YASKAWA

Machine Controller and AC Servo Drive Solutions Catalog



YASKAWA

Ever Forward, Ever Better 100 Years Together with Our Customers

Since its founding in 1915 as a manufacturer for motors, Yaskawa Electric has capitalized on its motor drive technology to provide continuing support for the key industries of the times, first for factory automation, and today, for mechatronics and robotics.

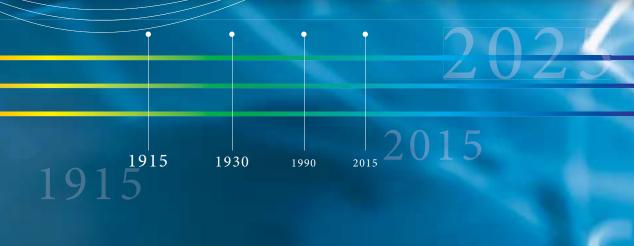
Today, Yaskawa is striving to make effective use of its technologies developed in the motion control, robotics, and system engineering sectors, and is also taking on the challenges of achieving the highly efficient utilization of natural energy and the creation of a society in which people and robots exist side-by-side.

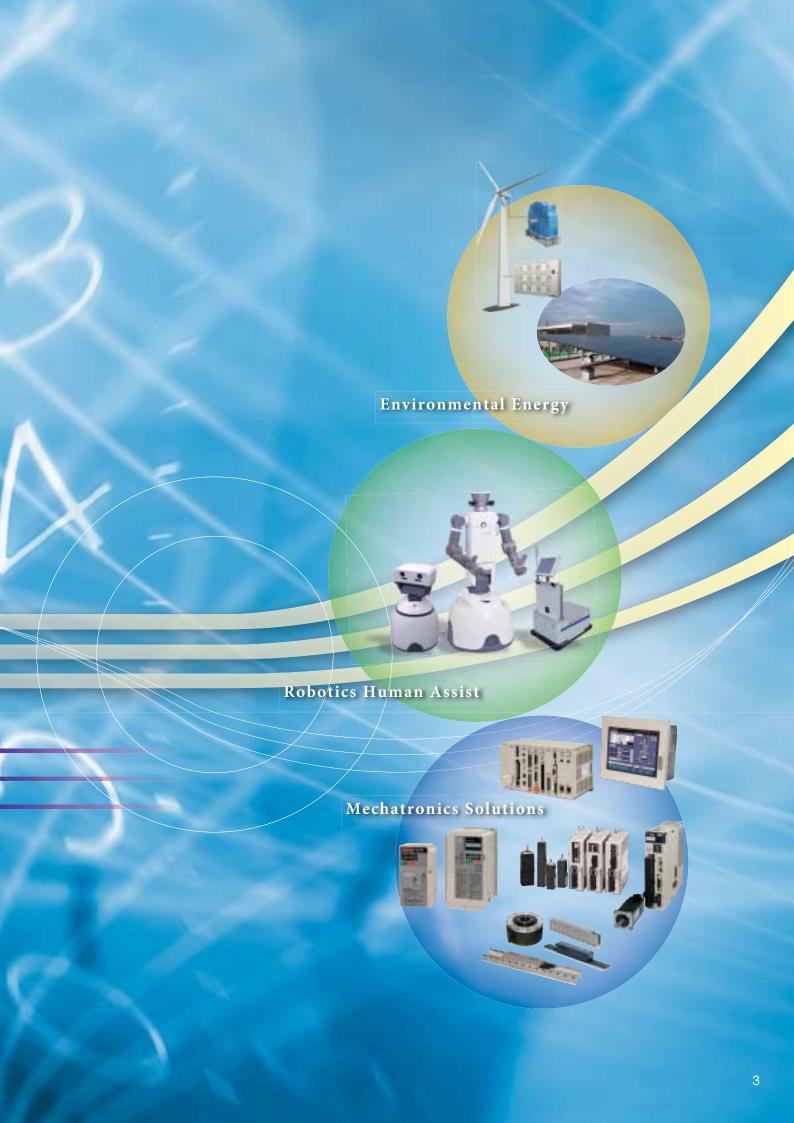
Throughout our extensive 100-year history, we have consistently sought to develop the world's leading technologies and applications that would best delight and be most useful to our customers. Yaskawa will continue to treasure the results, technologies, and reputation we have achieved thus far, and look ahead to create "e-motional solutions" for emerging global challenges.

Motion Control

Robotics

System Engineering

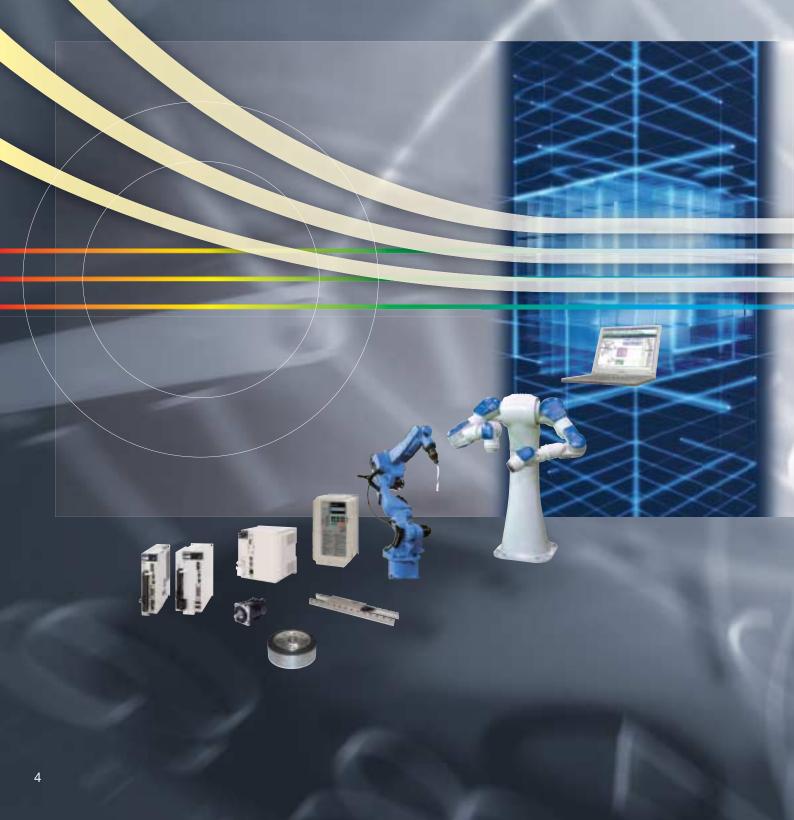




i - *Mechatronics*Changing Motion, Changing the World

Yaskawa is committed to developing innovative mechatronics products and offering new solutions to the world.

Yaskawa's technology and mechatronics products are used in a wide-variety of industrial sectors, systems, and machinery, and enable ultra-high-speed and ultra-precision control. In addition to industrial sectors, our motion technology has a nearly limitless range of applications, including familiar sectors such as lifestyles, medicine, and welfare. Changing the motions performed by motors creates new concepts and products that can change the world.



Motion Control Solution

APPLICATIONS



Semiconductor

Electronic parts

Liquid crystal

Machine tools



- Integrated
 Integration of components
 (System integration)
- i³-Mechatronics

Intelligent components

Innovated

Evolution of components through technical innovation

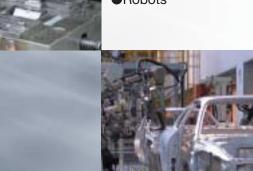
Yaskawa carries out Motion & Control Business activities based on the concept of i³-Mechatronics (Integrated, Intelligent, and Innovated).



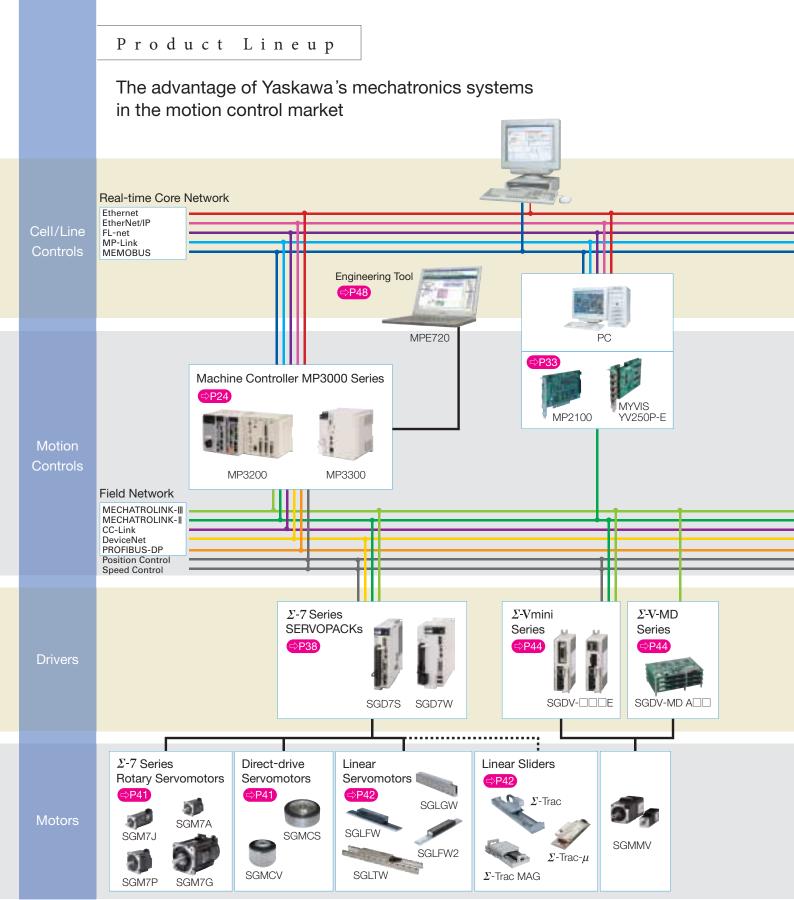
- ●Food/packing
- Transfer
- ●Textile



- Injection/moldingMaterial processing
 - Robots







Note: These linear sliders must be used with $\Sigma ext{-}V$ SERVOPACKs.

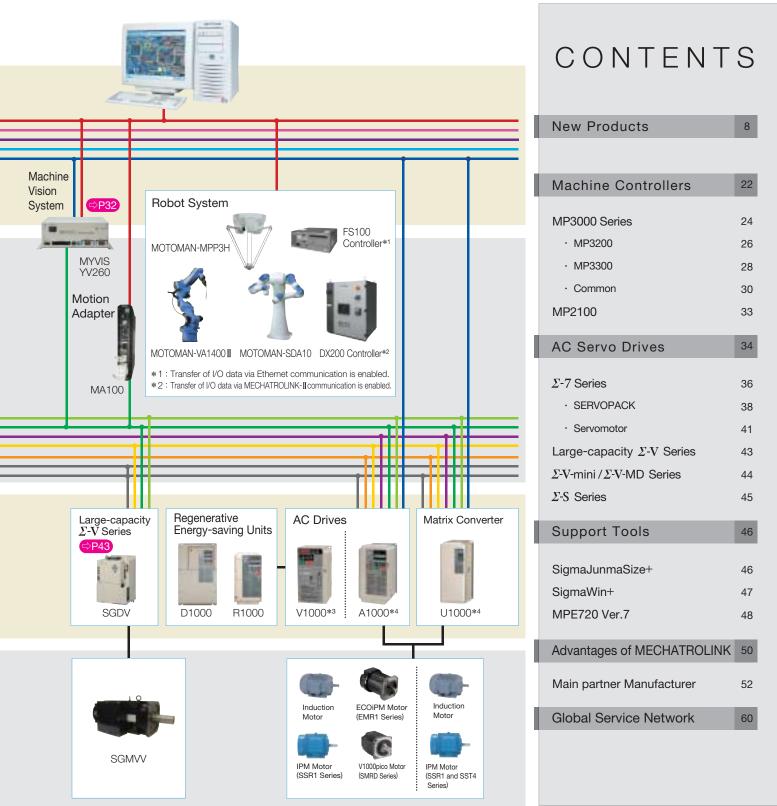
Support for industrial standard networks for open system architecture

We provide components compatible with the industrial standards required for mechanical system configurations including real-time core networks to connect controllers and field networks to connect equipment.

- Support for systems around the world through compliance with international standards. (Consult with Yaskawa for information on support for standard networks.)
- Supports multi-vendor system configurations.

Real-time core networks : Ethernet, MODBUS (MEMOBUS), FL-net, EtherNet / IP

Field networks : MECHATROLINK-III, MECHATROLINK-II (Consult with Yaskawa for information on support for other networks.)

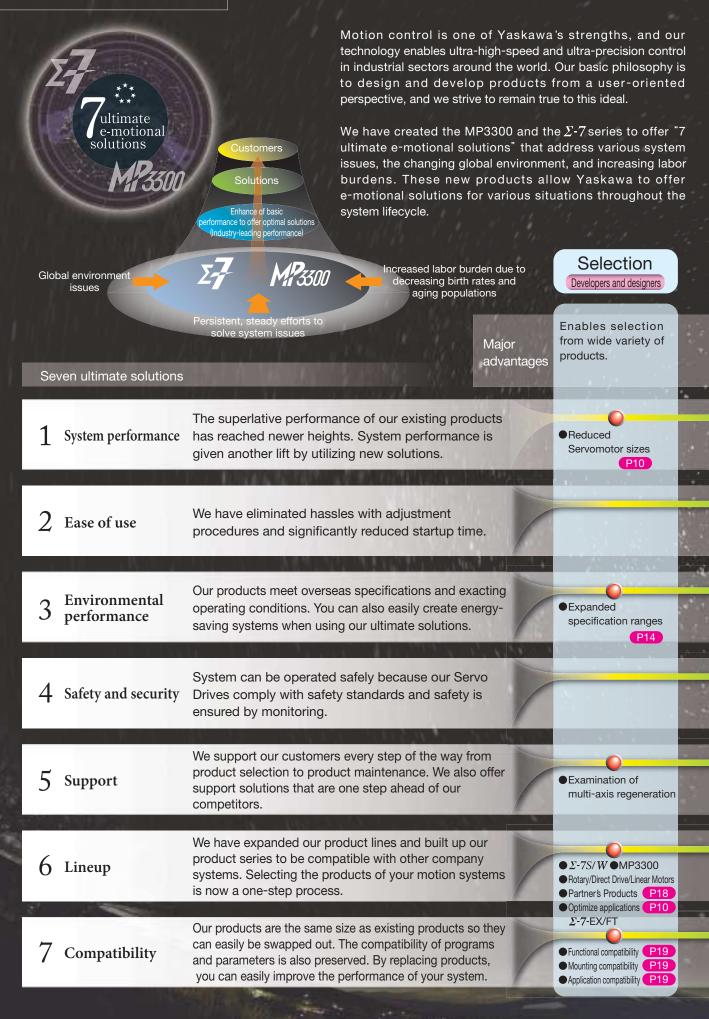


- *3: Compatible with CompoNet and CANopen*4: Compatible with CANopen and LONWORKS
- MECHATROLINK, the motion network from our motion control expertise

High-performance mechanical systems can be constructed, in combination with our mechatronics components.

- Servo systems and input/output equipment necessary for configuring mechanical systems can be easily connected, providing high-speed response.
- 1: n synchronous communication for high-precision motion control.
- Certification under the SEMI E54.19 standard has been acquired. (This standard covers the sensor and actuator networks of semiconductor production systems.)
- Communication specifications MECHATROLINK-II: Transmission speed: 10 Mbps; communication cycle: 250 µs and higher; transmission distance: 50 m max.

