7	10 to 25
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- Ultra-flat profile reduces floor space requirements.
- For applications requiring short strokes
- Vibration-free transmission device enables high-precision positioning with a repetitive positioning accuracy of  $\pm 0.5$  m max.
- Locations of armature coils on the stator reduce the effects of heat on the table or workpiece.

Note: These linear sliders must be used with  $\Sigma$ -V SERVOPACKs.

### AC Servo Drives

### Large-capacity 2-V<sub>Series</sub>

Announcing the debut of a large-capacity servo drive series which follows in the footsteps of the series with its superlative performance, simple startup, and outstanding expandability. Considerable energy savings enabled by using a separate converter.





[Catalog No. KAEPS80000086]

### Combinations

Combinations			200 V				400 V		
Rated output		22 kW	30 kW	37 kW	22 kW	30 kW	37 kW	45 kW	55 kW
Servon	notor SGMVV-	2BA	3ZA	3GA	2BD	3ZD	3GD	4ED	5ED
SERVOPACK SGDV-		121H	161H	201H	75	0J	101J	13	1J
Converter SGDV-COA		2BAA	3G	AA	3Z	DA		5EDA	











\*: For detail, contact your Yaskawa representative.

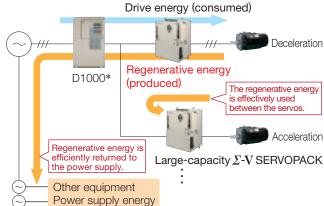
### Upgraded by combining a Machine Controller

- O High torque can be generated with synchronized control of multiple axes.
- © The high-precision synchronized control of multiple axes (roller, takeup, etc.) increases quality.
- O Seamless switching between position control and torque control improves machine takt time.

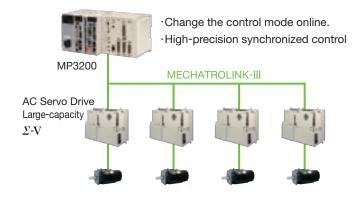
### Easily build an energy-saving system

By separating the converter, optimal support can be provided for a power regeneration converter or common converter. This paves the way for broad-based energy savings in the systems with, for instance, the regeneration of the energy produced during motor deceleration at the power supply side.

### ■Energy-saving Application Example



\*: D1000 is the sine-wave PWM converter able to regenerate power. In combination with an AC drive, realizes high power factor operation, and entirely eliminates problems of power source harmonics.



### **Application Examples**

### Machine Tools

Helps meet speed and capacity demands of feed and spindle motors in high-speed, heavy-duty machining applications.

### Rotary Cutters

Outstanding acceleration/deceleration torque for high-speed tracking

### Transfer Presses

The large-capacity servo drives bring better levels of performance to today's large, high-speed machinery, improving operations with digitalization and making them quieter than ever.

### Servo Presses

To attain cleaner and more efficient operation, servo presses are now being driven electrically instead of hydraulically. Energy savings in servo presses are also achieved thanks to the use of power regeneration converters.

### Injection Molding Systems

High-resolution encoders for higher levels of precision in injection control.

### Wire Saws

With a greater cutting force due to the high torque, saws can now cut hard materials. When combined with the MP series, it is possible to synchronize roller shafts, wind-up shafts and other such parts to a high level of precision.







# AC Servo Drives $\Sigma$ -Vmini Series

These ultra-compact Servo Drives retain all the leading performance, functionality and ease of use of the  $\Sigma$ -V series in a palm-size package.

 $\Sigma$ -V mini Servo Drives operate with DC power input (main circuit power supply 24 VDC/ 48 VDC; control power supply 24 VDC), which makes them well-suited for clean room robots and clean AGVs\*1 and other battery-driven transport systems.

[Catalog No. KAEPS80000042]

### Features

- Helps reduce the overall size of control boards and machinery.
   Servomotor dimensions (See table on right)
   SERVOPACK dimensions: 100\*2 (H) × 30 (W) × 80 (D) mm
- Model tracking control, anti-vibration control, and friction compensation functions
- \*1: Automated Guided Vehicle.
- \*2: Size: 116 mm including the mounting base



SERVOPACK Model SGDV-

### Servomotor Specifications

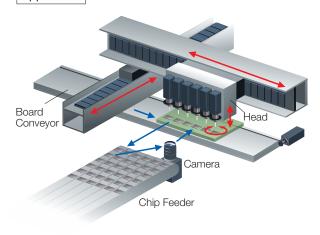
Model SGMMV-	Rated Output (W)	Rated Motor Speed/ Max. Motor Speed (min <sup>-1</sup> )	Square Flange Dimensions (mm)	Total Length (mm)
взЕ	3.3			58
B5E	5.5		15	64
B9E	11	3000/6000		98
A1E	10	3000/8000		70
A2E	20		25	80
A3E	30			90

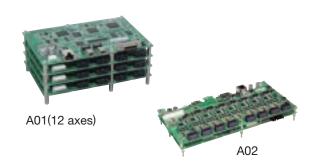
### ∑-V-MD Series A01/A02

These board-type SERVOPACKs enable multi-axis control of  $\Sigma\text{-V}$  mini servomotors.

The machine size and wiring can be reduced by incorporating  $\Sigma$ -V-MD SERVOPACKs into the moving parts of chip mounters and other equipment. Two types are available: the A01 that enables easy expansion of the number of axes (4, 8, or 12 axes), and the 8-axis integrated type A02.







SERVOPACK Model SGDV-MDA EM3A Servomotor Model SGMMV

### **SERVOPACK Specifications**

Model	SGDV-MD A01	SGDV-MD A02				
Number of Axes	4, 8, or 12	8				
Interface	MECHATROLINK-III (transmission cycle: 250 $\mu$ s to 4 ms)					
Innut Davier Cumply	Main circuit: 24 VDC/ 48 VDC					
Input Power Supply	Control circuit: 24 VDC					
Applicable Motor	SGMMV: 3.3 W to 30 W					
	4 axes: 170×115×46					
Dimensions (mm)	8 axes: 170×115×61	238×120×29				
	12 axes: 170×115×76					



The  $\Sigma$ -S series was developed to be compact, easy to use, and available at a low price, which makes it an ideal product for applications that do not conventionally use Servo Drives.