 MECHATROLINK-III: Transmission speed: 100 Mbps, Communication cycle: 125 µs and higher; transmission distance: 75 m between stations





| Design Developers and designers | Trial production Developers and designers | Production Manufacturers | Operation Operators | Maintenance Maintenance staff |
|---|--|---|---|--|
| Enhance performance and preventive safety measures to increase safety and security. | Avoid wasted time with stable and vibration-free operation without tuning. | Ship products with specified parameters to facilitate assembly. | Monitor temperatures directly using built-in temperature sensors to increase safety and security. | Easily collect and manage product data to enhance service. |
| Industry-leading P10 performance Optimal functions for each application P10 | ●Vibration suppression P10 | | | |
| ●Self-configuration P12 | Multi-axis tuning P12 Tuning-less P12 Integrated tracing | | | ●Traceability P17 |
| | | | | |
| ●List of specifications | | | ●Energy-saving functions P14 ●2-axis SERVOPACKs P14 | |
| | | | | |
| Safety functionsSupports SIL3specification requirements | | | ● Momentary power interruptions ● Temperature protection P15 | |
| ● Downloading of CAD data ● Self-configuration P12 | | Build-To-Order P16 service | Visual identification of operating statuses P14 (Monitoring by controller) | ● Traceability P17 ● Data logging ● Lifespan diagnostics P17 |
| | | | | |
| | | | | |

The superlative performance of our existing products has reached newer heights. System performance is given another lift by utilizing new solutions.

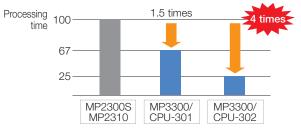
MP3300

- ★ Operates 1.5 times faster
- ★ 64-bit data types (double-precision real numbers, quadruple-length integers) supported

Fastest in the

★ MECHATROLINK- III provided as a standard feature

Improved CPU performance*



*: Ladder operation speed where the scan time of the MP2300S/MP2310=100

Double-precision real-number, 64-bit integer data for higher precision



With double-precision real-number, 64-bit integer data, rounding errors during arithmetic calculations are reduced, and control at higher levels of precision can be achieved.

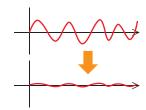


- ★ 3.1 kHz response frequency
- ★ FT specifications to optimize applications (to be released)
- ★ Improved vibration suppression



- ★ 2-axis SERVOPACKs (200 W x 2 axes to 1 kW x 2 axes)
- ★ 3.1 kHz response frequency
- ★ Improved vibration suppression

Ripple compensation



 Σ -7 SERVOPACKs can reduce speed ripples caused by motor cogging, even for machines for which speed loop gains cannot be set high. This ensures smooth operation.

Enhanced vibration suppression function

Suppresses high-frequency vibrations of 500 Hz or higher.

- ⇒ Number of filters increased from 2 to 5.
- Anti-resonance control

Suppresses vibrations at frequencies ranging from several hundred Hz to 1 kHz.

- ⇒ Vibrations can now be suppressed at multiple frequencies in comparison with one frequency in earlier models.
- Vibration suppression

Suppresses vibrations at low frequencies (30 Hz and lower).

⇒ Vibrations can now be suppressed at two different frequencies in comparison with one frequency in earlier models.

These functions can be adjusted automatically using the autotuning function.

Σ -7 servomotors

- ★ Compact dimensions (approx. 80% smaller than our earlier models)
- ★ High-resolution 24-bit encoder incorporated (16,777,216 pulses/rev)
- ★ Maximum torque: 350% (small capacity)

Smallest in

Highest in the industry

Compact dimensions

Models: SGM7J, SGM7A □40 mm (50/100/150 W)



Approx. 80% smaller than earlier models.

High-resolution, 24-bit encoder

Encoder resolution comparison

 Σ -Vseries 20 bits = 1 million pulses/rev (approx.

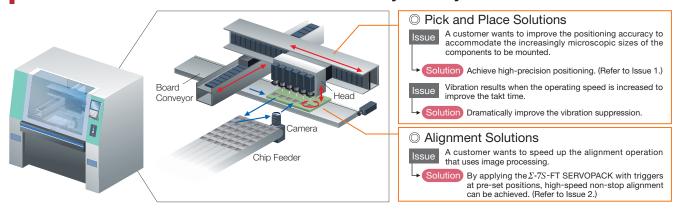
 Σ -7series 16 million pulses/rev (approx.)

16 times higher!

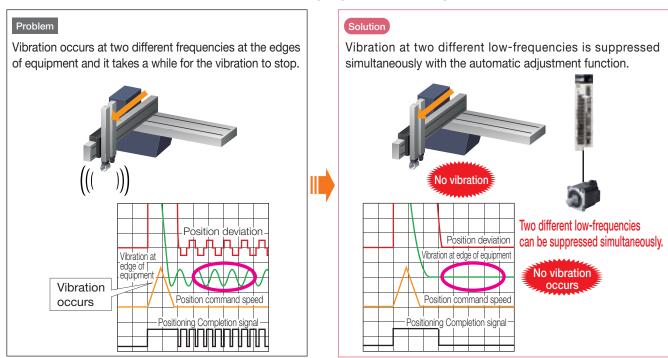
Solution for 50-W or greater models



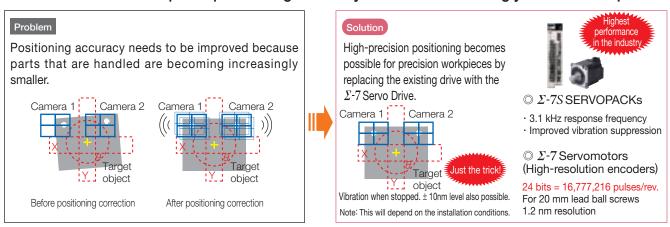
The superlative performance of our products and the broad spectrum of their functions will resolve whatever issues you may have.



Issue 1 We want to increase productivity by suppressing vibration of equipment.



Issue 2 We want to improve positioning accuracy to handle increasingly smaller workpieces.



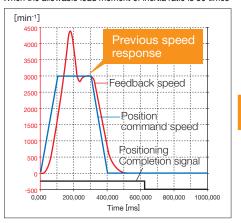


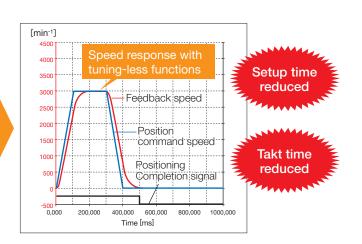
No need to adjust servo gains Σ -7

With Yaskawa's original tuning-less function, systems can run without vibration for a load with 30 times (max.) of the load moment of inertia. Systems remain stable even with load changes during operation.

| | ∠ - V Series | ∠ - / Series |
|--|------------------------------------|---------------------------------|
| Allowable load moment of inertia ratio | 30 times (max.) | 30 times (max.) |
| Max. control gain | Speed loop gain 40 Hz (approx.) | Speed loop gain 70 Hz (approx.) |

When the allowable load moment of inertia ratio is 30 times:





Automatic setup using the self-configuration function



The self-configuration function automatically recognizes the configuration of all the MP3300 optional units and modules, as well as all slave devices (servo units and I/O devices) connected to the MECHATROLINK motion network. This function eliminates the need for definition input work, and delivers vastly shortened startup times. The self-configuration function generates the definition files listed below.

· Module configuration definition

which dramatically reduces the setup time.

- · I/O register assignments
- · Communication parameters for Communication Module
- · Servo Drives connected to MECHATROLINK (servo parameters and user definitions)
- · I/O devices connected to MECHATROLINK (number of input and output points)

Using the DIP Switch

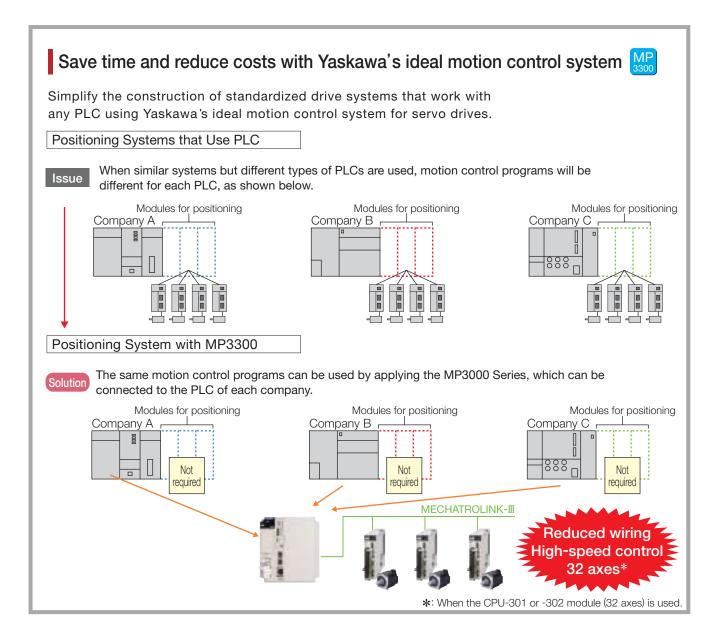


● Using the MPE720 support tool



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Procedure ① Select a PLC product. ② Enter the IP address of the PLC. ③ Enter the port number of the PLC. ④ Establish the connection by clicking the OK Button. Procedure ① Select a PLC product. ② Enter the IP address of the PLC. ④ Establish the connection by clicking the OK Button.

Satisfies specifications for use overseas and in harsh operating conditions

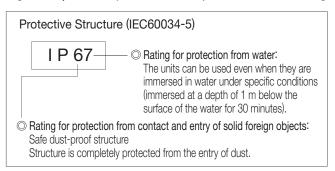
- · 240 VAC supply voltage also supported
- · High-altitude use increased to 2,000 meters above sea level*



Waterproof protective structure Σ-7 upgrade to IP67 rating



[SGM7J, SGM7A (IP22 for 7.0 kW) and SGM7G models]



Saves energy with effective use of regenerative energy Σ -7

Regenerative energy can be effectively used between two axes when using a 2-axis integrated SERVOPACK or single-axis SERVOPACKs with a DC bus connection. This saves energy in equipment where regenerative energy was previously consumed by regenerative resistors.

Features

- Energy savings for all equipment
 - · Supplies regenerative energy that was discarded as heat to other axes.
 - · Reduces the amount of electrical power consumed.
- Eliminates the need for regenerative resistors*
 - · Uses regenerative energy and eliminates the need for regenerative resistors.
 - · Lowers the cost of systems and saves space.
 - · Reduces temperature increases commonly caused by the use of regenerative resistors.
- * : Regenerative resistors may be required, depending on machine configurations.

Σ -7S model Σ -7Wmodel 2-axis SERVOPACK DC bus connection Regenerative resistor Consumption . [W/h]

DC bus

connection

2-axis

SERVOPACK

Supports energy conservation with visual motion system

A power monitor for the motion system connected to the MP3300 is provided. This feature supports the monitoring of the power on a day-to-day basis and annual plans for reducing the level of power used.





Monitoring of the amount of energy used enabled

Regenerative

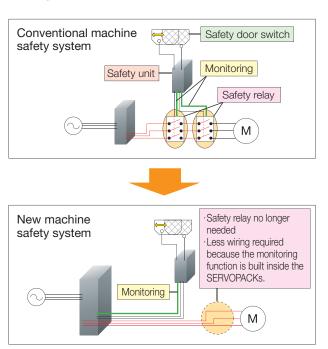
resistor connection

Monitoring display (image)



Satisfies requirements of the SIL 3 of the IEC 61508 functional safety standards (first in Japan)

Certification under this standard will improve the safety of our customers' systems and reduce the costs associated with additional safety certification. It will also be easier to implement compliant safety systems for press machines and other systems on the market in Europe and other regions. This certification will also reduce the man-hours required for wiring connections and the number of peripheral devices.



Features

Stop Category 0 (Safe Torque Off) incorporated

- Meets safety standards for SIL 3 of the IEC 61508 Yaskawa will become the first company in Japan to acquire SIL3 certification for its servo drives. This indicates a significant improvement in safety compared to the Σ -V series.
- Improved functions with safety option module The safety option module (SGDV-OSA01A) for the Σ -V series can also be used with the Σ -7 series. The following functions meet the requirements stipulated under IEC 61800-5-2:*
 - STO: Safe Torque Off (immediate removal of power to motor)
 - SS1: Safe Stop 1 (removal of power after motor has decelerated and stopped)
 - SS2: Safe Stop 2 (maintenance of power after motor has decelerated and stopped)
 - SLS: Safely Limited Speed (limit placed on motor speed)

The responsiveness of these safety functions is significantly enhanced without going through a host system.

* : SIL2 applies when a system is used with the safety option.

Protect systems from high temperatures 🎹

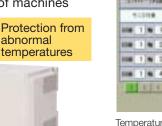


abnormal

temperatures

MP3300, Σ -7 SERVOPACKs, and servomotors are equipped with temperature sensors that can directly monitor temperatures of machines and detect abnormalities to prevent failures.

Real-time temperatures can be viewed on a display by using MP3300.



Temperature monitoring display (image)

Several kinds of powerful functions to prevent unauthorized access

Built-in

temperature



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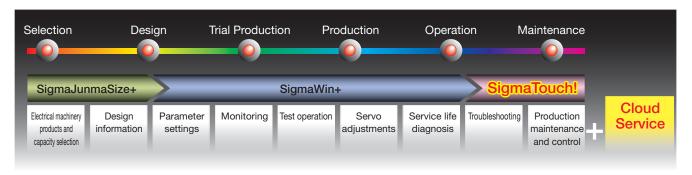
Security functions stand guard to block off multiple possible entry points including programs, projects, controllers, and users.



Yaskawa supports our customers in all their decisions, from product selection to production maintenance, and offers solutions that are always one step ahead of our competitors.

Yaskawa's MechatroCloud offers Build To Order (BTO) services. The SigmaTouch! smartphone application can be used to enhance product lifecycle management and maintenance service.









MechatroCloud is a new cloud service provided by the Yaskawa Electric.

MechatroCloud is available in Japan only. ★See page 20 for the details on MechatroCloud.



Details of service

Build To Order service

Customers can place orders after specifying the parameters they want when their SERVOPACKs are shipped from the factory.

Product management and maintenance service The product manufacturing information used specifically by each customer can easily be saved and displayed at any time.

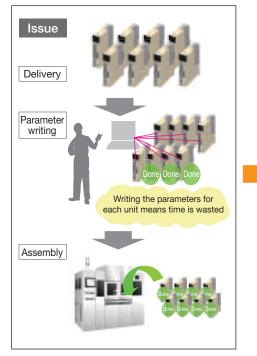
How to use the service

Register as a corporate member of our customer Web services. You can use MechatroCloud after you have registered.

Single or multiple orders possible after specifying parameters (BTO) 2-7



Customers can now place single or multiple orders for SERVOPACKs in the Σ -7 series after specifying parameters at the factory shipment stage. It is no longer necessary to write the parameters at the system assembly site, which means that production lead times can be reduced.



Solution

The Σ -7 SERVOPACKs are delivered with the customer-specified parameters already written prior to shipment.

This reduces the man-hours involved in system assembly work.

The names of the axes are printed on the boxes in which the products are delivered. This ensures that these are no mistakes made when installing the axes.





Product management and maintenance service 🎆

- · Manufacturing information for each product can be easily viewed by using SigmaTouch!, Yaskawa's smartphone application. To view, simply hold your smartphone over the QR code of the product.
- · MechatroCloud can also be used with SigmaWin+.

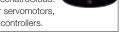








- · You can view the product manufacturing information and the troubleshooting information stored in the MechatroCloud.
- You can view manuals for servomotors, servo drives, and machine controllers.





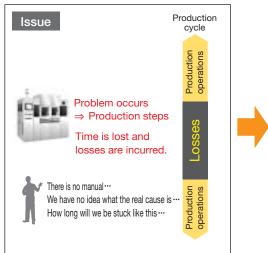
Note: QR code is a registered trademark of Denso Wave Incorporated.

Easier and faster troubleshooting options



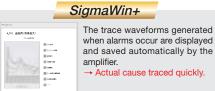
Operators can use smartphones on-site to display the amplifier manual and troubleshooting details. The trace waveforms generated when alarms occur can be saved automatically, and the real causes of problems can be tracked faster, which reduces downtime.

Features:





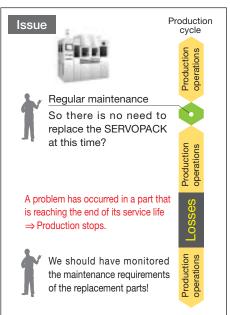


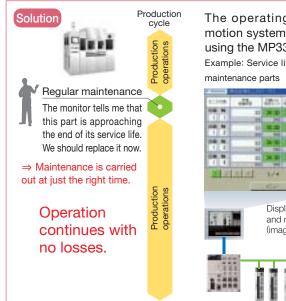


Planned maintenance possible by monitoring the operational status $\frac{MP}{3300}$ Σ -7

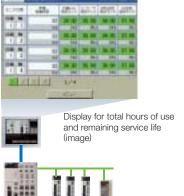


The service life of a product can be estimated, and users are notified when the parts should be replaced. System failure can be prevented because parts can be replaced before products fail or a fault occurs.

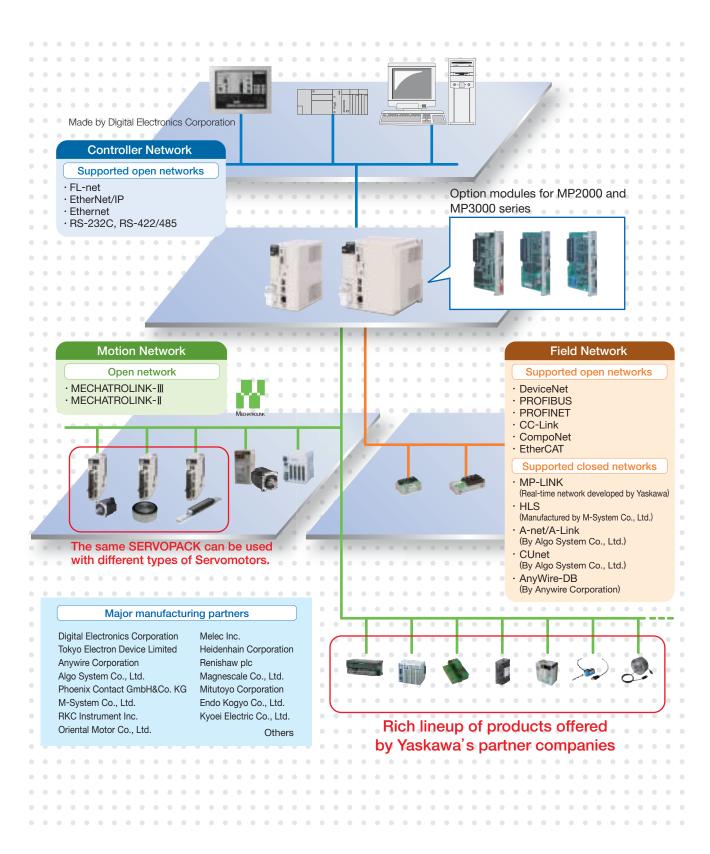




The operating statuses of the motion system can be monitored using the MP3300. Example: Service life diagnosis monitor for

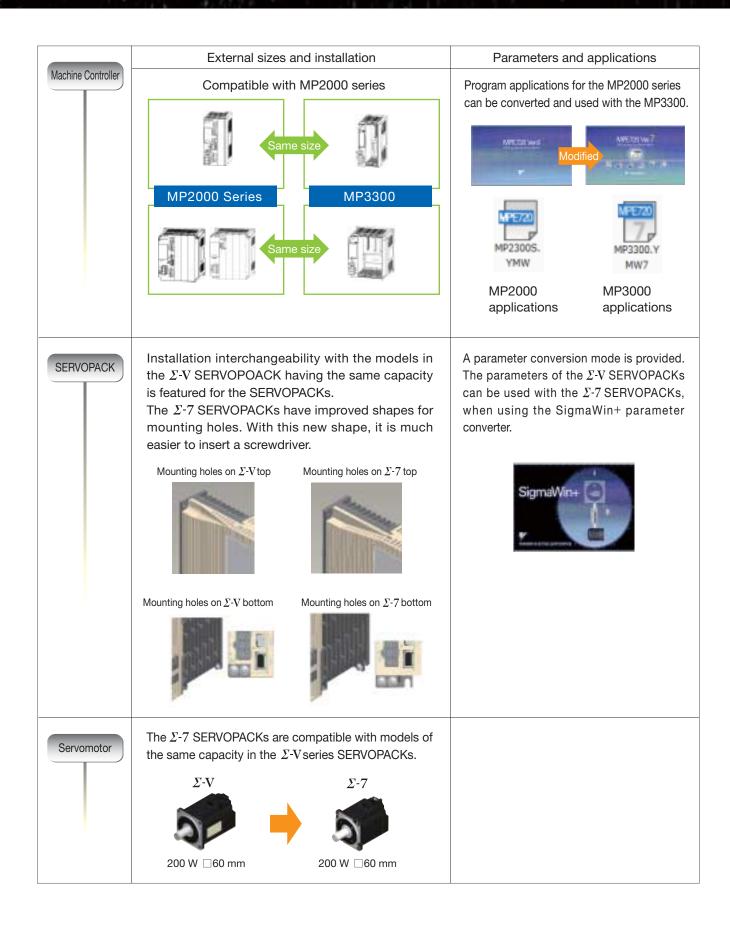


We have expanded our product lines and built up our product series to be compatible with other company systems. Selecting the products of your motion systems is now a one-step process.



Our products are the same size as existing products so they can easily be swapped out. The compatibility of programs and parameters is also preserved. By replacing products, you can easily improve the performance of your system.





MechatroCloud is available in Japan only.

MechatroCloud is a cloud service offered by the Motion Control Division of Yaskawa Electric. With this service, it is now easier and more convenient to use Yaskawa's motion control products. A wide range of services are now available through Yaskawa's website, smartphone applications, and QR codes.

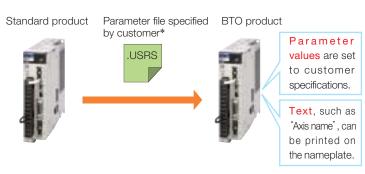
Note: "QR code" is a registered trademark of DENSO WAVE, Inc.





In the BTO (build to order) service available from Yaskawa, parameters for SERVOPACKs are set to the values specified by customers when placing orders. Customers can order customized SERVOPACKs by simply registering parameter specifications on the website. If customers must assemble multiple pieces of the same equipment and/or different equipment on site at one time, they can eliminate the time to write over parameters by simply ordering SERVOPACKs with customized parameters through the BTO service.

Note: To use MechatroCloud service, you must register your name under the corporate membership of the e-mechatronics website, the Yaskawa Electric website for product and technical information.



★: Use a parameter file for version 5.71 or later versions of SigmaWin+.



MechatroCloud Introduction Videos - Now on YouTube

Use the standard bar code reader on your smartphone to read these codes and view videos on YouTube.

"YouTube" is a trademark or a registered trademark of Google Inc.

BTO service



SigmaTouch!



Easy troubleshooting with SigmaTouch! Anytime, Anywhere







"SigmaTouch!" is a smartphone application for MechatroCloud. Product information, such as manufacturing information and parameter lists, can be viewed by simply reading the QR codes of Yaskawa Electric's products with a smartphone camera. Alarm details and troubleshooting information can also be viewed on the smartphone, which can greatly reduce recovery time.

Note: The QR codes can be read with Android OS 4.0.3 or later versions. The Android must be connected to the network to use this service.



Machine Controller

The MP Machine Controller series anticipates the needs of increasingly complex and advanced systems to offer customers the most optimal solutions.

In the 1990s, Yaskawa introduced Machine Controllers to the motion control market that was dominated at the time by programmable controllers. Since then, Yaskawa has evolved as a top manufacturer of Machine Controllers and is turning customer problems into opportunities.

These efforts have included improvements in the high-speed performance of machines and systems, enhancement of productivity by reducing takt times, and monitoring the operation status.

















Modular Type



Machine Controller

NEW

The base unit, CPU modules and optional modules can be freely combined to create a Machine Controller best suited to the user's control scale and control panel size.



Machine Controller

MP3200

Motion, vision, and robotics systems deliver the highest possible machine performance.

Board Type

Machine Controller MP2100

51 motion Application Program Interfaces (API) are available to effectively achieve the desired motion control using a personal computer.



Machine Controller

MP3000 Series

The MP3000 series includes an extensive lineup of Machine Controllers and develop the most ideal system scale and meet motion requirements. In addition, diversified functions, performances, and services are available to support customer needs throughout the entire machine lifecycle.





Features

Ultimate system performance

Equipped with the fastest CPU, the MP3300 Machine Controller makes it simple to construct a high-speed, high-accuracy, and multi-axis system by connecting units that support MECHATROLINK-III.

Ultimate environmental performance

The power consumption of the motion system can be monitored, which helps to conserve energy.

Ultimate support

The support available from Yaskawa now makes it easier to handle large-volume data, such as system operation statuses. This improves traceability at the production site. New support services such as Yaskawa's MechatroCloud service make it even more convenient for users to store and manage product information.

Ultimate ease of use

M23000

The adjustments to a multi-axis system can be completed in a short time using the MPE720 Ver. 7 engineering tool. It is also easy to add a motion system to an existing sequence system.

Ultimate safety and security

Security measures have been enhanced to prevent the outflow of know-how. In addition, temperature sensors installed in the MP3300 enable early identification of abnormal temperatures in the system.

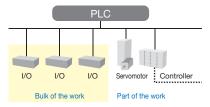
Ultimate lineup

In addition to the Σ -7 series of AC Servo Drives, a strong lineup of products is also available from Yaskawa's partners.

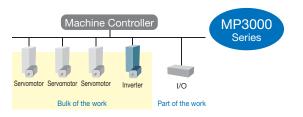
Ultimate compatibility

Program applications for the MP2000 series can be converted and used with the MP3000 series.

Machine Controller and PLC (Programmable Logic Controller): How do They Differ?



- Excellent at controlling I/O.
- Focuses more on connectability to various I/O devices than axes synchronization.
- Most are modules.



- Ideal for controlling machines and devices.
- O Focuses on precise synchronous and high-speed control on multiple motors.
- The optimal controller models can be selected based on the device requirements.

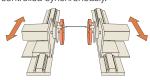


Four all-in-one control modes

Every aspect of control from simple to complex operations can be achieved using one CPU without adding optional modules for each kind of control.

Synchronous Phase Control

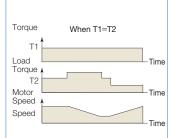
Speed control with position compensation (electronic shaft) or position control with 100% speed feed forward (electronic cam). Multi-axis servomotors can be controlled synchronously



0.3 mm dia. mechanical pencil lead does not break.

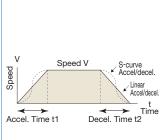
Torque Control

Generates a constant torque, regardless of speed.



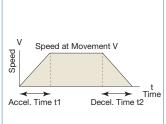
Position Control

Advances to the target position, and stops or holds.



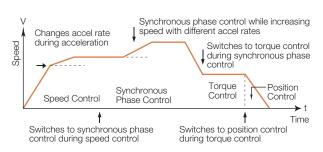
Speed Control

Turns the motor at the specified speed, with user-defined acceleration/deceleration slopes.



Switch between any of the modes while online

The MP3000 series can switch between these four modes while online.



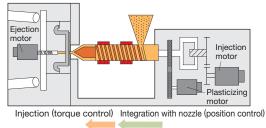
Packaging machines

Synchronized phase control enables cutting, sealing and other kinds of processing that are synchronized with the movement of the workpiece.



Injection molding machines

Switching from position control to torque control can be executed without deceleration.



Return operation (positioning)

The MP3000 Series Brings a Cornucopia of Solutions

Gantry Mechanism and Alignment Stage Mechanism

These mechanisms comprise the basic system used in devices for the manufacturing and the inspection of semi-conductor chips, LCDs, and other components. High precision as well as high acceleration and deceleration are required for these processes. Two axes must be synchronized to control and operate the gantry mechanism.

Advantage Achieves complete synchronous multi-axis control and online adjustment.

Solution for Conveyance

Provides a solution for the control mechanism that allows workpieces to be processed in accordance with the speed of the production line.

Advantage Allows the slave axes to follow master axis operation when the inverter is used as the master axis and both the inverter and servo drives are connected through a network.

Solution for Winder

Provides a solution for the control mechanism where a winder winds and a feeder unwinds.

Advantage Achieves high-precision winding, feeding, dancer control, and tension control with standard servo drives and inverters. Line control can be constructed easily with user functions set in advance.



Machine Controller MP3000 Series

MP3200

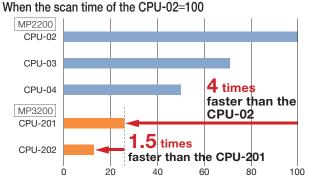
The MP3200 is the flagship model of the MP3000 series that integrates motion, vision, and robotics systems to provide the most optimal machine performance. Adjustments, design, and maintenance can be also centrally controlled using the MPE720 Ver. 7 system integrated engineering tool.



[Catalog No. KAEPC88072502]

Takt times improved by ultra-high-performance CPU

 \odot Fastest application processing in the industry: 4-axis, 125 μ s Arithmetic processing must be performed at higher speeds for systems to work faster. The MP3200 features the CPU-202, an ultra-high-speed CPU that runs 1.5 times faster than the CPU-201, to improve takt times.



\bigcirc MECHATROLINK-III: 125 μ s communications cycle

Revolutionize machine accuracy and tracking control precision by combining the CPU-202 module for 125 μ s communications cycle and the Σ -7SERVOPACKs.



Varied applications by expanding program capacity

O Application program capacity: 31 MB

The program capacity has been dramatically expanded to 31 MB (over the previous capacity of 11.5 MB) to support large-scale control systems. The number of application drawings has also been increased significantly to support many different kinds of applications.



| Controller Name | MP2200 (Conventional) | MP3200 |
|---------------------------------|--------------------------|-----------|
| No. of high-speed scan drawings | 200 DWGs | 1000 DWGs |
| No. of low-speed scan drawings | 500 DWGs | 2000 DWGs |
| No. of user function drawings | 500 DWGs | 2000 DWGs |

New memory area increases the speed of applications

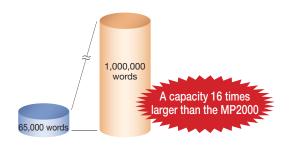
G register: New capacity of 2 M words

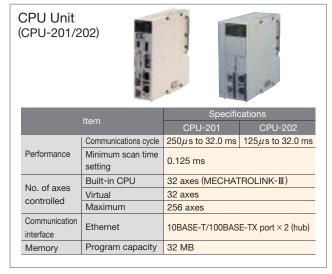
A new G register, a general-purpose register (with no battery backup) has been added, making it possible to process even complex applications at higher speeds.



O M register capacity: 1 M words

The capacity of the M register (general-purpose register with backup capability) has been greatly expanded for use with system recipes in diversified small-quantity production.







Enhanced Usability and Traceability

- O USB memory interface provided as a standard feature.
- Maintainability and traceability improved by the incorporation of the FTP server/client function and logging function.