### Potential applications of the $\Sigma$ -S Series in pneumatic equipment

### Advantages of the $\Sigma$ -S Series Suggestion 1: Electric chuck Impressive reference tracking capability and reductions in takt time © Easy adjustment of chucking holding power using torque limit Energy savings achieved and running costs reduced Multi-point positioning enabled (expanded range of applications) Cow-level operating noise Suggestion 2: Electric actuator Compressor Servomotor Pneumatic Air-pressure Directional actuator Air purifier auxiliary device control device Motor Electricity Energy conversion Energy conversion Pressure transmission Electric power conversion loss: High loss: High loss: High loss: Low

### Features

### 1. Hold-in-place operation

Workpiece can be held in place at any torque.

### 2. Multi-point positioning

Positions can be set according to the size of the workpiece.

### 3. Program tables

Programming can be simplified by setting numerical values in the tables provided.

### 4. ZONE output

Users can recognize that the actuator is operating within the specified range.

5. Acceleration/deceleration control Impacts on the workpiece can be reduced.

### SERVOPACK Specifications

- Power supply: 24 VDC (Common input for main circuit and control circuit)
- Reference interfaces (2 types): ① Contact commands (program table method) ② Pulse train references
- Dimensions: 80 mm × 123 mm

### Servomotor Specifications

Model SGMSL-	Rated Output (W)	Rated Motor Speed/ Max. Motor Speed (min <sup>-1</sup> )	Encoder	Square Flange Dimensions (mm)	Total Length (mm)
А3	30	3000/6000	Incremental,	25	85
A5	50	3000/3000	10 bits	40	92

SigmaSize+ is a Web-based software application used to easily select the optimal YASKAWA servo drives for your machinery. SigmaSize+ is available from our website at http://www.e-mechatronics.com.

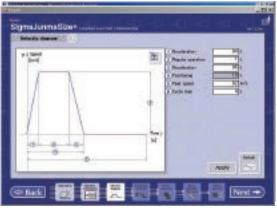
### Features

- 1. A wide range of the latest information.
- 2. A wizard system with a conversational mode to select optimal servo drives.
- 3. View SigmaSize+ in your browser wherever internet access is available. (Enhanced security measures with cryptographics)
- 4. Available to view and reuse previously input and stored data.

### Servo Selection Screen



**Application Selection Window** 



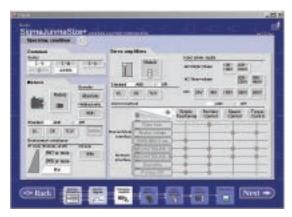
Velocity Diagram Input Window



Motor Selection Window



Machine Information Input Window



Operating Condition Selection Window



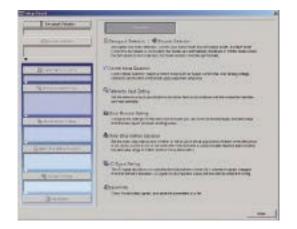
SERVOPACK Selection Window

# SigmaWin+

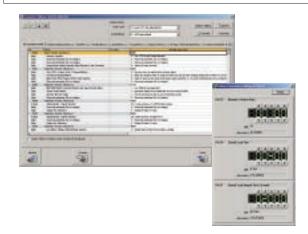
Supported OS: Windows 10/8.1/8/7

SigmaWin+ is a Windows-based engineering PC tool with various monitoring functions to make quick and easy adjustments to the settings for Yaskawa servo drives. SigmaWin+ supports a widerange of operations from setting parameters to trial operation.

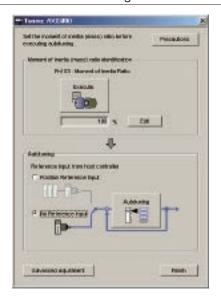
### Setup using Wizard



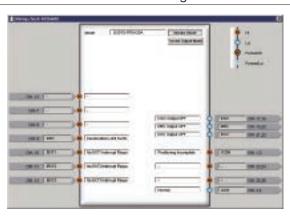
Parameter Edit (at online)



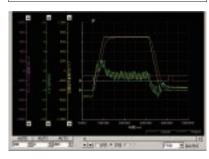
Tuning



Check Wiring



SERVOPACK internal data can be displayed in the monitor just like an oscilloscope.



Calculating Moment of Inertia and Measuring Vibration Frequency



Alarm Display and Alarm Diagnostic Function



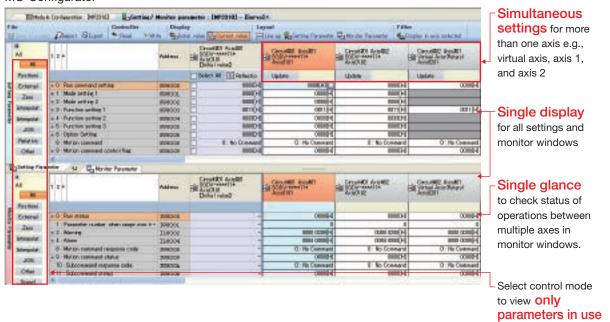
### A one-stop solution for strengthening the integration environment and system design!