Flexible System Construction

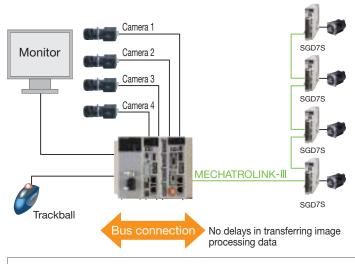
- All MP2000 series optional modules* supported.
- *: See "Optional Modules" on page 31.

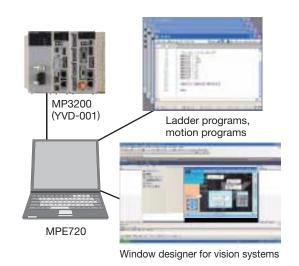
Integration of Motion and Vision Systems

O Processing with zero delays

The CPU Unit and Vision Unit are connected using a high-speed bus (an industry first), which enables motion processing and vision processing to be executed with absolutely no communication delays. Four digital interface cameras, each with a different format, can be connected.

- All image processing executed using combinations of the basic 4 vision commands.
- O Development of motion-vision system using MPE720.
- Easy customization of vision systems with window designer.





Vision Unit (YVD-001)



| | Item | Specifications |
|------------------------------|----------------------------|--|
| Performance | Rate of improved operation | Double*1 |
| Imaga propaging | Blob analysis | Feature extraction and measurement using binary images |
| Image processing | Template matching | Normalized correlation pattern matching |
| Imaga innut | Camera interface | Mini Camera Link (PoCL) × 4 |
| Image input | No. of pixels | 640 × 480 to 2440 × 2048 (5 megapixels) |
| Manitarautout | Monitor interface | VGA 15-pin D-sub connector |
| Monitor output | Display colors | Graphics: 64 colors, Images: 256 gray levels |
| Operating interface | Trackball | USB mouse interface |
| Communication interface | Ethernet | 100BASE-TX port × 2 (hub) |
| | Image capture memory | 64 MB |
| Managari | Image analysis memory | 32 MB |
| Memory | Image display memory | 64 MB |
| | External memory | USB memory (2 GB) of CPU unit |
| I/O | Trigger input | 4 points |
| 1/0 | Flashlight output | 4 points |
| Programming | Image processing programs | Programming at CPU side (ladder language, motion language) |
| methods User window creation | | Programming-free (using MPE720 window designer*2 for vision systems) |

*1: Compared with the MYVIS YV260

*2: Under development

Machine Controller MP3000 Series

MP3300_

The MP3300 Machine Controller makes it possible to freely combine the Base Unit and CPU modules to match the customer's control scale and control panel size.

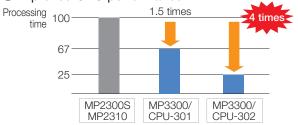
Combination with the Σ -7 series of AC Servo Drives realizes e-motional motion control in the customer's system.



[Catalog No. KAEPC88072503]

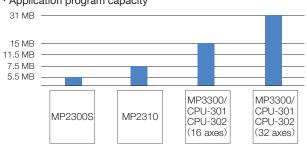
Enhanced control performance

The MP3300 delivers high-speed and high-level performances, and expands program capacity. The MP3300 is also capable of high-speed, synchronized communication with MECHATROLINK-III compatible Servo Drives and AC Drives.



*: Ladder operation speed where the scan time of the MP2300S/MP2310=100

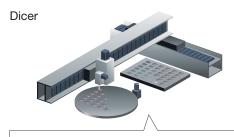
- Expanded program capacity
 - · Application program capacity



· Number of drawings

| Number of drawings | MP2000 series | MP3300/CPU-301/CPU-302 |
|---------------------|---------------|------------------------|
| For high-speed scan | 200 drawings | 1000 drawings |
| For low-speed scan | 500 drawings | 2000 drawings |
| For user function | 500 drawings | 2000 drawings |

O Double-precision real-number, 64-bit integer data for higher precision



With double-precision real-number, 64-bit integer data, rounding errors during arithmetic calculations are reduced, and control at higher levels of precision can be achieved.

Dispenser

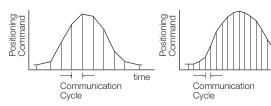
Controlling the path performance in the corner areas is an issue. However, implementing path control with a higher level of precision enhances dispensing quality.

\odot Fastest transmission cycle: 125 μ s (4 stations)

The MECHATROLINK-III motion network, which is among the fastest in the industry, is provided with the main unit CPU of the MP3300 as a standard option. The smoother motion control results in higher levels of precision.

| MECHATROLINK-Ⅲ | | | | |
|-----------------------|--------------------------|---------------------------------|--|--|
| Transmission Speed | | ion Cycles nected Stations) | | |
| 100 Mbps | 125 μ s (4 stations) | $500 \mu\text{s}$ (14 stations) | | |
| 100 Mbps | $250\mu s$ (8 stations) | 1.0 ms (16 stations)* | | |

*: The maximum number of stations, including I/O, is 21.



CPU module (CPU-301/302)

| Item | Specifications |
|------------------------|---|
| | JAPMC-CP3301-1-E [CPU-301(16 axes)] |
| Model (Abbreviation) | JAPMC-CP3301-2-E [CPU-301(32 axes)] |
| iviodel (Appreviation) | JAPMC-CP3302-1-E [CPU-302(16 axes)]* |
| | JAPMC-CP3302-2-E [CPU-302(32 axes)]* |
| High-speed scan | Min. 250 μs (CPU-301) |
| time setting | Min. 125 μs (CPU-302) |
| Flash memory | 16 axes: 24 MB (User memory 15 MB) |
| T lasti memory | 32 axes: 40 MB (User memory 31 MB) |
| SRAM | 16 axes: 4 MB, 32 axes: 8 MB |
| DRAM | 256 MB |
| MECHATROLINK | · MECHATROLINK-Ⅲ × 2 ports |
| WEGHAINOLINK | Master function |
| Ethernet | 10BASE-T/100BASE-TX × 1 port |
| | Seconds, minutes, hour, day, week, |
| Calendar | month, year, day of week, |
| | and timing (battery backup) |
| USB | · USB 2.0 Type-A host × 1 port |
| | · Compatible devices: USB storage |
| | 0.1.1.00.1.1.01.1.1.1.1.1.1.1.1.1.1.1.1 |

*: CPU-302 Module uses 2 slots, CPU Slot and Option Slot 1 for the Base Unit.



Better usability

Instead of opening an adjustment screen for each axis, multi-axis tuning can be performed on one screen, which dramatically reduces the setup time.



Enhanced maintainability

A storage USB port is provided on the CPU Unit as a standard option, which makes it easy to update the version of the equipment, back up data, and import and export large-volume data. A data logging function also allows the system's operation statuses to be saved in the internal RAM or on a USB memory device. The logging data can be easily accessed from remote host systems. This makes it possible to acquire large volumes of data such as the system's operation statuses, and vastly improves traceability on the production site.

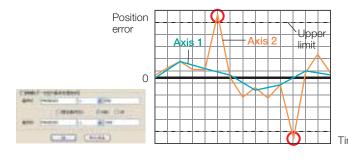
Loading/Saving of programs and data

Operations can be performed using the DIP switches on the CPU Unit body. Even in places where a PC cannot be brought in, you can update the versions of the equipment and back up the data on-site with ease.



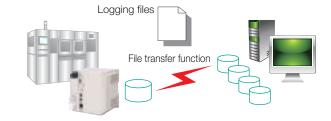
Data logging

Settings can be selected for the conditions under which the logs are output. The logging data is saved only if the values of the specified registers fail to meet the output conditions. This enables a rapid response when trouble occurs.



File transferring

By transferring the system's operation data (logging data and register data) at the specified synchronization, large volumes of operation data can be acquired with no fear that the data may be unexpectedly damaged. As a result, the traceability at the production site is vastly improved.



Complete upper compatibility with the MP2000 series

The full lineup of optional modules and application programs for the MP2000 series can be used with the MP3300. This enables a completely hassle-free upgrade from the MP2000 series to the MP3300, and enhances system performance and functions.

Common

Specification Comparison of MP3200 and MP3300

| | | MP3 | 3300 | MP3 | 3200 | |
|---|-----------------------------------|---|---|--|---------------------------|--|
| | | CPU-301 (16 axes) CPU-302 (16 axes) | | CPU-201 | CPU-202 | Remarks |
| Performan | ce comparison odule*1 | CPU-301: 1.5 CPU-302: 4.0 | CPU-301: 1.5 CPU-302: 4.0 | 4.0 | 6.0 | *1: When compared to MP2310 and MP2200/CPU-02 |
| Number of | slots (on main rack) | 1/3 | 3/8 | 3/5 | 5/8 | |
| Rack expa | nsion | | Pos | sible | | |
| Multi-CPU | configuration | Not po | Not possible Possible*2 | | ible*2 | *2: Up to 5 modules, including the main CPU module |
| Ethernet | | 100Base- | ise-TX ×1 port 100Base-TX × 2 ports (HUB)*3 | | *3: Built-in HUB function | |
| USB I/F | | | Provided (for s | torage device) | I | |
| MECHATR | OLINK I/F | Provided (CPU-301 250 μs, (| CPU-302 125 μs*4) | Provided (250 μs*4) | Provided (125 μs*4) | *4: Minimum communications cycle |
| | SVC | 16 axes | | 32 axes | | |
| Number of controlled | SVR | 16 axes | | 32 axes | | |
| axes | Maximum number of controlled axes | 256 axes (wh | 56 axes (when SVB-01 or SVC-01 optional modules are used, or when racks are expanded) | | | |
| | Data tracing | 256 K words | | 1 M words | | |
| Program | Table data | 1 MB | | 3 MB | | Battery backup |
| memory capacity | M registers | | 1 M words | | | |
| | User memory | 15 MB | | 31 MB | | |
| Optional m | nodules | All | MP2000 series opti | onal modules availa | ble | |
| MotomanS | Sync-MP | Ethernet o | Ethernet connection Ethernet MP3000 bus connection | | | |
| | Number of ladder programs | High-speed scan DWGs: max. 1000, Low-speed scan DWGs: max. 2000, User function DWGs: max. 2000, Motion programs: max. 512 | | | | |
| Basic | Register types | S/M/G/I/O/C/D/# | | | | |
| functions | Data types | B/W/L/Q/F/D/A | | | | |
| | Index registers | Subscripts I /J, and array registers | | | | |
| | Register capacity | M registers: 1 M words, G registers: 2 M words | | | | |
| Motion control | Slave functions | Supported | | | | |
| functions | Slave CPU synchronization | Supported | | | | |
| Communi- cations | Automatic reception | Supported (Maximum number of automatic reception connections: 10) | | | | |
| functions | File transfer functions | Supported (FTP server/client) | | | | |
| Data | Number of groups | | | 4 (selectable) | | |
| tracing functions | Trace memory | 256 K words/4 groups 1 M words/4 groups | | | | |
| | Traceable data points | | | oints/group | | |
| Data | Number of groups | 4 | | *5: When using recommended USB memory device | | |
| logging functions | Number of log files | Built-in RAM disk (max. 8 MB), or USB memory device (4 GB*5) | | | | |
| Data logging points USB memory functions | | 64 points Backup/restore of project files, data logging, import/export of register data | | | | |
| | | backup/restore of | | | ort or register data | |
| Linkage functions | Servo tracing | | • | orted | | |
| for Σ -7 Servo Drives | Monitoring | | | orted | | #6: Indox develor |
| JOING DINES | Multi-axis tuning | | Developmer | nt planning*6 | | *6: Under development |



Optional Modules

■ Motion Modules



Connects to the SERVOPACK for motion control. Various MECHATROLINK slaves can be connected to the SVC-01 and SVB-01 modules.

| Name | Description |
|--------|------------------------------------|
| SVC-01 | MECHATROLINK-∭ × 1 channel |
| SVB-01 | MECHATROLINK-II × 1 channel |
| SVA-01 | Analog-output 2-axis servo control |
| PO-01 | Pulse-output 4-axis servo control |

Note: One CPU can control up to 16 modules.

I/O Modules



Provides digital or analog I/O interface.

| Name | Description | |
|---------|--|--|
| | Digital input: 16 points (sink output mode) | |
| LIO-01 | Digital output: 16 points (sink output mode) | |
| | Pulse input: 1 point | |
| | Digital input: 16 points (source output mode) | |
| LIO-02 | Digital output: 16 points (source output mode) | |
| | Pulse input: 1 point | |
| | Digital input: 32 points | |
| LIO-04 | Digital output: 32 points | |
| | (sink output mode) | |
| | Digital input: 32 points | |
| LIO-05 | Digital output: 32 points | |
| | (source output mode) | |
| | Digital input: 8 points | |
| | Digital output: 8 points (sink output mode) | |
| LIO-06 | Analog input: 1 channel | |
| | Analog output: 1 channel | |
| | Pulse counter: 1 channel | |
| DO-01 | Digital output: 64 points (sink output mode) | |
| AI-01 | Analog input: 8 channels | |
| AO-01 | Analog output: 4 channels | |
| CNTR-01 | Pulse-input counter | |

■Communication Modules



Used to construct an open network. Modules with various types of interfaces are available.

| Name | Description | |
|--------------|---------------------------------------|--|
| 218IF-01 | Ethernet (10BASE-T) port × 1 | |
| 21015-01 | RS-232C port × 1 | |
| 218IF-02 | Ethernet (100BASE-TX) port \times 1 | |
| 21015-02 | RS-232C port × 1 | |
| 217IF-01 | RS-232C port × 1 | |
| 21/15-01 | RS-422/485 port × 1 | |
| 260IF-01 | DeviceNet port × 1 | |
| 20015-01 | RS-232C port × 1 | |
| 261IF-01 | PROFIBUS port × 1 | |
| 20115-01 | RS-232C port × 1 | |
| | FL-net | |
| 262IF-01 | (100BASE-TX) port × 1 | |
| | (10BASE-TX) port × 1 | |
| 263IF-01 | EtherNet/IP (Scanner and adapter) | |
| 20311 -01 | port × 1 | |
| 264IF-01 | Port for EtherCAT slave \times 2 | |
| 20415-01 | (1 circuit) | |
| 265IF-01 | CompoNet port × 1 | |
| 266IF-01 | PROFINET master | |
| 266IF-02 | PROFINET slave | |
| 215AIF-01 | MPLINK communication/RS-232C | |
| Z I JAIF U I | CP-215 communication/RS-232C | |

Note: One CPU can control up to 8 modules.

■ Distributed I/O Modules

I/O devices can be installed in a decentralized manner.

MECHATROLINK-II Compatible Modules

| Name | Description |
|---------------------|----------------------|
| IO2310 | 64-point I/O |
| 102310 | (sink mode output) |
| 102330 | 64-point I/O |
| 102330 | (source mode output) |
| PL2900 | Reversible counter |
| PL2910 | Pulse output |
| AN2900 | Analog input |
| AN2910 | Analog output |
| 102900 | 16-point input |
| 102910 | 16-point output |
| 102920 | 8-point I/O |
| IO2950 Relay output | |
| | |

MECHATROLINK-III Compatible Modules

| = | | | |
|---|----------------------------------|--|--|
| Name | Description | | |
| MTD2310 | 64-point input | | |
| | (sink/source input) | | |
| | 64-point output | | |
| | (sink/source input) | | |
| MTA2900 | Analog input: 8 channels | | |
| MTA2910 | Analog output: 4 channels | | |
| MTP2900 | Pulse input: 2 channels | | |
| MTP2910 | ITP2910 Pulse output: 4 channels | | |

■ Connection Module

Used to connect the Base Unit to the Connection Modules or connect between the Connection Modules.

| Name | Description | |
|--------|----------------------------|--|
| EXIOIF | Expansion Interface Module | |

Machine Controller MP3000 Series

Common

MYVIS YV260 Network Machine Vision System

The MYVIS is a high-performance vision system that combines advanced image processing technologies with many of the servocontrol technologies developed by Yaskawa over the years as a pioneer in the field of servo drives.