The MPE720 Ver. 7 engineering tool integrates the engineering environments for servo, inverter, and I/O devices into a single software package. This enables all-in-one engineering from setup to maintenance of Setup and drive units connected to an MP3000 series machine controller via the adjustments MECHATROLINK network. [Catalog No. KAEPC88076100] Engineering Tool **MPE720 Ver. 7 ALL-IN-ONE ENGINEERING** SigmaWin+ IoWin Programming AC servo drive engineering tool Inverter support tool I/O unit setting tool SigmaWin+ **DriveWizard Plus loWin** Maintenance and control

### Execution of parameter settings and monitoring enabled for multiple axes simultaneously

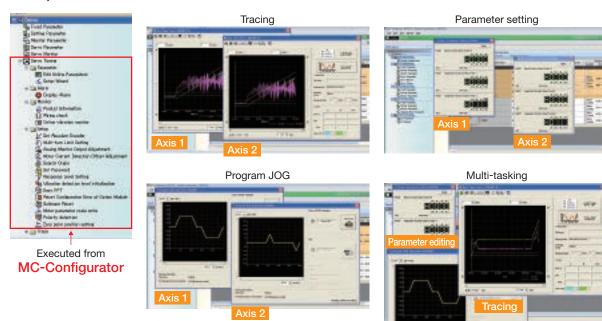
The parameter settings and monitor windows of the drive units can be executed for a multiple number of axes simultaneously. Establishing the settings for the entire system is a simple job, and comparing the monitors on an axis-by-axis basis is also easy.

### MC-Configurator



### Adjustment work supported by a variety of adjustment functions

A wide variety of functions required for servo adjustments are provided, and these functions support the adjustment work.



### Efficiency improved by choosing the programming method that works best for the user

### Ladder programming

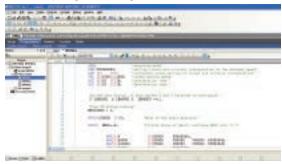


- · A new user interface (UI) enables operations to be undertaken easily by anybody.
- · All types of control including position, speed, torque, and phase control are supported.
- · Arithmetic expressions in the ladders have been made even simpler by boosting the EXPRESSION instructions.

### This system is recommended for:

· Users who are using a PLC

### Motion programming



- · Positioning and interpolation instructions can be described using single instructions.
- · Programs can be very easily edited using expressions in a text format.
- New variable programming can provide PC-like programming.

### This system is recommended for:

· Users of PC-based devices and in-house fabricated boards (C language, BASIC language)

### Advantages of MECHATROLINK

MECHATROLINK was created based on technology developed by Yaskawa as a specialized network for motion control, and has been made available as an open field network.

Yaskawa helped found the MECHATROLINK Members Association (MMA) in 2003 as a member of the MMA Board Committee. Yaskawa has continued to work with the MMA to promote the use of MECHATROLINK.

MECHATROLINK acquired certification for IEC61784 and IEC61158 international standards from the IEC in August 2014.

IEC61784 and IEC61158 are international standards for specifying industrial computer network protocols.

It is expected that the adoption of MECHATROLINK as a standard by the IEC will help promote the worldwide use of MECHATROLINK and contributing greatly to improving the productivity of manufacturing sites around the world.

### MECHATROLINK Members Association (MMA)

MMA was established to promote the MECHATROLINK open field network for high-speed motion. The MMA consists of members that develop compatible products and the users of those products. There are five membership ranks: Board Members, Executive Members, Regular Members, User Members, and Registered Members.

There are eight Board Member companies in the MMA: M-System Co., Ltd., Oriental Motor Co., Ltd., Keyence Corporation, Schneider Electric Japan Holdings Ltd., Yaskawa Electric Corporation, Yaskawa Information Systems Corporation, Yokogawa Electric Corporation, and Texas Instruments Inc. These companies are responsible for the management of the MMA.

The MMA provides global support to its members with branch offices in Germany, the U.S., South Korea, China, Taiwan, India, and ASEAN. These offices offer technical support and conduct promotional activities tailored to the local conditions in each country.

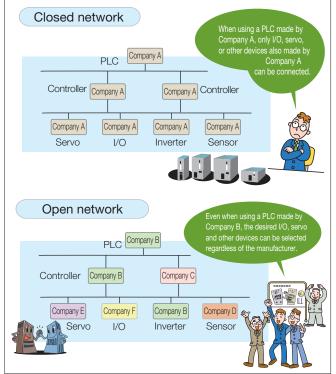
MECHATROLINK Members Association website: http://www.mechatrolink.org

# **Den** Wide variety of available products

The most important point in freely constructing systems is a wide variety of available products.

MECHATROLINK adopts open and standardized communication specifications to enable connections between equipment made by different device manufacturers. Customers can arbitrarily select products made by different manufacturers based on criteria such as design, functionality, and cost. By ensuring that their products comply with applicable standards, device manufacturers can also access a larger market.

### Difference between an open and closed network



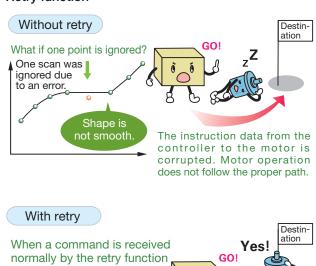
# Reliable Guaranteed high communications performance

The most important point in communications is to reliably transmit accurate data.

When transmitting digital data in particular, an error in transmitting even 1 bit can corrupt the entire communications data. MECHATROLINK has a retry function that automatically detects command and response communication errors and retransmits the data. Retry is performed within the same transmission cycle, so there is no loss of synchronicity.

New industrial connectors and cables are also used, and antivibration and noise measures have been enhanced.

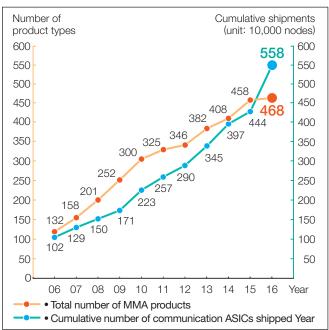
### **Retry function**



### **Expanding MECHATROLINK family**



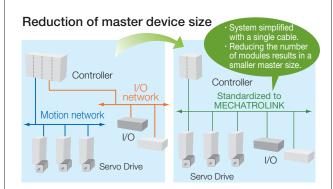
### Increasing numbers of product types and nodes

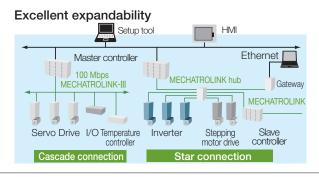


Simple Low cost, easy maintenance, and expandability

A key point for constructing a low-cost system is to reduce the wiring.