[Catalog No. KAEPC86077500]

Example of System Configuration

In this example, the MYVIS YV260 is connected to the open motion network MECHATROLINK. With MECHATROLINK communications, the MYVIS can receive data on the current position of the motor's axes in succession. Using this data, the necessary adjustments are determined for high-accuracy calibration of the machine coordinate system.



Features

- Compatible with high-resolution camera
 - · Digital camera (300,000 to 5,000,000 pixels)
 - · Analog camera (300,000 to 1,250,000 pixels)
- 2 High-speed preprocessing of image quality improvement by hardware
- 3 Possible to simultaneously capture images from four cameras
- 4 Compatible with color camera
- 5 Compatible with MECHATROLINK-II and 100-Mbps Ethernet communications

Specifications

| Item | | Description |
|-----------------------------|----------------------------|--|
| Number of cameras connected | | 4 |
| Camera interface | Analog | 300,000 to 1,250,000 pixel (1280 × 960) |
| | Digital (camera link) | 300,000 to 5,000,000 pixel (2440 × 2048) |
| | Simultaneous image capture | 4 (2 for 5,000,000 pixel) |
| | External trigger input | 4 simultaneous or individual inputs |
| Preprocessing | | Inter-frame operation, convolution filter (3×3) , |
| | | Morphology (Dilation / Erosion) |
| Monitor output | | VGA or XGA |
| External interface | Field network | MECHATROLINK-II |
| | Ethernet | 10BASE-T/100BASE-TX |
| | Serial communications | RS-232C × 2 channels (115.2 kbps max.) |
| | Parallel I/O | General purpose output 16 points + alarm 2 points |
| | | General purpose input 16 points + mode change 3 points |
| | | + trigger input 1 point |
| | Trackball | USB mouse interface |
| Program development | | C language (SH-C compiler Ver. 9 or later) |

Board Type

Machine Controller MP2100

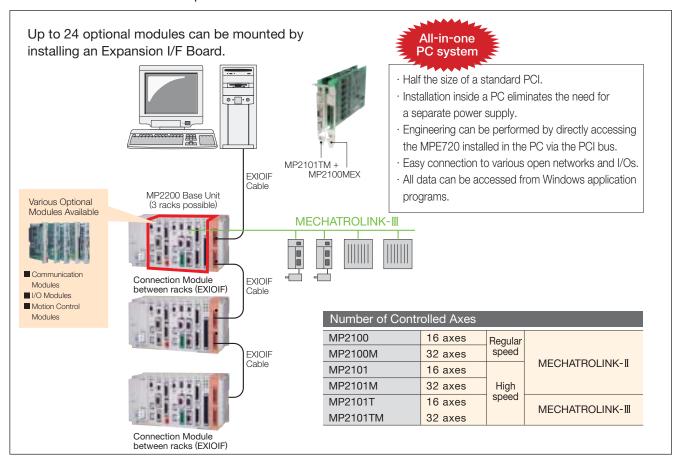
MP2100 is the perfect controller for machines connected to a personal computer. 51 motion Application Program Interfaces (API) are available to effectively realize the desired motion control using a personal computer.



[Catalog No. KAEPC88070015]

Example of System Configuration

Up to three racks of additional MP2200 Base Units (up to 24 optional modules) can be connected using the MP2101TM dedicated Rack Expansion I/F Board with EXIOIF Cables and EXIOIF Modules.



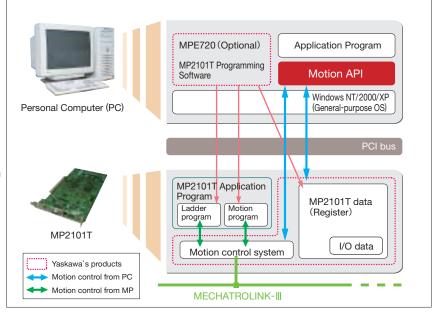
Main Motion APIs

Motion related API

- Device related: Servo ON/OFF
- Positioning: JOG feed, origin return, positioning, external positioning, and specified time positioning
- Interpolation: Linear, circular, and helical interpolation
- Torque reference Gear function
- Latch function
- Motion operation: Modification of motion data and parameters

System API

- Register operation: I/O operation
- Alarm: Information acquisition and alarm clearing
- System operation: Opening, closing, and switching of object controller
- Operation calendar



AC Servo Drives

The AC Servo Drives Σ series guarantees maximum performance as the core components of systems.

Yaskawa introduced its AC Servo Drives to the market in 1983, and further marketed the Σ series in 1992. Since then, Yaskawa has continued to develop the Σ series, focusing on making these products compact, and enhancing performance and ease of use. As a result of these efforts, the total shipments of AC servomotors reached 10 million units in March 2012.

Yaskawa will continue to develop world-class AC Servo Drives to provide even greater satisfaction to its customers.





NEW CONCEPT Σ -S Series

Easy, compact, and low price! The Σ -S series is recommended for applications that do not conventionally use Servo Drives, and enables servo control of pneumatic and other equipment.





The Σ -7 series delivers a leading performance based on the concept of "7 ultimate e-motional solutions." These Servo Drives also support a variety of new needs, such as further enhancing safety and incorporating environmentally friendly designs.

3.3 W to 30 W

Σ -Vmini/ Σ -V-MD

The powerful Σ -Vmini Servo Drives retain all the leading performance, functionality and ease of use of the Σ -V series in a palm-size package.

These board-type SERVOPACKs enable multi-axis control.



 Σ -Vmini



22 kW to 55 kW

Large-capacity Σ -V

Large-capacity Σ -V Servo Drives feature superlative performance, simple startup, and outstanding expand ability. These drives also help achieve considerable energy savings.





Σ -7Series

The Σ -7 series delivers a world-leading performance based on the concept of "7 ultimate e-motional solutions." These Servo Drives also support a variety of new needs, such as further enhancing safety and incorporating environmentally friendly designs. This makes it possible to offer solutions that can satisfy a wide range of conditions throughout the system lifecycle.

[Catalog No. KAEPS80000123]



Features

Ultimate system performance

 Σ -7 series SERVOPACKs can achieve a high-speed response frequency of 3.1 kHz. Vibration suppression functions have also been enhanced. The motors incorporate 24-bit, high-resolution encoders that further increase system takt times and achieve a high throughput.

Ultimate environmental performance

Specifications have been improved to allow installation in a wider range of environments. These new safe and secure designs enable use even in harsh environments where previously prohibited, such as altitudes of 2,000 m or ambient temperatures of 60°C*1. Regenerative servo energy inside the system can also be effectively used with 2-axis integrated SERVOPACKs or by connecting multiple axes with a DC bus connection.

Ultimate support

- Build-To-Order service (BTO)
 Products can be shipped from the factory with the specified parameters, which helps to reduce system production lead times.
- Product control and maintenance support
 Product QR codes can be read using Yaskawa's SigmaTouch! smartphone application. This allows users to view manuals and troubleshooting information.

Ultimate compatibility

Mounting compatibility with the Σ -V series is ensured, and Σ -V parameters can be converted simultaneously to Σ -7 parameters using the SigmaWin+ parameter converter.

Ultimate ease of use

Tuning-less function stability has been increased to approximately twice that of the Σ -V series. This enables swift movement with no vibration or gain adjustment.

Ultimate safety and security

 Σ -V Servo Drives satisfy of SIL3 the functional safety standard IEC61508 (first certification in Japan*2). Temperature sensors are incorporated as a standard feature, and signs of abnormalities can be caught at an early stage by monitoring the temperature from a host controller.

Ultimate lineup

In addition to Yaskawa's products, our partner companies in the MECHATROLINK Members Association (MMA) offer an extensive lineup of I/O devices and sensors, and provide all the components needed to construct equipment motion systems.

- *1 : Derating required.
- *2 : As investigated by Yaskawa.

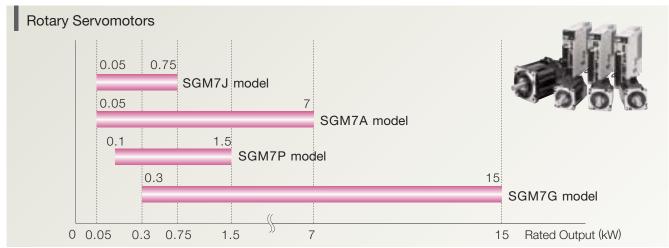


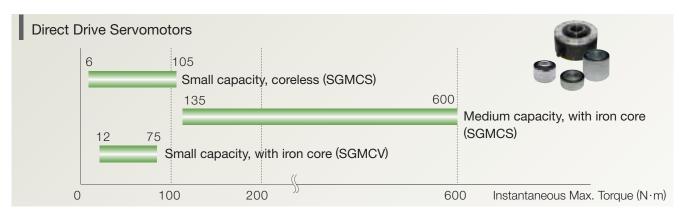


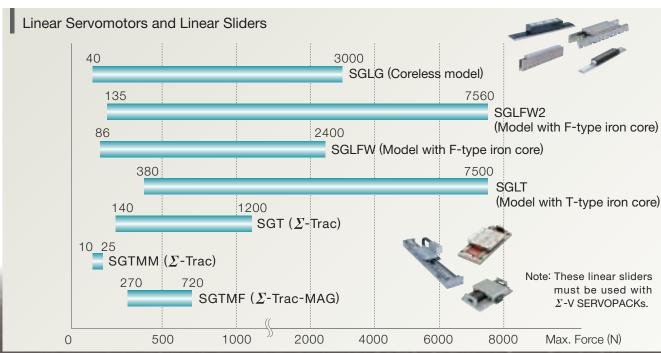
 Σ -7SSingle-axis SERVOPACK . 50 W to 15 kW



 Σ -7WTwo-axis SERVOPACK 200 W to 1.8 kW







SERVOPACK

SERVOPACKs



Single-axis MECHATROLINK-III communications reference Σ -7S



Two-axis
MECHATROLINK-III
communications
reference Σ-7W



Single-axis MECHATROLINK-II communications reference Σ -7S



Analog voltage/ pulse train reference

■ MECHATROLINK-III/-II Communications Reference

©Real-time communication

A high transmission speed allows real-time transmission of various data required for control.

Cost savings

Multiple stations can be connected to a single MECHATROLINK transmission line, so wiring costs and time are greatly reduced. Also, only one signal connector is required on the host controller. The all-digital network eliminates the need for a converter to change speed/torque references from digital to analog and for a pulse generator to create position references.

©High-precision motion control

The SERVOPACK when connected to the host controller in the MECHATROLINK-III/-II network provides not only torque, position, and speed control, but also synchronized phase control that requires advanced control technology. The control mode can be changed online so that the machine can move smoothly in complex motions with great efficiency.

| Communications protocol | MECHATROLINK-III | MECHATROLINK-II | |
|-----------------------------------|--|-----------------------------------|--|
| Physical layer | Ethernet | Same as RS-485 | |
| Baud rate | 100 Mbps | 10 Mbps | |
| Transmission cycle | Σ -7S: 125 μ s to 4 ms, Σ -7W: 250 μ s to 4 ms | 125 μ s to 4 ms | |
| Number of transmission bytes | 32 or 48 bytes/station | 17 or 32 bytes/station 30 max. | |
| Number of slaves | 62 max. | | |
| Maximum transmission distance | 75 m between stations | 50 m total (100 m with Repeater) | |
| Minimum distance between stations | 20 cm | 50 cm | |

Analog Voltage/Pulse Train Reference

| Φ | Speed | Reference | Max. input voltage | ±12 V (forward s | peed reference with positive reference) | | | |
|-----------------------------|---------------------|--------------------------------|---------------------|--|---|--|--|--|
| voltag | control | voltage | Factory setting | 6 VDC at rated speed (Input gain setting can be changed.) | | | | |
| Analog voltage reference | Torque | Reference | Max. input voltage | ±12 V (forward to | ±12 V (forward torque reference with positive reference) | | | |
| A 57 | control | voltage | Factory setting | 3 VDC at rated torque (Input gain setting can be changed.) | | | | |
| φ | Position control | puise | Туре | Select one: Sign + pulse train, CW + CCW pulse train, or two-phase pulse train with 90° phase differential | | | | |
| enc | | | Form | For line driver, op | pen collector | | | |
| Oulse train reference | | | pulse Max. input | Line driver | Sign + pulse train, CW + CCW pulse train: 4 Mpps Two-phase pulse train with 90° phase differential: 1 Mpps | | | |
| Pulse t | | | pulse frequency* | Open Collector | Sign + pulse train, CW + CCW pulse train: 200 kpps Two-phase pulse train with 90° phase differential: 200 kpps | | | |
| | | Clear signal (Position erro | or clear) | For line driver, op | pen collector | | | |

^{*:} If the maximum reference frequency exceeds 1 Mpps, use a shielded cable for I/O signals and ground both ends of the shield. Connect the shield at the SERVOPACK to the connector shell.

Command Option Attachable Type

- \bigcirc Compatible with all features of the new Σ -V Series
- SERVOPACKs can interface with various communication formats by using attachable optional modules for commands.

Note: Be sure to use INDEXER or DeviceNet optional modules for the command option attachable type SERVOPACKs. They will not work without these modules.





Command Option Attachable Type

Servopack

With Optional Module



Optimal expandability can be achieved by attaching an optional module to the SERVOPACK.

Combination of SERVOPACKs and Option Modules

✓ : Can be used X: Cannot be used

| | Fully-closed Loop Control (SGDV-OFA01A) | Safety (SGDV-OSA01A) | | | | |
|---|---|---|----------|---|--|--|
| Analog Voltage and Pulse Train | Reference (Single Axis: SG | GD7S-□□□A00A) | ✓ | ✓ | | |
| MECHATROLINK-II Communica | ations Reference (Single Axis: SG | GD7S-□□□A10A) | ✓ | ✓ | | |
| MECHATROLINK-III Communica | ✓ | ✓ | | | | |
| MECHATROLINK-Ⅲ Communica | × | × | | | | |
| SERVOPACK & Option Module Set (Set Model Number) | SERVOPACK (Model Number) | Command Option Module (Model Number) | _ | | | |
| SERVOPACK with INDEXER Module Mounted (SGD7S - AE0A - 10 - 10 -) | Command Option Attachable-type | INDEXER (SGDV-OCA03A) | ~ | × | | |
| SERVOPACK with DeviceNet Module Mounted | (Single-axis: SGD7S- | DeviceNet*1 (SGDV-OCA04A) | ✓ | × | | |
| (SGD7S - AE0A - 50 -) (SGD7S - AE0A - 60 -) | AE0A) | DeviceNet*2 (SGDV-OCA05A) | ✓ | × | | |

^{*1:} Driven by SERVOPACK control power supply.

INDEXER Module

INDEXER Module

Simple

- Simple connection to the host controller can be established with the I/O module.

Smart

Special languages are not required, because required operation patterns are easily made by simply setting the data for position and speed in program tables. Optimum operation method supports your application. For positioning, up to 256 steps can be programmed.

(Operation) Program tables,

Position and speed tables (station positioning), Registration (positioning by external signals), Serial communication

Various functions, including external positioning, JOG table operation, homing, and programmable signal outputs are provided.

Speedy

- \bigcirc Reliable high-speed, high-precision positioning when combined with high-performance \varSigma -7S SERVOPACKs.
- Motion control is accomplished without using motion controllers.