MECHATROLINK can connect a master device with each slave device using a single cable. MECHATROLINK also enables a reduction in the number of master device modules and cables by integrating the motion control network and I/O network into a single wiring system. This reduces costs and facilities maintenance and system expansion.





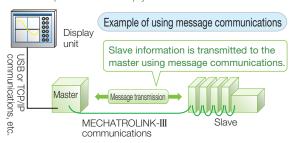
Simultaneous control of multiple axes and high-capacity message communications

Faster network speeds are required to enhance productivity and increase system scales.

MECHATROLINK-III has a communication speed of 100 Mbps and a transmission cycle of 31.25  $\mu$ s, which is the best in the industry. This shortens the cyclic communications cycle and enables communications with more slaves per unit time to achieve simultaneous control of up to 62 axes. High-capacity message communication is also possible.

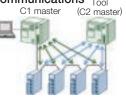
### Promotion of message communication

The MMA aims to popularize the use of message communications to improve the ease of maintenance. To achieve this, the MMA actively encourages members to use various compatible product setup tools that comply with MECHATROLINK-III.



### MECHATROLINK-III message communications Tool

The C1 master supports message communications. The C2 master can also control the parameters, alarm history, and other data of each slave as a tool master.



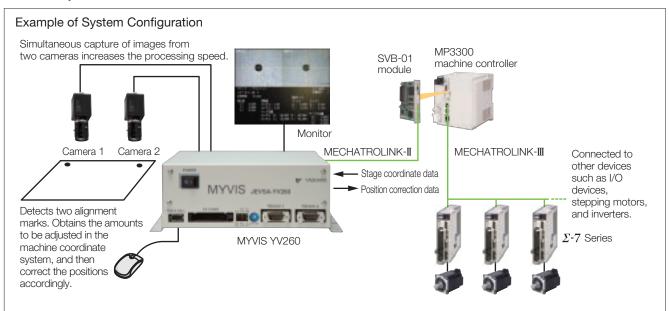
### MYVIS YV260 Network Machine Vision System

In this example, the MYVIS YV260 is connected to the open motion network MECHATROLINK.

With MECHATROLINK communications, the MYVIS can receive data on the current position of the motor's axes in succession. Using this data, the necessary adjustments are determined for high-accuracy calibration of the machine coordinate system.

### Features

- 1 Compatible with high-resolution camera
  - · Digital camera (300,000 to 5,000,000 pixels)
- · Analog camera (300,000 to 1,250,000 pixels)
- 2 High-speed preprocessing of image quality improvement by hardware
- 3 Possible to simultaneously capture images from four cameras
- 4 Compatible with color camera
- 5 Compatible with MECHATROLINK-II and 100-Mbps Ethernet communications



ltem			For Analog Cameras	For Camera Link				
Model			JEVSA-YV260□1-E	JEVSA-YV260□2-E				
Image Processing			Gray scale pattern matching, binary image analysis etc.					
	Application Program		512 Kbytes (flash memory)					
	Backup Memory		256 Kbytes CMOS (for saving parameters)					
Memory	Template	Storage Memory	CF cards (2 Gbytes max.)					
	Image	Frame Memory	$4096 \times 4096 \times 8$ bits $\times 4$ images (Can be use	ed for $640 \times 480 \times 8$ bits $\times$ 192 images)				
	Memory	Template Memory	16 Mbytes					
	Camera Interface		New EIAJ 12-pin connector $\times$ 4 VGA (640 $\times$ 480) to SGXA (1280 $\times$ 960) Four B&W, 8-bit A/D-converter circuits	Camera Link (MDR 26 pins) $\times$ 4 VGA (640 $\times$ 480) to QSXGA (2440 $\times$ 2048), Base Configuration, PoCL-compatible				
Image	Camera Power Supply		Single camera: 12 V, 400 mA, Total: 1.2 A					
Input	Camera Sync Mode		Internal/external sync	Internal sync				
	Random Shutter Supported		Sync-nonreset, sync-reset, single VD or V reset					
	Simultaneous Image Capture		Four cameras					
	Input Image Conversion		Gray level conversion (LUT), mirror mode					
	Monitor Output		VGA, XGA (color), 15-pin D-sub					
Monitor	Image Dis	splay	A full-screen or a partial-screen for one camera, simultaneous screen reduction for two or four cameras, gray level conversion (binary image display supported)					
	Field Network		MECHATROLINK-I/II					
	LAN (Ethe	ernet)	10BASE-T/100BASE-TX					
	General-purpose Serial		RS-232C × 2 channels (115.2 kbps)					
I/F	Parallel I/O		16 general-purpose outputs (4 of these are also used for stroboscope) +2 outputs exclusive for alarms (24 VDC, photocoupler isolation) 16 general-purpose inputs (4 of these are also used for trigger) +3 inputs exclusive for mode switchings +1 input exclusive for trigger (24 VDC, photocoupler isolation)					
	Track Ball		USB mouse					
Power Supply			100/200 VAC, 24 VDC, 30 W					

M2M Communication Adapter

### Yaskawa Information Systems Corporation

The M2M communication adapter offers one-stop solution for remote control and monitoring as well as management of devices via mobile communications networks. The environment required for remote monitoring is offered as a set.

### MMLink-3G, Global Communication Adapter

This communications device for the Internet of things (IoT) delivers seamless remote monitoring and control via 2G and 3G networks.



- 1 Supports connection to 2G and 3G networks.
- 2 Data transfer possible over wide areas
- 3 Equipped with GPS navigation system
- 4 Supports various communications protocols
- 5 Easy initial settings



LTE gateway with multi-carrier support



- 1 Supports multi-carrier LTE (Docomo and au networks).
- 2 Equipped with IPSec, PPTP, L2TP, GRE, and OpenVPN as standard
- 3 A compact size that can be easily incorporated into equipment (93×90×27 (mm)).
- 4 Redundancy through dual SIM cards (failover)
- 5 Additional applications can be built and customized (development support is available).



A carrier-independent SIM-free industrial USB communications adapter



- 1 Select a domestic or international carrier or an MVNO according to the application.
- 2 A compact and lightweight device compatible with various installation environments.
- 3 Equipped with GPS positioning function
- 4 Easy to install with USB cable interface
- 5 Available in two models: Standard version and advanced version



M2M Cloud Service

### MMCloud, Cloud Service for Product Life Cycle Management Support

This is a cloud service that collects and manages the operational information of products and related information in order to support the management of the life cycle of products.





- 1 Supports management of product life cycle
  - Product information that is managed separately can be consolidated and used for work in various processes, including planning, development, sales, inspection, and maintenance.
- 2 Enables ideal monitoring of equipment located in different locations around the world Global-scale monitoring of equipment is made possible by using internet connections and wireless communication networks for mobile phones. User environment is also globalized. Local times of different countries where equipment are used can be displayed and languages can be selected on the screen.
- 3 Displays collected information in real time
  Collected data, status of customer equipment, information collected via sensors, and GPS information is
  displayed in graphs and maps so that equipment conditions can be checked in real time. This service can be
  used to monitor operation status and mobile equipment.
- 4 Can start with a small-scale operation
  Customers can first use this service with a small investment and a short leadtime by using the standard cloud service. The monitoring scale can be increased in line with the expansion of the customer's business operations.

### MMPredict, Failure Prediction Service

MMPredict is a service that uses artificial intelligence techniques to predict failures of equipment using accumulated sensor data.



- 1 Failures can be predicted to a high degree of accuracy with our proprietary techniques.
- 2 Failure points can be estimated from information provided by sensors.

Website http://www.ysknet.co.jp/



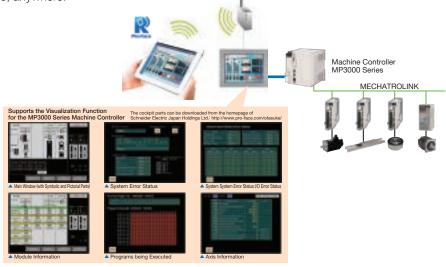


Programmable Display

### Schneider Electric Japan Holdings Ltd.

### Pro-face GP4000 Series

The GP4000 series display features a touch screen that can be connected directly, without using any application programs, to control devices, such as controllers, servo drives, and AC drives. Current conditions of these devices is displayed on the screen so that they can be set up, adjusted, and maintained on site. Users can easily check operational status, edit registers, identify errors, and update or backup application programs without using a computer. The GP4000 series supports Proface Remote HMI, the remote monitoring software for mobile devices. This allows users to view product information on tablets and smartphones anytime, anywhere.

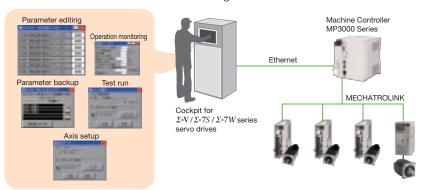


### Engineering Support Function

Program Transfer with an External Memory Unit!



Adjustment and Maintenance of Servo Drives and Inverters Right on the Touch Panel!



Website http://www.proface.co.jp/product/hmi/gp4000.html

IP Core

### Tokyo Electron Device Limited

### MECHATROLINK-III Master/Slave IP Core

Model: Master: TIP-ML3MST-PROJ···Supports Xilinx, Inc. Spartan-6 LX/LXT FPGAs and Zynq-7000 SoCs. Slave: TIP-ML3SLV-PROJ···Supports Xilinx, Inc. Spartan-6 LX/LXT FPGAs (single slave and multi-slave functions).

This original IP core for FPGAs manufactured by Xilinx, Inc. significantly reduces the number of components on a board.

This reduces development costs and time required for development can be significantly reduced.

- ·Supports MECHATROLINK-III master and slave functions.
- Delivers a high-speed host interface synchronized with a 66 MHz clock (max.).
- · Enables flexible system configuration by using FPGA fabrics.

Website http://ppg.teldevice.co.jp

I/O Module

M-System Co., Ltd.

### MECHATROLINK-I- and -II-compliant Remote I/O

Model: R7ML series, R7K4FML, R7K4DML, R7G4HML

- · Can handle 16 to 32 discrete I/O signals, 4 analog input, and 2 analog output signals.
- · Analog and discrete signals can be mixed.
- · 3M screw terminals (2-piece configuration) are used for power supply and I/O terminal blocks. Saves space because relay terminal is not required.
- · R7K4DML-B used with e-CON connectors for I/O connection is also available.



R7ML Base Module

### MECHATROLINK-III-compliant Remote I/O

Model: R7G4FML3, R7G4HML3, R7F4HML3, R7K4FML3, R7K4JML3

- · Can handle 16 to 64 discrete I/O signals and 4 analog output signals (max.).
- · Equipped with discrete I/O, DC input and output, temperature input, and rotary encoder input.
- · High-speed A/D conversion unit (conversion speed:  $200 \,\mu$ s) and Strain Gauge Input Module are available.
- · 3M screw terminals (2-piece configuration) are used for power supply and I/O terminal blocks. Saves space because relay terminal is not required.
- · R7K4JML3-E used with spring clamp connectors for I/O connection and R7F4HML3-D used with MIL connectors are also available.



R7G4FMI 3-6

### HLS (High-speed Link System) Master Module

Model: MPHLS-01

- · Master module that can be used with MP2200, MP2300, and MP3300 series machine controllers. Note: When using this module with a MP3200 machine controller, attach a MP2000 base unit (optional) to the machine controller first and install this module in the base unit.
- · Wiring for discrete I/Os and analog I/Os can be reduced with M-System's rich product lineup of remote I/O modules (R7HL and R7F4DH series) that can be connected to the HLS master module.