Note: The INDEXER module can be used in combination with the fully-closed module.





Program Table Editing Window

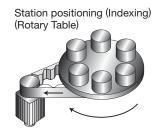
Specifications

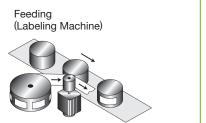
| Function | Specifications |
|--|---|
| Stations for Program | 256 |
| Table Operation | 230 |
| JOG Speed Setting | 16 |
| ZONE Signal Output | 32 |
| Serial Communication | HR: ASCII; max. axes: 16 MEMOBUS: Binary |
| Homing Methods | 3 |
| Equally-dividing and Indexing Positioning (Station Positioning Command) | Rotary machine and tool setting |

Application Examples

Point-to-point positioning (X-Y Table)







^{*2:} Driven by external power supply.

SERVOPACK

With Optional Module

Using Commands

DeviceNet Module

- © Compliant with the communication specifications of the DeviceNet open field network.
- Maintainability improved by the host controller using DeviceNet to monitor the operating conditions of servo drives, alarm status, and other information.
- © Full range of positioning functions featured including simple positioning, homing, continuous speed operation, positioning after continuous speed operation, and programmed operation.
- ORound micro-connectors used for the connectors.
- Modules can be driven by two different power-supply methods: servo control power or external power.

Note: The DeviceNet module can be used in combination with the fully-closed module.

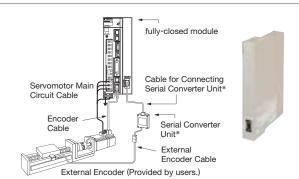


With Feedback

Fully-closed Module

- O High-precision and high-response positioning by using feedback from detector (such as an external encoder) installed on the machine.
- High resolution with external encoders (linear scales).
- *: Not required depending on the type of the external encoder.

Note: The fully-closed module can be used in combination with the INDEXER module or DeviceNet module.



Safety Module

The Safety Module complies with EN ISO13849-1 (the standards harmonized with EU Machinery Directive 2006/42/EC) and has safety functions equivalent to those stipulated in IEC61800-5-2. By using Σ -7S SERVOPACKs with the safety module, optimum safety designs can be created for mechanical systems to better meet the needs of the industry.

- © The first product for AC servo drives in Japan that has safety functions equivalent to the following ones stipulated in the international standard IEC Safe Torque Off (STO), Safe Stop 1 (SS1), Safe Stop 2 (SS2), Safely Limited Speed (SLS)
- Two safety functions (A and B) are provided and stopping functions can be allocated individually to these safety functions.
- With the attachable Safety Modules for SERVOPACKs, system configurations are simplified and compact.



■With Functions Defined by IEC61800-5-2

By using the Hard Wire Base Block function (HWBB) of SERVOPACKs, the following four safety functions can be achieved.

Products Safety Applicable SERVO **SERVOPACK** Standards Standards **PACK** + Safety Module EN ISO13849-1:2008 Safety of EN 954-1 Machinery IC 60204-1 IEC 61508 Series Functional IEC 62061 Safety IEC 61800-5-2 **EMC** IEC 61326-3-1 \bigcirc

■Compliance with Safety Standards

| 0.1.1 | | F | Products |
|---|---|---------------|------------------------------|
| Safety Function | Description | SERVO PACK | SERVOPACK + Safety Module |
| Safe Base Block Function (SBB function) | This safety function is equivalent to the STO function. It shuts OFF the power supply to the motor. | 0 | 0 |
| Safe Base Block with Delay Function (SBB-D function) | This safety function is equivalent to the SS1 function. It shuts OFF the power supply to the motor after monitoring the deceleration of the motor for the specified length of time. | _ | 0 |
| Safe Position Monitor with Delay Function (SPM-D function) | This safety function is equivalent to the SS2 function. It monitors the deceleration of the motor for the specified length of time and the position after the motor has stopped. | _ | 0 |
| Safely Limit Speed with Delay Function (SLS-D function) | This safety function is equivalent to the SLS function. It monitors the deceleration of the motor for the specified length of time and the motor speed to make sure it is within the allowable range. | _ | 0 |



Rotary Servomotors

| Rated output | Rated speed/ Max. speed (min ⁻¹) | | |
|---------------|---|--|--|
| 50 M +- 750 M | 2000/0000 | | |



SGM7J model (Medium inertia, high speed)

50 W to 750 W 30

- Instantaneous peak torque (350% of rated torque)
- O Protective structure: IP67
- O Mounted high-resolution serial encoder: 24 bits
- © Cable installation direction is possible both of the toward load, and away from load.



SGM7A model (Low inertia, high speed)

50 W to 7 kW

3000/6000

- Instantaneous peak torque (350% of rated torque) *
- © Protective structure: IP67 (IP22 for 7.0 kW motor)
- O Mounted high-resolution serial encoder: 24 bits
- Cable installation direction is possible both toward load and away from load.*

*: For motors of less than 1 kW



SGM7P model (Medium inertia, flat type)

100 W to 1.5 kW

3000/6000

- Flat type
- O Mounted high-resolution serial encoder: 24 bits



SGM7G model (Medium inertia, large torque)

300 W to 15 kW

1500/3000

- O Protective structure: IP67
- Mounted high-resolution serial encoder: 24 bits

Direct Drive Servomotors

| | Rated torque / Max. torque (N·m) | Rated speed / Max. speed (min ⁻¹) | Diameter dimensions (mm) |
|----|--|---|--------------------------|
| 3) | 2 to 35/ | 150 to 200/ | φ135 |
| | 6 to 105 | 250 to 500 | to φ290 |



Small capacity, coreless (SGMCS)

- O Directly couples to a load without any mechanical transmission such as a gear
- O Powerful and smooth running throughout all the low to high speed ranges
- O High-resolution, 20-bit encoder for highly precise indexing
- © Easy wiring and piping enabled by the hollow structure



Medium capacity, with iron core (SGMCS)

45 to 200/ 135 to 600 150/ 250 to 300 *φ*280 to *φ*360

© Directly couples to a load without any mechanical transmission such as a gear

- Powerful and smooth running throughout all the low to high speed ranges
- O High-resolution, 20-bit encoder for highly precise indexing
- © Easy wiring and piping enabled by the hollow structure



Small capacity, with iron core (SGMCV)

4 to 25/ 12 to 75 300/ 500 to 600 φ135 to φ175

- O Compact design using iron core (slot-winding structure)
- O High-speed and high-frequency positioning (Max. speed increased by 20%)
- O High-resolution, 22-bit encoder for highly precise indexing

AC Servo Drives Σ -7Series

Servomotor

Linear Servomotors



Max. speed

Rated force

Peak force



- O Direct-feed mechanism for high-speed and high-precision positioning
- Lack of magnetic attraction force helps extend the life of linear motion guides and minimizes noise.
- Zero cogging for minimal force ripple



SGLFW2 (Model with F-type iron core) | Standard 2.5 to 5 | 45 to 2520 | 135 to 7560 |

- O Direct-feed mechanism for high-speed and high-precision positioning
- The large magnetic attraction force between the moving and stationary members can be used to effectively increase the rigidity by preloading the linear guide.
- The magnetic preloading on linear guide can help increase the system's frequency response, improving its damping and settling performances.



| SGLTW (Model with T-type iron core) | Standard | 2.5 to 5 | 130 to 2000 | 380 to 7500 |
|-------------------------------------|------------|------------|-------------|-------------|
| | High force | 3.1 to 4.8 | 300 to 900 | 600 to 1800 |

- O Direct-feed mechanism for high-speed and high-precision positioning
- Yaskawa's unique construction principles of the SGLTW linear motors negate the effects of the magnetic attraction force between the relative motor members.
- Lack of magnetic attraction force helps extend the life of linear motion guides and minimizes noise.
- Very little cogging

AC Servo Drive Σ - V_{Series}

Note: These linear sliders must be used with Σ -V SERVOPACKs.

Linear Sliders

Rated force Max. force Effective stroke (N) 47 to 560 140 to 1200 70 to 1950



- SGT (Σ -Trac) © For long strokes and high-speed, high-precision positioning (Repetitive positioning accuracy less than ± 1.0 m)
- Several tables can be mounted on one magnetic way, and each table can be driven independently.
- O Standard and high-precision models are available.



SGTMM (Σ -Trac- μ)

3.5 to 7 10 to 25 10 to 65

- O Ultra-flat profile reduces floor space requirements.
- For applications requiring short strokes
- Vibration-free transmission device enables high-precision positioning with a repetitive positioning accuracy of ± 0.5 m max.
- O Locations of armature coils on the stator reduce the effects of heat on the table or workpiece.



SGTMF (Σ -Trac-MAG)

90 to 200 | 270 to 720 | 65 to 185

- Optimum drive for high-acceleration and high-tact operations because of its lightweight moving member.
- For short strokes (65 mm to 185 mm)
- Ocoling units (pipes, etc.) for forced-air or liquid cooling systems can be placed on the fixed side.
- © Linear scale options: Incremental or absolute.
- Improved stroke efficiency*

AC Servo Drives

Large-capacity 2-V_{Series}

Announcing the debut of a large-capacity servo drive series which follows in the footsteps of the series with its superlative performance, simple startup, and outstanding expandability. Considerable energy savings enabled by using a separate converter.





[Catalog No. KAEPS80000086]

Combinations

| Combinations | | 200 V | | | 400 V | | | | |
|--------------------|--|-------|-------|-------|-------|-----------|-------|-------|-------|
| Rated output | | 22 kW | 30 kW | 37 kW | 22 kW | 30 kW | 37 kW | 45 kW | 55 kW |
| Servomotor SGMVV- | | 2BA | 3ZA | 3GA | 2BD | 3ZD | 3GD | 4ED | 5ED |
| SERVOPACK SGDV- | | 121H | 161H | 201H | 750J | | 101J | 13 | 1J |
| Converter SGDV-COA | | 2BAA | 3G | AA | 3Z | 3ZDA 5EDA | | | |

SGMVV Servomotor













*: For detail, contact your Yaskawa representative.

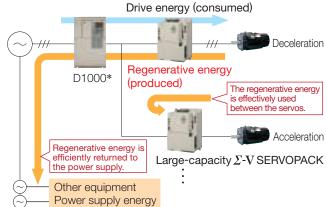
Upgraded by combining a Machine Controller

- O High torque can be generated with synchronized control of multiple axes.
- © The high-precision synchronized control of multiple axes (roller, takeup, etc.) increases quality.
- O Seamless switching between position control and torque control improves machine takt time.

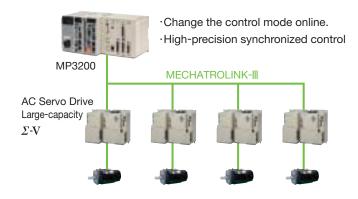
Easily build an energy-saving system

By separating the converter, optimal support can be provided for a power regeneration converter or common converter. This paves the way for broad-based energy savings in the systems with, for instance, the regeneration of the energy produced during motor deceleration at the power supply side.

■Energy-saving Application Example



*: D1000 is the sine-wave PWM converter able to regenerate power. In combination with an AC drive, realizes high power factor operation, and entirely eliminates problems of power source harmonics.



Application Examples

Machine Tools

Helps meet speed and capacity demands of feed and spindle motors in high-speed, heavy-duty machining applications.

Rotary Cutters

Outstanding acceleration/deceleration torque for high-speed tracking

The large-capacity servo drives bring better levels of performance to today's large, high-speed machinery, improving operations with digitalization and making them quieter than ever.

Servo Presses

To attain cleaner and more efficient operation, servo presses are now being driven electrically instead of hydraulically. Energy savings in servo presses are also achieved thanks to the use of power regeneration converters.

Injection Molding Systems

High-resolution encoders for higher levels of precision in injection control.

Wire Saws

With a greater cutting force due to the high torque, saws can now cut hard materials. When combined with the MP series, it is possible to synchronize roller shafts, wind-up shafts and other such parts to a high level of precision.







AC Servo Drives Σ -Vmini Series

These ultra-compact Servo Drives retain all the leading performance, functionality and ease of use of the Σ -V series in a palm-size package.

 Σ -V mini Servo Drives operate with DC power input (main circuit power supply 24 VDC/ 48 VDC; control power supply 24 VDC), which makes them well-suited for clean room robots and clean AGVs*1 and other battery-driven transport systems.

[Catalog No. KAEPS80000042]

Features

- Welps reduce the overall size of control boards and machinery.
 Servomotor dimensions (See table on right)
 SERVOPACK dimensions: 100*2 (H) × 30 (W) × 80 (D) mm
- Model tracking control, anti-vibration control, and friction compensation functions
- *1: Automated Guided Vehicle.
- *2: Size: 116 mm including the mounting base



SERVOPACK Model SGDV-

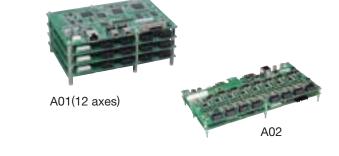
Servomotor Specifications

| Model SGMMV- | Rated Output (W) | Rated Motor Speed/ Max. Motor Speed (min ⁻¹) | Square Flange Dimensions (mm) | Total Length (mm) |
|-----------------|------------------------|--|-------------------------------------|-------------------------|
| B3E | 3.3 | | | 58 |
| B5E | 5.5 | | 15 | 64 |
| B9E | 11 | 3000/6000 | | 98 |
| A1E | 10 | 3000/8000 | | 70 |
| A2E | 20 | | 25 | 80 |
| A3E | 30 | | | 90 |

Σ -V-MD Series A01/A02

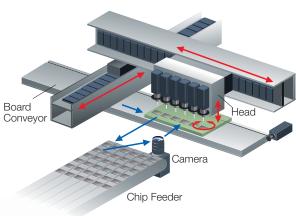
These board-type SERVOPACKs enable multi-axis control of $\boldsymbol{\varSigma}\text{-}\mathbf{V}$ mini servomotors.

The machine size and wiring can be reduced by incorporating Σ -V-MD SERVOPACKs into the moving parts of chip mounters and other equipment. Two types are available: the A01 that enables easy expansion of the number of axes (4, 8, or 12 axes), and the 8-axis integrated type A02.



SERVOPACK Model SGDV-MDA EM3A Servomotor Model SGMMV

Application



SERVOPACK Specifications

| Model | SGDV-MD A01 | SGDV-MD A02 | | | |
|--------------------|--|-------------|--|--|--|
| Number of Axes | 4, 8, or 12 | 8 | | | |
| Interface | MECHATROLINK- ${ m III}$ (transmission cycle: 250 μ s to 4 ms) | | | | |
| Innut Dawar Cumply | Main circuit: 24 VDC/ 48 VDC | | | | |
| Input Power Supply | Control circuit: 24 VDC | | | | |
| Applicable Motor | SGMMV: 3.3 W to 30 | W | | | |
| | 4 axes: 170×115×46 | | | | |
| Dimensions (mm) | 8 axes: 170×115×61 | 238×120×29 | | | |
| | 12 axes: 170×115×76 | | | | |



The Σ -S series was developed to be compact, easy to use, and available at a low price, which makes it an ideal product for applications that do not conventionally use Servo Drives.



Potential applications of the Σ -S Series in pneumatic equipment

Advantages of the Σ -S Series Suggestion 1: Electric chuck Impressive reference tracking capability and reductions in takt time Easy adjustment of chucking holding power using torque limit Energy savings achieved and running costs reduced Multi-point positioning enabled (expanded range of applications) Cow-level operating noise Suggestion 2: Electric actuator Compressor Servomotor Pneumatic Air-pressure Directional actuator Air purifier auxiliary device control device Motor Electricity Energy conversion Energy conversion Pressure transmission Electric power conversion loss: High loss: High loss: High loss: Low

Features

1. Hold-in-place operation

Workpiece can be held in place at any torque.