Website http://www.m-system.co.jp/



ALGO System Co., Ltd.

### A-net/A-Link Master Unit Module

Model: MPANL00-0

This A-net/A-Link master unit module can be directly attached to the MP3000 series Controller. The resulting system needs less wiring and conforms to SEMI E54.17.

Features

- 1 Two H8S units by Renesas Technology Corp. can be added maximum.
- 2 Max. 4032 points can be scanned in 0.95 ms (at 12 Mbps). Note: The case using two A-Link channels (1 channel: 2016 points/system, 0.95 ms at 12 Mbps).
- 3 Shared memory of 512 Bytes (response speed: 2.36 ms) with A-net.
- 4 Self-diagnostic function.

Website http://www.algosystem.co.jp/



MPANL00-0

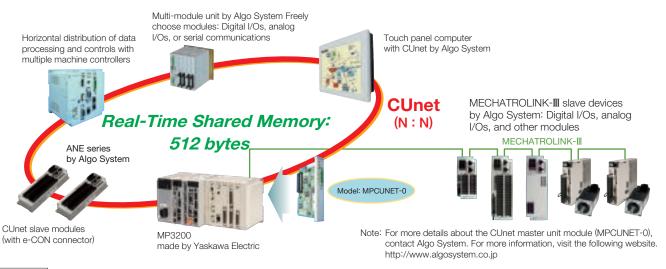
MP3200

### **CUnet Master Unit Module**

Model: MPCUNET-0

The master module for CUnet communications that can be directly connected to the MP3000 Series Controllers.

- 1 Pre-mounted H8S unit (By Renesas Electronics).
- 2 Large shared memory of 512 bytes (Response speed: 2.36 ms).
- 3 Distributed control in real time.



Website http://www.algosystem.co.jp/

### WAGO Company of Japan, Ltd.

### WAGO-I/O-SYSTEM 750 Series

Model No. 750-346: Compatible with the 260IF-01 DeviceNet Communication Module Model No. 750-352: Compatible with the 263IF-01 EtherNet/IP Communication Module and 218-01/-02 Ethernet Communication Module.

WAGO-I/O-SYSTEM 750 series I/Os are module-type remote I/Os. Nodes can be constructed by combining a communication unit (bus coupler) with a function module of your choice. Various communication units that are compatible with a wide range of open fieldbus are available. Yaskawa Electric's MP series machine controllers can be connected via DeviceNet, Ethernet/IP, and Modbus-TCP Ethernet networks. Instruction manuals contain information on easy ways to connect the machine controller.

Function modules are available for a wide range of I/O signal types: digital I/O (2 to 16 channels), analog I/O ( $\pm$ 10 V, 0 to 20 mA, thermocouples), serial communications, counter I/O, etc.

Website http://www.wago.co.jp/io



756-346 For DeviceNet



750-352 For EtherNet/IP MODBUS



Example of Node Configuration (Bus coupler + Module)

Module for MP3300, and I/O Terminal

### **Anywire Corporation**

### AnyWire DB Master Module

Model: AFMP-01

The AnyWire DB master module can be connected directly to the machine controllers in the MP3000 series. This module is equipped with the master functions of the AnyWire DB A40 series and is compatible with a variety of I/O terminals in the same series.



System Configuration: Full Triple Mode Transmission

Bit-Bus slave

Word-Bus slave

UNI-WIRE slave

Note: For more details on the AFMP-01 module, contact the Anywire Corporation or visit its web site, http://www.anywire.jp.

Features

- 1 The AnyWire system saves space and reduce costs because fewer cables are reduced and low-cost, general-purpose cables can be used. Time required for wiring is also reduced.
- 2 Highly efficient transmission is achieved with the Dual-Bus system. Analog inputs/outputs (128 words max) can be connected without adversely affecting the digital input/output signal transmission (512 points max).
- 3 General-purpose robot cables, cableveyor, slip rings can be used with the product. This is an ideal module to reduce wiring at drive sections.

### CC-Link interface board

Models: AFMP-02-C, AFMP-02-CA

These slave interface boards connect the machine controllers in the MP3000 series to the CC-Link master. One CC-Link master can be connected to a maximum of 16 machine controllers in the MP3000 series through the CC-Link when the PLC in the Q series (manufactured by Mitsubishi Electric Corporation) is used as a master station. Costs can be reduced and space saved by using the AFMP-02-CA board equipped with wire-saving DB ports.



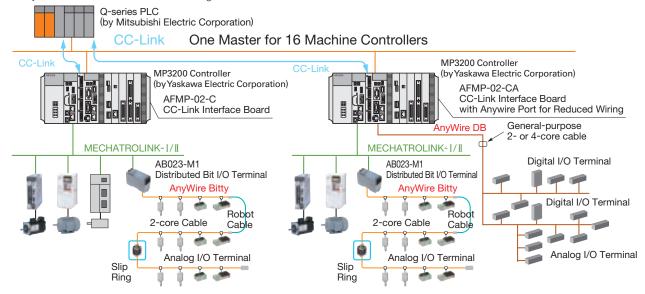
- 1 A single CC-Link master station, a PLC from the Q series by Mitsubishi Electric Corporation, can be connected to 16 MP3200 controller with the CC-Link.
- 2 The setup time can be greatly reduced by the self-configuration function of the MP3200.
- 3 Anywire port for reduced wiring saves costs and space.



AFMP-02-CA

### System Configurations

If a Q-series PLC made by Mitsubishi Electric Corporation is connected to a Machine Controller through CC-Link, only one CC-Link master allows you to connect to 16 controllers including MP3200 Controller.



### MECHATROLINK bit-type distributed I/O terminal

Model: AB023-M1

The MECHATROLINK bit-type distributed I/O terminal reduces the wiring required for drive systems that use MECHATROLINK-I and -II. The introduction of this I/O terminal into a MECHATROLINK open-network system significantly reduces total costs and increases system reliability because the MECHATROINK I/O terminal can be used with any transmission media, such as robot cables and slip rings.