2. Multi-point positioning

Positions can be set according to the size of the workpiece.

3. Program tables

Programming can be simplified by setting numerical values in the tables provided.

4. ZONE output

Users can recognize that the actuator is operating within the specified range.

5. Acceleration/deceleration control Impacts on the workpiece can be reduced.

SERVOPACK Specifications

- Power supply: 24 VDC (Common input for main circuit and control circuit)
- Reference interfaces (2 types): 1) Contact commands (program table method) 2 Pulse train references
- Dimensions: 80 mm × 123 mm

Servomotor Specifications

| Model SGMSL- | Rated Output (W) | Rated Motor Speed/ Max. Motor Speed (min ⁻¹) | Encoder | Square Flange Dimensions (mm) | Total Length (mm) |
|-----------------|------------------------|--|--------------|-------------------------------------|-------------------------|
| A3 | 30 | 3000/6000 | Incremental, | 25 | 85 |
| A5 | 50 | 3000/3000 | 10 bits | 40 | 92 |

SigmaJunmaSize+ is a Web-based software application used to easily select the optimal YASKAWA servo drives for your machinery. SigmaJunmaSize+ is available from our website at http://www.e-mechatronics.com.

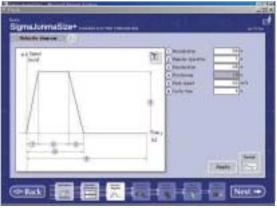
Features

- 1. A wide range of the latest information.
- 2. A wizard system with a conversational mode to select optimal servo drives.
- 3. View SigmaJunmaSize+ in your browser wherever internet access is available. (Enhanced security measures with cryptographics)
- 4. Available to view and reuse previously input and stored data.

Servo Selection Screen



Application Selection Window



Velocity Diagram Input Window



Motor Selection Window



Machine Information Input Window



Operating Condition Selection Window



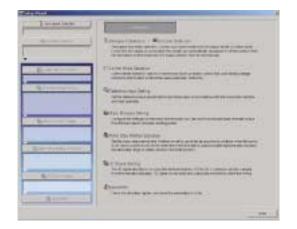
SERVOPACK Selection Window

SigmaWin+

Supported OS: Windows XP/Vista/7

SigmaWin+ is a Windows-based engineering PC tool with various monitoring functions to make quick and easy adjustments to the settings for Yaskawa servo drives. SigmaWin+ supports a widerange of operations from setting parameters to trial operation.

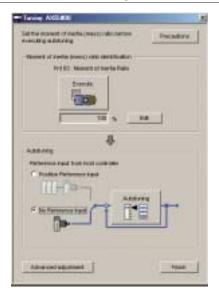
Setup using Wizard



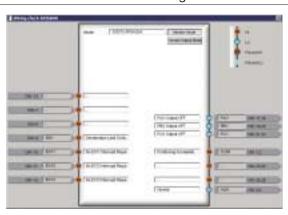
Parameter Edit (at online)



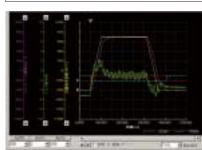
Tuning



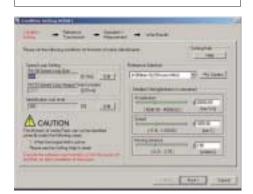
Check Wiring



SERVOPACK internal data can be displayed in the monitor just like an oscilloscope.



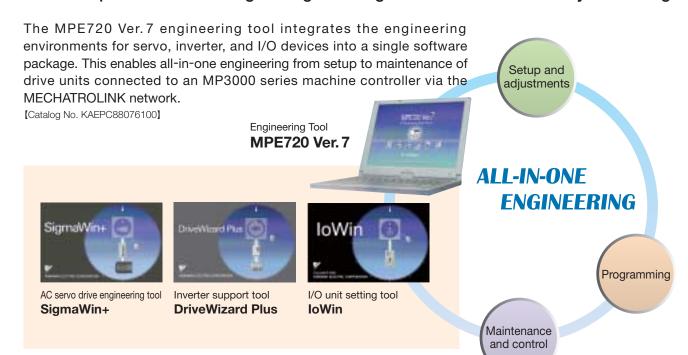
Calculating Moment of Inertia and Measuring Vibration Frequency



Alarm Display and Alarm Diagnostic Function



A one-stop solution for strengthening the integration environment and system design!



Execution of parameter settings and monitoring enabled for multiple axes simultaneously

The parameter settings and monitor windows of the drive units can be executed for a multiple number of axes simultaneously. Establishing the settings for the entire system is a simple job, and comparing the monitors on an axis-by-axis basis is also easy.

MC-Configurator



Adjustment work supported by a variety of adjustment functions

A wide variety of functions required for servo adjustments are provided, and these functions support the adjustment work.



Efficiency improved by choosing the programming method that works best for the user

Ladder programming



- · A new user interface (UI) enables operations to be undertaken easily by anybody.
- · All types of control including position, speed, torque, and phase control are supported.
- · Arithmetic expressions in the ladders have been made even simpler by boosting the EXPRESSION instructions.

This system is recommended for:

· Users who are using a PLC

Motion programming



- · Positioning and interpolation instructions can be described using single instructions.
- · Programs can be very easily edited using expressions in a text format.
- New variable programming can provide PC-like programming.

This system is recommended for:

· Users of PC-based devices and in-house fabricated boards (C language, BASIC language)

Advantages of MECHATROLINK

MECHATROLINK was created based on technology developed by Yaskawa as a specialized network for motion control, and has been made available as an open field network.

Yaskawa helped found the MECHATROLINK Members Association (MMA) in 2003 as a member of the MMA Board Committee, Yaskawa has continued to work with the MMA to promote the use of MECHATROLINK.

MECHATROLINK acquired certification for IEC61784 and IEC61158 international standards from the IEC in August 2014.

IEC61784 and IEC61158 are international standards for specifying industrial computer network protocols.

It is expected that the adoption of MECHATROLINK as a standard by the IEC will help promote the worldwide use of MECHATROLINK and contributing greatly to improving the productivity of manufacturing sites around the world.

MECHATROLINK Members Association (MMA)

MMA was established to promote the MECHATROLINK open field network for high-speed motion. The MMA consists of members that develop compatible products and the users of those products. There are five membership ranks: Board Members, Executive Members, Regular Members, User Members, and Registered Members.

There are six Board Member companies in the MMA: M-System Co., Ltd., Oriental Motor Co., Ltd., Digital Electronics Corporation, Yaskawa Electric Corporation, Yaskawa Information Systems Corporation, and Yokogawa Electric Corporation. These companies are responsible for the management of the MMA. The MMA provides global support to its members with branch offices in Germany, the U.S., South Korea, China, and Taiwan. These offices offer technical support and conduct promotional activities tailored to the local conditions in each country.

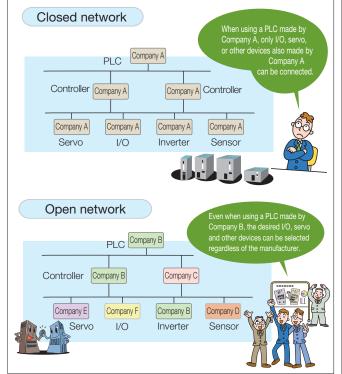
MECHATROLINK Members Association website: http://www.mechatrolink.org

Den Wide variety of available products

The most important point in freely constructing systems is a wide variety of available products.

MECHATROLINK adopts open and standardized communication specifications to enable connections between equipment made by different device manufacturers. Customers can arbitrarily select products made by different manufacturers based on criteria such as design, functionality, and cost. By ensuring that their products comply with applicable standards, device manufacturers can also access a larger market.

Difference between an open and closed network



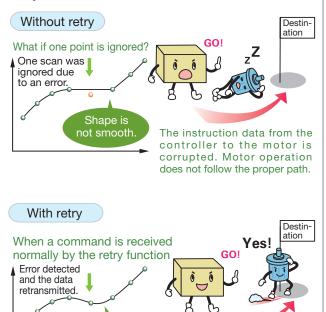
Reliable Guaranteed high communications performance

The most important point in communications is to reliably transmit accurate data.

When transmitting digital data in particular, an error in transmitting even 1 bit can corrupt the entire communications data. MECHATROLINK has a retry function that automatically detects command and response communication errors and retransmits the data. Retry is performed within the same transmission cycle, so there is no loss of synchronicity.

New industrial connectors and cables are also used, and antivibration and noise measures have been enhanced.

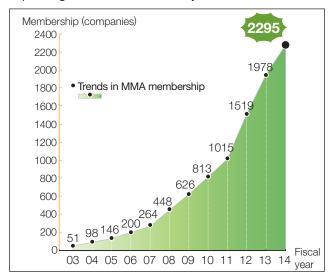
Retry function



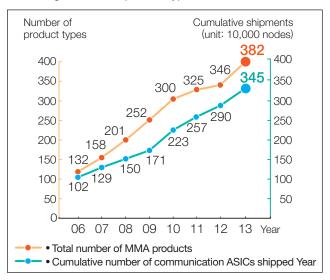
The error is corrected within the appropriate transmission cycle. The motor operates as instructed.

shape!

Expanding MECHATROLINK family



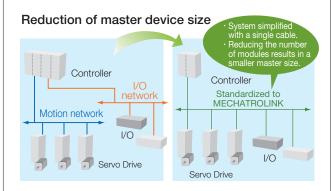
Increasing numbers of product types and nodes

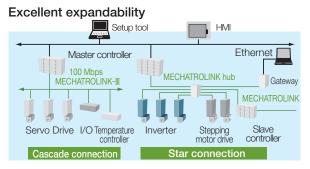


Simple Low cost, easy maintenance, and expandability

A key point for constructing a low-cost system is to reduce the wiring.

MECHATROLINK can connect a master device with each slave device using a single cable. MECHATROLINK also enables a reduction in the number of master device modules and cables by integrating the motion control network and I/O network into a single wiring system. This reduces costs and facilities maintenance and system expansion.





Speedy

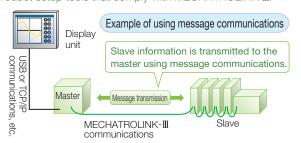
Simultaneous control of multiple axes and high-capacity message

Faster network speeds are required to enhance productivity and increase system scales.

MECHATROLINK-Ⅲ has a communication speed of 100 Mbps and a transmission cycle of 31.25 μ s, which is the best in the industry. This shortens the cyclic communications cycle and enables communications with more slaves per unit time to achieve simultaneous control of up to 62 axes. High-capacity message communication is also possible.

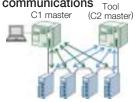
Promotion of message communication

The MMA aims to popularize the use of message communications to improve the ease of maintenance. To achieve this, the MMA actively encourages members to use various compatible product setup tools that comply with MECHATROLINK-III.



MECHATROLINK-III message communications Tool

The C1 master supports message communications. The C2 master can also control the parameters, alarm history, and other data of each slave as a tool master.





Yaskawa Information Systems Corporation

The M2M communication adapter offers one-stop solution for remote control and monitoring as well as management of devices via mobile communications networks. The environment required for remote monitoring is offered as a set.

MMLink-3G, Global Communication Adapter

Seamless remote monitoring and control via 2G and 3G networks.

Features

- Supports connection to 2G and 3G networks.
- 2 Data transfer possible over wide areas
- 3 Equipped with GPS navigation system
- 4 Supports various communications protocols
- 5 Easy initial settings



MMLink-G, Global Communication Adapter

Supports connections to GSM networks, the optimal solution for overseas remote monitoring.



- Supports connection to GMS networks that is a major network used overseas.
- Can be used with multi-operator systems (e.g. more than 100 countries).
- Supports LAN and serial interface.



MMLink-1X, Adapter for CDMA 1X Packet Communications

Remote operation and control with CDMA 1X

Features

- Supports RS-232C serial and LAN interface and expands the range of applications.
- Easy connection to a network by simply turning the power on (Automatic OTA)
- Easy initial settings via browser.
- Earthquake early warning notifications via networks to minimize damage and injuries.



M2M Cloud Service

MMCloud, Cloud Service for Product Life Cycle Management Support

This is a cloud service that collects and manages the operational information of products and related information in order to support the management of the life cycle of products.



Features

Supports management of product life cycle

Product information that is managed separately can be consolidated and used for work in various processes, including planning, development, sales, inspection, and maintenance.

- 2 Enables ideal monitoring of equipment located in different locations around the world Global-scale monitoring of equipment is made possible by using internet connections and wireless communication networks for mobile phones. User environment is also globalized. Local times of different countries where equipment are used can be displayed and languages can be selected on the screen.
- 3 Displays collected information in real time Collected data, status of customer equipment, information collected via sensors, and GPS information is displayed in graphs and maps so that equipment conditions can be checked in real time. This service can be used to monitor operation status and mobile equipment.
- 4 Can start with a small-scale operation Customers can first use this service with a small investment and a short leadtime by using the standard cloud service. The monitoring scale can be increased in line with the expansion of the customer's business operations.

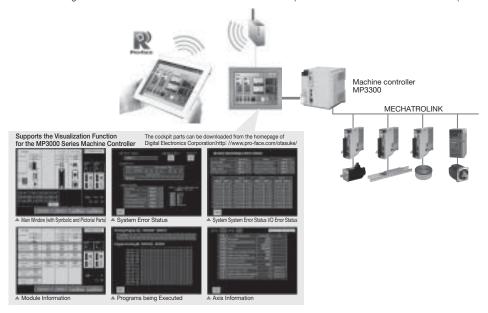
Website http://www.ysknet.co.jp/

Programmable

Digital Electronics Corporation

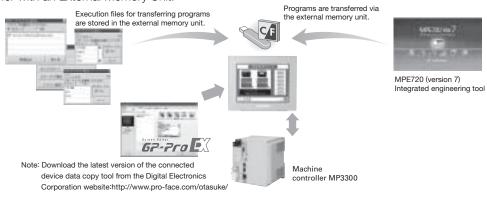
Pro-face GP4000 Series

The GP4000 series display features a touch screen that can be connected directly, without using any application programs, to control devices, such as controllers, servo drives, and AC drives. Current conditions of these devices is displayed on the screen so that they can be set up, adjusted, and maintained on site. Users can easily check operational status, edit registers, identify errors, and update or backup application programs without using a computer. The GP4000 series supports Proface Remote HMI, the remote monitoring software for mobile devices. This allows users to view product information on tablets and smartphones anytime, anywhere.

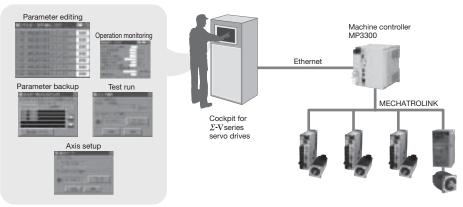


Engineering Support Function

Program Transfer with an External Memory Unit!



Adjustment and Maintenance of Servo Drives and Inverters Right on the Touch Panel!



IP Core

Tokyo Electron Device Limited

MECHATROLINK-III Master/Slave IP Core

Model: Master: TIP-ML3MST-PROJ Slave: TIP-ML3SLV-PROJ

This original IP core for FPGAs manufactured by Xilinx, Inc. significantly reduces the number of components on a board. This reduces development costs and time required for development can be significantly reduced.

- · Supports MECHATROLINK-III master and slave functions.
- · Delivers a high-speed host interface synchronized with a 66 MHz clock (max.).
- · Enables flexible system configuration by using FPGA fabrics.

Website http://ppg.teldevice.co.jp

I/O Module

M-System Co., Ltd.