The AnyWire Bitty series for I/O terminals from AnyWire can be connected to this distributed I/O terminal to increase the flexibility in transmissions by supporting the connection of cables for signals from sensors and actuators in the system. It is possible to increase the number of I/O points to 432 by connecting I/Os with a bus that reduces the amount of wiring required.





### RKC Instrument Inc.

### Module-type Digital Temperature Controller

Model: SRZ Communications converter module COM-MY

- ·Temperature control module Z-TIO
- ·Digital I/O module Z-DIO
- · Easily construct a multi-channel temperature control system by connecting the
- MECHATROLINK-compliant communications converter module to the temperature control modules.
- · A single temperature control module can control temperatures of four points or two points. Also, 16 modules can be connected for temperature control of maximum 64 points.
- · Digital I/O modules to output temperature alarms and to switch operation modes by using contact signals can also be connected.

Website http://www.rkcinst.com



### **Azbil Corporation**

### K1G Series High-accuracy Position Sensors

Model: MECHATROLINK-III-compatible K1G-C04M

Performance and functions that far exceed conventional norms, allowing you to make the measurements you want.

Features

- 1 See what you previously couldn't Minute variations not visible with conventional sensors can now be reliably detected.
- 2 Easily mounts anywhere Compact dimensions are achieved by slim sensor head design.
- 3 Less wasted time Comes with a full range of functions to help cut job time for design, installation, and maintenance.
  - Support for MECHATROLINK-III also opens up a host of new applications and advantages.

Website http://www.azbil.com

### Stepping Motor Drive

### Oriental Motor Co., Ltd.

### **Network Converter for Controlled Motors**

Model: NETC01-M2 for MECHATROLINK-II NETC01-M3 for MECHATROLINK-III

- ·These network converters convert the MECHATROLINK communication protocol to Oriental Motor's original RS-485 communication protocol. Oriental Motor's products that support the RS-485 protocol (up to 16 axes) can be controlled in MECHATROLINK communications.
- ·Only a single MECHATROLINK communication cable is required for wiring, reducing the number of wires and saving space.
- ·Parameters can be set by using an OPX-2A module or MEXEO2 software (both sold separately.)

### AZ Series Multi-axis Driver for Motors Equipped with Mechanical Absolute Encoders Model: AZD ☐ A-KM3

- · This  $\alpha$  STEP AZ series driver, for use with motors equipped with battery-free mechanical absolute encoders, now supports MECHATROLINK-III communications.
- · Because an external sensor is not required, you can save on wiring and reduce maintenance.
- · The motor will not miss steps, even under rapid load fluctuations or rapid acceleration, and highly responsive positioning is possible without tuning and hunting.
- · AZ series DC power supply input motors and actuators can be connected to this multi-axis driver for two to four axes.

Website http://www.orientalmotor.com







Endo Kogyo Co., Ltd.

### Slip ring for communications and control

Model: SRP-MLII-3

The SRP-ML slip ring enables communications with and control of drive units and systems that include rotating devices.

- ·Compact and highly durable structure
- · Improved reliability with the new brush system that enables uninterrupted communications
- ·Connected directly by using MECHATROLINK-II cables

Website http://www.endo-kogyo.co.jp/japanese/sr/con-index.html

Slip Ring

Kyoei Electric Co., Ltd.

### Slip ring system for MECHATROLINK-II communications

Model: SRC120-MLII

This highly functional slip ring transmits data through MECHATROLINK communications from a fixed device to a rotating device.

- ·Can be packaged with a power device, such as power supply for a motor.
- · Complies with RoHS Directive.

Website http://www.kyoeidenki.jp



Slip Ring

**NSD** Corporation

### Slip-ring system for MECHATROLINK-II communications

Model: 3TE Ø 17-7P

This slip-ring system achieves your intended measurements with unprecedented performance and functionality.

Features

- 1 A small (43 mm dia. × 87 mm), lightweight slip-ring that supports MECHATROLINK-II communications.
- 2 Can be used without maintenance for up to 50 million rotations at a maximum speed of 700 min<sup>-1</sup>.
- 3 Can simultaneously supply power (200/220 VAC 3A) and transmit data. Power can also be supplied to a servo amplifier by combining this slip-ring with our slip-ring for high currents.



### Slip-ring system for MECHATROLINK-III communications

Model:  $3TE\phi 17-5P-MIII$ 

This slip-ring system achieves your intended measurements with unprecedented performance and functionality.



- 1 A small (43 mm dia.×107 mm), lightweight slip-ring that supports MECHATROLINK-III communications.
- 2 Can be used without maintenance for up to 50 million rotations at a maximum speed of 700 min-1.
- 3 Power can also be supplied to a servo amplifier by combining this slip-ring with our slip-ring for high currents.



Website http://www.nsdcorp.com



### ◆Incremental Linear Encoders

Output Signal	Manufacturer	Linear Encoder Type	Model			Linear	Recolution	Maximum	Support	Application	
			Scale	Sensor Head	Interpolator (Serial Converter Unit)	Encoder Pitch $\mu \mathrm{m}$	nm	Speed*4 m/s	Polarity Sensor Input		to Fully-Closed Loop Control
	Heidenhain Corporation	Exposed	LIDA48□		JZDP-H003/-H006*6	20	78.1	5	✓	✓	<b>✓</b>
4.14					JZDP-J003/-J006*6		4.9	2	✓	✓	*9
1 Vp-p			LIF48□		JZDP-H003/-H006*6	4	1	✓	~	✓	
Analog Voltage*1					JZDP-J003/-J006*6		1.0	0.4	✓	*9	*9
Voltage	Renishaw plc*5	Exposed	RGS20	RGH22B	JZDP-H005/-H008*6	20	78.1	5	✓	✓	✓
					JZDP-J005/-J008*6		4.9	2	✓	✓	*9
	Magnescale Co., Ltd.	Exposed	SL7□0	PL101-RY*7		800	97.7 10	_	✓	✓	
				PL101	MJ620-T13*8	800	97.7	10	✓	✓	*9
Encoder for			SQ10	PQ10	MQ10-FLA	400 48	48.83	3	_	~	✓
Yaskawa's Serial					MQ10-GLA		40.00	3	✓	~	_
Interface*2 $(\Sigma$ -LINK)		Sealed	SR75LF		_	80	9.8	3.33	_	~	✓
			SR75-□□		_	80	78.1	3.33	_	✓	✓
			SR85-		_	80	9.8	3.33	_	✓	✓
			SR85-		_	80	78.1	3.33	_	✓	✓