MECHATROLINK-I- and -II-compliant Remote I/O

Model: R7K4FML, R7ML series

- · Can handle 16 to 32 discrete I/O signals, and 4 analog input and 2 analog output signals.
- · Analog and discrete signals can be mixed.
- · 3M screw terminals (2-piece configuration) are used for power supply and I/O terminal blocks. Saves space because relay terminal is not required.
- · Channels are insulated.



R7ML Base Module

MECHATROLINK-III-compliant Remote I/O

Model: R7G4FML3. R7G4HML3. R7K4FML3



- · Equipped with discrete I/O, DC input and output, temperature input, rotary encoder input
- · High-speed A/D conversion unit (conversion speed:200 μ s) available.
- · High-speed load cell input unit to be released around March 2015.
- · 3M screw terminals (2-piece configuration) are used for power supply and I/O terminal blocks. Saves space because relay terminal is not required.
- · Channels are insulated.



R7G4FMI 3-6

Master Module

HLS (High-speed Link System) Master Module Model: MPHLS-01

- · Master module that can be used with MP2200, MP2300, and MP3300 series machine controllers. Note: When using this module with a MP3200 machine controller, attach a MP2000 base unit (optional) to the machine controller first and install this module in the base unit.
- · Wiring for discrete I/Os and analog I/Os can be reduced with M-System's rich product lineup of remote I/O modules (R7HL and R7F4DH series) that can be connected to the HLS master module.

Website http://www.m-system.co.jp/



ALGO System Co., Ltd.

A-net/A-Link Master Unit Module

Model: MPANL00-0

This A-net/A-Link master unit module can be directly attached to the MP3200 Controller. The resulting system needs less wiring and conforms to SEMI E54.17.



- Two H8S units by Renesas Technology Corp. can be added maximum.
- Max. 4032 points can be scanned in 0.95 ms (at 12 Mbps). Note: The case using two A-Link channels (1 channel: 2016 points/system, 0.95 ms at 12 Mbps).
- Shared memory of 512 Bytes (response speed: 2.36 ms) with A-net.
- Self-diagnostic function.

Website http://www.algosystem.co.jp/



I/O Module

WAGO Company of Japan, Ltd.

WAGO-I/O-SYSTEM 750 Series

Model No. 750-346: Compatible with the 260IF-01 DeviceNet Communication Module Model No. 750-352: Compatible with the 263IF-01 EtherNet/IP Communication Module and 218-01/02 Ethernet Communication Module.

WAGO-I/O-SYSTEM 750 series I/Os are module-type remote I/Os. Nodes can be constructed by combining a communication unit (bus coupler) with a function module of your choice. Various communication units that are compatible with a wide range of open fieldbus are available.

Yaskawa Electric's MP series machine controllers can be connected via DeviceNet, Ethernet/IP, and Modbus-TCP Ethernet networks. Instruction manuals contain information on easy ways to connect the machine controller.

Function modules are available for a wide range of I/O signal types: digital I/O (2 to 16 channels), analog I/O (±10 V, 0 to 20 mA, thermocouples), serial communications, counter I/O, etc.

Website http://www.wago.co.jp/io



Example of Node Configuration (Bus coupler + Module)



Anywire Corporation

AnyWire DB Master Module

Model: AFMP-01

The AnyWire DB master module can be connected directly to the machine controllers in the MP3000 series. This module is equipped with the master functions of the AnyWire DB A40 series and is compatible with a variety of I/O terminals in the same series.



- The AnyWire system saves space and reduce costs because fewer cables are reduced and low-cost, general-purpose cables can be used. Time required for wiring is also reduced.
- Highly efficient transmission is achieved with the Dual-Bus system. Analog inputs/outputs (128 words max) can be connected without adversely affecting the digital input/output signal transmission (512 points max).
- General-purpose robot cables, cableveyor, slip rings can be used with the product. This is an ideal module to reduce wiring at drive sections

CC-Link interface board

Models: AFMP-02-C, AFMP-02-CA

These slave interface boards connect the machine controllers in the MP3000 series to the CC-Link master. One CC-Link master can be connected to a maximum of 16 machine controllers in the MP3000 series through the CClink when the PLC in the Q series (manufactured by Mitsubishi Electric Corporation) is used as a master station. Costs can be reduced and space saved by using the AFMP-02-CA board equipped with wire-saving DB ports.

MECHATROLINK bit-type distributed I/O terminal

Model: AB023-M1

The MECHATROLINK bit-type distributed I/O terminal reduces the wiring required for drive systems that use MECHATROLINK-I and -II. The introduction of this I/O terminal into a MECHATROLINK open-network system significantly reduces total costs and increases system reliability because the MECHATROINK I/O terminal can be used with any transmission media, such as robot cables and slip rings.

The AnyWire Bitty series for I/O terminals from AnyWire can be connected to this distributed I/O terminal to increase the flexibility in transmissions by supporting the connection of cables for signals from sensors and actuators in the system. It is possible to increase the number of I/O points to 432 by connecting I/Os with a bus that reduces the amount of wiring required.

Website http://www.anywire.jp







Phoenix Contact GmbH & Co. KG

MECHATROLINK Inline Bus Coupler

Model: IL MIBK DI8 DO4-PAC

- · The Inline bus coupler, model IL MII BK DI8 DO4-PAC, has eight digital input terminals and four digital output terminals as a standard feature.
- · The Inline modules for I/O signals can be expanded, and 52 modules can be connected.
- · A wide range of input and output modules are available, including digital input, digital output, analog input, analog output, and temperature control modules.

Website http://www.phoenixcontact.com/global/



modules

modules

RKC Instrument Inc.

Module-type Digital Temperature Controller

Model: SRZ · Communications converter module COM-MY

- · Temperature control module Z-TIO
- · Digital I/O module Z-DIO
- · Easily construct a multi-channel temperature control system by connecting the MECHATROLINKcompliant communications converter module to the temperature control modules.
- · A single temperature control module can control temperatures of four points or two points. Also, 16 modules can be connected for temperature control of maximum 64 points.
- Digital I/O modules to output temperature alarms and to switch operation modes by using contact signals can also be connected.



Website http://www.rkcinst.com

Stepping Motor Drive

Oriental Motor Co., Ltd.

Network Converter for Controlled Motors

Model: NETC01-M2 for MECHATROLINK-II NETC01-M3 for MECHATROLINK-**Ⅲ**

- · These network converters convert the MECHATROLINK communication protocol to Oriental Motor s original RS-485 communication protocol. Oriental Motor's products that support the RS-485 protocol (up to 16 axes) can be controlled in MECHATROLINK communications.
- · Only a single MECHATROLINK communication cable is required for wiring, reducing the number of wires and saving space.
- · Parameters can be set by using an OPX-2A module or MEXE02 software (both sold separately.)

No Out-of-step Stepping Motor and Driver Package

- ·The MECHATROLINK- ${
 m I\hspace{-.1em}I}$ compliant α STEP stepping motor and driver in the ARL-series uses a unique closed-loop control and eliminates missed steps.
- The α STEP does not require tuning or hunting to achieve high-response positioning without any missing steps during sudden load changes or acceleration.
- · Only one cable is required to connect the motor to the driver.
- · A wide range of products including various types of geared motor, the EZ Limo motorized sliders, and the DG series of hollow rotary actuators can be connected and controlled with MECHATROLINK-II.







Melec Inc.

Controller for Stepping & Servo Motors

Model: C-M581S

- · Easy operation by combining I/O bit signals.
- · Specially designed software enables you to make settings or confirm operation status on the personal computer.
- · Individual control of four axes with compact motion controller: 88.5 mm × 94 mm × 59 mm (W×D×H)

Controller for Stepping Motors

Model: CD-M582S/ADB5432

- · Easy operation by combining I/O bit signals.
- · Specially designed software enables you to make settings and confirm operation status on the personal computer.
- · Individual control of two axes with a relay unit and a DC drive for five-phase motors integrated in the compact design: 75 mm × 91 mm × 82.5 mm (W×D×H)

Website http://www.melec-inc.com



Slip Ring

Endo Kogyo Co.,Ltd.

Slip ring for communications and control

Model: SRP-MLII-3

The SRP-ML slip ring enables communications with and control of drive units and systems that include rotating devices.

- · Compact and highly durable structure
- · Improved reliability with the new brush system that enables uninterrupted communications
- · Connected directly by using MECHATROLINK-II cables

Website http://www.endo-kogyo.co.jp/japanese/sr/con-index.html

Slip Ring

Kyoei Electric Co., Ltd.

Slip ring system for MECHATROLINK-II communications

Model: SRC120-MLI

This highly functional slip ring transmits data through MECHATROLINK communications from a fixed device to a rotating device.

- \cdot Can be packaged with a power device, such as power supply for a motor.
- · Complies with RoHS Directive.

Website http://www.kyoeidenki.jp



Incremental Linear Encoders

| Output Signal | Manufacturer | Linear Encoder Type | Scale | Mod Sensor Head | el Interpolator (Serial Converter Unit) | Linear Encoder Pitch | Resolution nm | Maximum Speed*3 m/s | Support for Polarity Sensor Input | Application to Linear Motors | Application to Fully-closed Loop Control |
|---|---------------------------|---------------------------|--------------|-----------------------|---|----------------------------|---------------|---------------------------|---|---------------------------------------|--|
| 1 Vp-p Analog Voltage*1 | Heidenhain Corporation | Exposed | LIDA48□ | | JZDP-H003/-H006*5 | - 20 ∤ | 78.1 | 5 | ~ | ~ | ✓ |
| | | | | | JZDP-J003/-J006*5 | | 4.9 | 2 | ✓ | ~ | *8 |
| | | | LIF48□ | | JZDP-H003/-H006*5 | 4 | 15.6 | 1 | ~ | ~ | ✓ |
| | | | | | JZDP-J003/-J006*5 | | 1.0 | 0.4 | ✓ | *8 | *8 |
| | Renishaw plc*4 | Exposed | RGS20 | RGH22B | JZDP-H005/-H008*5 | 20 | 78.1 | 5 | ✓ | ✓ | ✓ |
| | | | | | JZDP-J005/-J008*5 | | 4.9 | 2 | ✓ | ✓ | *8 |
| Encoder for Yaskawa's Serial Interface*2 | Magnescale Co., Ltd. | Exposed | SL7□0 | PL101-RY*6 | | 800 | 97.7 | 5 | _ | ✓ | ✓ |
| | | | | PL101 | MJ620-T13*7 | 800 | 97.7 | 5 | Polarity Sensor Input | ✓ | *8 |
| | | Sealed | SR75-□□□□□LF | | _ | 80 | 9.8 | 3.33 | _ | ✓ | ✓ |
| | | | SR75- | | _ | 80 | 78.1 | 3.33 | _ | ✓ | ✓ |
| | | | SR85-□□□□□LF | | _ | 80 | 9.8 | 3.33 | _ | ✓ | ✓ |
| | | | SR85-□□□□□MF | | _ | 80 | 78.1 | 3.33 | _ | ✓ | ✓ |

Absolute Linear Encoder

| Output Signal | Manufacturer | Linear Encoder- Type | Model | | | Linear Encoder Resolution | Maximum Speed*3 | Support for Polarity | Application to | Application to | |
|---|---------------------------|----------------------------|----------------|----------------|---|------------------------------|--------------------|----------------------------|-----------------|------------------|---------------------------------|
| | | | Scale | Sensor Head | Interpolator (Serial Converter Unit) | Pitch μm | nm | m/s | Sensor Input | Linear Motors | Fully-closed Loop Control |
| Encoder for Yaskawa's Serial Interface*2 | Magnescale Co., Ltd. | Sealed | SR77-□□□□□LF | | _ | 80 | 9.8 | 3.33 | _ | ✓ | ✓ |
| | | | SR77- | | _ | 80 | 78.1 | 3.33 | _ | ✓ | ✓ |
| | | | SR87-□□□□□LF | | _ | 80 | 9.8 | 3.33 | _ | ✓ | ✓ |
| | | | SR87- | | _ | 80 | 78.1 | 3.33 | _ | ✓ | ✓ |
| | Mitutoyo Corporation | Exposed | ST781A | | _ | 256 | 500 | 5 | _ | ✓ | ✓ |
| | | | ST782A | | _ | 256 | 500 | 5 | _ | ✓ | ✓ |
| | | | ST783A | | _ | 51.2 | 100 | 5 | _ | ✓ | ✓ |
| | | | ST784A | | _ | 51.2 | 100 | 5 | _ | ~ | ✓ |
| | | | ST788A | | _ | 51.2 | 100 | 5 | - | ✓ | ✓ |
| | | | ST789A*9 | | _ | 25.6 | 50 | 5 | - | ✓ | ✓ |
| | | | ST1381 | | _ | 5.12 | 10 | 8 | _ | ✓ | ✓ |
| | | | ST1382 | | _ | 0.512 | 1 | 8 | _ | ✓ | ✓ |
| | Heidenhain Corporation | Exposed | LIC4100 series | | EIB3391Y*7 | - | 5 | 5 | _ | ✓ | ~ |

- *1. You must also use a Yaskawa Serial Converter Unit. The output signal will be multiplied by 8 bits (256 divisions) or 12 bits (4,096 divisions) in the Serial Converter Unit.
- *2. The multiplier (number of divisions) depends on the Linear Encoder. Also, you must write the motor constant file to the Linear Encoder in advance.
- *3. The maximum speeds given in the above table are the maximum applicable speeds of the encoders when combined with a Yaskawa SERVOPACK. The actual speed will be restricted by either the maximum speed of the Linear Servomotor or the maximum speed of the Linear Encoder (given above).
- *4. If you use the origin signals with a Linear Encoder from Renishaw plc, the origin may sometimes be falsely detected. If that occurs, use the BID/DIR signal to output the origin signal only in one direction.

 *5. Use this model number to purchase the Serial Converter Unit.
- *6. Use this model number to purchase the Sensor Head with Interpolator.
- *7. Use this model number to purchase the Interpolator.
- *8. Contact your Yaskawa representative.
- ★9. Contact Mitutoyo Corporation for details on the Linear Encoders.
- Note: Confirm detailed specifications, such as the tolerances, dimensions, and operating environment, with the manufacturer of the Encoder before you use it.

Absolute Rotary Encoder

| Output Signal | Manufacturer | Linear Encoder Type | Mod | Resolution | Maximum Speed* | |
|--------------------------|--------------|---------------------------|----------|-------------|----------------|-------------------|
| | Manufacturer | | Scale | Sensor Head | Bits | min ⁻¹ |
| Encoder for Yaskawa's | Magnescale | Sealed | RU77-40 | 20 | 2000 | |
| Serial Interface | Co., Ltd. | Sealed | RU77-409 | 22 | 2000 | |

^{*.} The maximum speeds given in the above table are the maximum applicable speeds of the encoders when combined with a Yaskawa SERVOPACK. The actual speed will be restricted by either the maximum speed of the Linear Servomotor or the maximum speed of the Linear Encoder (given above). Note: Confirm detailed specifications, such as the tolerances, dimensions, and operating environment, with the manufacturer of the Encoder before you use it.

Global Service Network

Yaskawa assists you in your global business with our worldwide network.





Machine Controller and AC Servo Drive Solutions Catalog

IRUMA BUSINESS CENTER (SOLUTION CENTER)

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YASKAWA ELECTRIC CORPORATION

In the event that the end user of this product is to be the military and said product is to be employed in any weapons systems or the manufacture thereof, the export will fall under the relevant regulations as stipulated in the Foreign Exchange and Foreign Trade Regulations. Therefore, be sure to follow all procedures and submit all relevant documentation according to any and all rules, regulations and laws that may apply. Specifications are subject to change without notice for ongoing product modifications and improvements.

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