### ◆Absolute Linear Encoder

Output Signal	Manufacturer	Linear Encoder Type	Model			Linear Encoder	Resolution	Maximum Speed*4	Support for Polarity	Application to	Application to
			Scale	Sensor Head	Interpolator (Serial Converter Unit)	Pitch* <sup>3</sup> μm	nm	m/s	Sensor Input		Fully-Closed Loop Control
		Sealed	SR77-□□		_	80	9.8	3.33	_	✓	✓
	Magnescale		SR77- DDDDDMF		_	80	78.1	3.33	_	✓	✓
	Co., Ltd.		SR87-		_	80	9.8	3.33	_	✓	✓
			SR87-□□	□□□ MF	_	80	78.1	3.33	_	✓	✓
	Mitutoyo Corporation	Exposed	ST781A		_	256	500	5	_	✓	✓
			ST782A		_	256	500	5	_	✓	✓
Encoder for			ST783A		_	51.2	100	5	-	✓	✓
Yaskawa's			ST784A		_	51.2	100	5	_	✓	✓
Serial			ST788A		_	51.2	100	5	_	✓	✓
Interface*2			ST789A*10		_	25.6	50	5	_	✓	✓
$(\Sigma$ -LINK)			ST1381		_	5.12	10	8	_	~	✓
			ST1382		_	0.512	1	3.6*11	_	✓	✓
	Heidenhain	Exposed	LIC4100	) series	EID0004)/*°	20.48	5	10	_	✓	✓
	Corporation	Sealed	LC115		EIB3391Y*8	40.96	10	3	_	✓	✓
	Renishaw plc	Exposed	EL36Y-□□050F□□□		_	12.8	50	100	_	✓	✓
			EL36Y-   100F		_	25.6	100	100	_	✓	✓
			EL36Y-□□500F□□□		_	128	500	100	_	✓	✓

- \*1. You must also use a Yaskawa Serial Converter Unit. The output signal will be multiplied by 8 bits (256 divisions) or 12 bits (4,096 divisions) in the Serial Converter Unit.
- \*2. The multiplier (number of divisions) depends on the Linear Encoder. Also, you must write the motor constant file to the Linear Encoder in advance.
- \*3. These are reference values for setting SERVOPACK parameters. Contact the manufacturer for actual linear encoder scale pitches.
- \*4. The maximum speeds given in the above table are the maximum applicable speeds of the encoders when combined with a Yaskawa SERVOPACK. The actual speed will be restricted by either the maximum speed of the Linear Servomotor or the maximum speed of the Linear Encoder (given above).
- \*5. If you use the origin signals with a Linear Encoder from Renishaw plc, the
- origin may sometimes be falsely detected. If that occurs, use the BID/DIR signal to output the origin signal only in one direction.
- \*6. Use this model number to purchase the Serial Converter Unit.
- \*7. Use this model number to purchase the Sensor Head with Interpolator.
- \*8. Use this model number to purchase the Interpolator.
- \*9. Contact your Yaskawa representative.
- \*10. Contact Mitutoyo Corporation for details on the Linear Encoders.
- $\pmb{*}$ 11. The speed is restricted for some SERVOPACKs.
- Note 1: Confirm detailed specifications, such as the tolerances, dimensions, and operating environment, with the manufacturer of the Encoder before you use it. 2:  $\Sigma$ -LINK is a registered trademark of YASKAWA ELECTRIC CORPORATION.

### Absolute Rotary Encoder

The following Absolute Rotary Encoders are for fully-closed control. Can not use it to control the motor.

Output Signal	Manufacturer	Rotary Encoder Type			Relay Device between Fully-Closed	Resolution	Maximum Speed*1
Output Signal			Scale	Sensor Head	Module and Rotary Encoder Type	Bits	min <sup>-1</sup>
Encoder for	Magnescale	Exposed	RU77-4096ADF*2		_	20	2000
Yaskawa's	Co., Ltd.		RU77-4096AFFT01*2		_	22	2000
Serial	Heidenhain Corporation	Sealed	RCN2 □ 10*2			26	3000
Interface*1 $(\Sigma$ -LINK)			RCN5 □ 10*2		EIB3391Y	28	800
			RCN8 □ 10*2			29	400

<sup>\*1.</sup> The maximum speeds given in the above table are the maximum applicable speeds of the encoders when combined with a Yaskawa SERVOPACK. The actual speed will be restricted by either the maximum speed of the Linear Servomotor or the maximum speed of the Linear Encoder (given above).

<sup>\*2.</sup> This is a single-turn absolute encoder.

Note 1: Confirm detailed specifications, such as the tolerances, dimensions, and operating environment, with the manufacturer of the Encoder before you use it. 2: Σ-LINK is a registered trademark of YASKAWA ELECTRIC CORPORATION.

### Product Information

### e-Mecha Site (http://www.e-mechatronics.com/en/)

To see details on Yaskawa's controllers, click Controllers on Yaskawa's Products and Technical Information website.

Users can download catalogs, manuals, and dimensional drawings from the e-mechatronics website.

Note: Users must register as members to use some of these documents.



MP3300 product information of e-Mecha site

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